

# Positioning and Navigation Systems I (MSS 311)

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## Chapter 3

# The Marine Magnetic Compass



# Magnetic Compass

- The magnetic compass still retains its importance despite the invention of the gyro-compass. While the latter is an extremely accurate instrument, it is relatively expensive, highly complex, dependent on an electrical power supply, and subject to mechanical damage.
- The magnetic compass is less expensive, entirely self-contained, fairly simple, and not easily damaged.

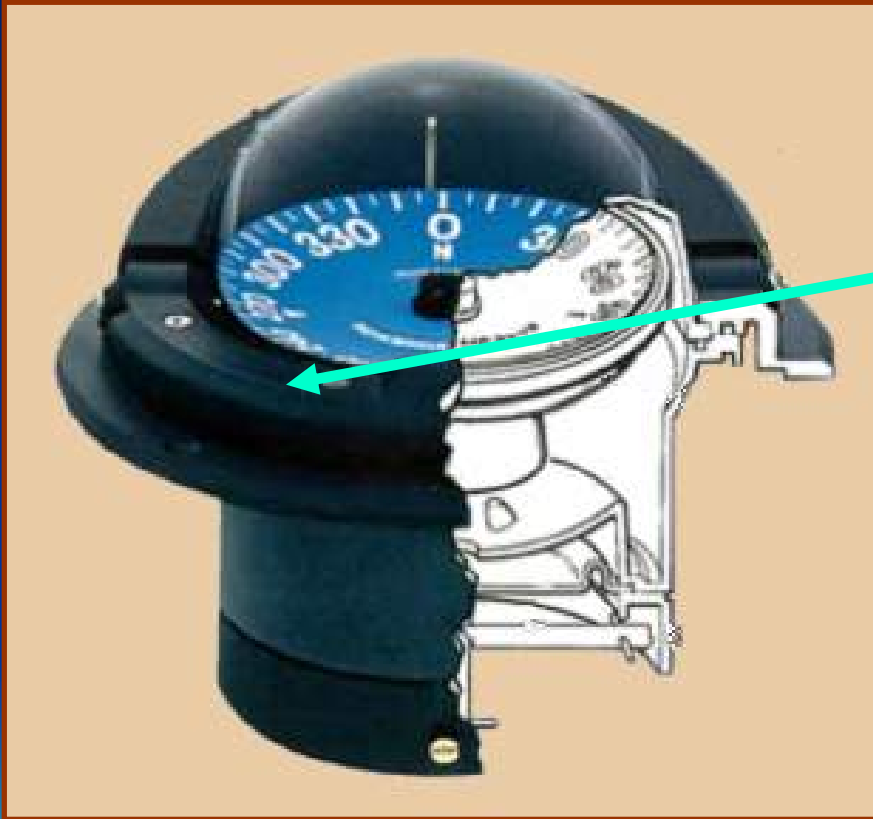


# What We'll Cover

- Compass design
- Principles of operation
- Deviation & swinging ship
- Compass calculations



# Parts of a Compass



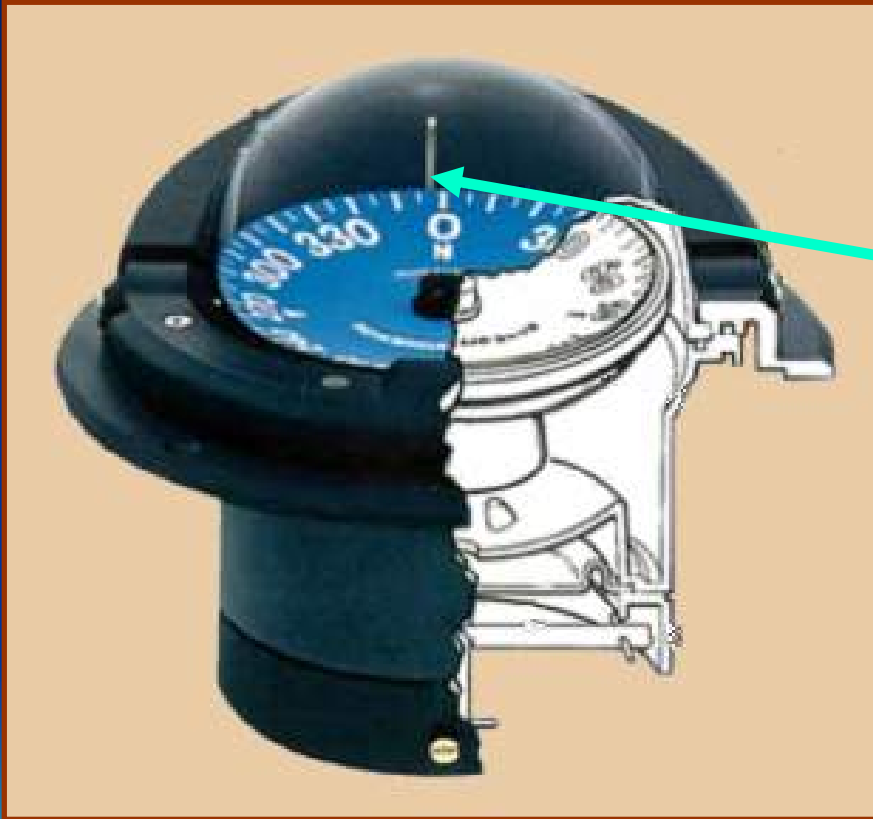
Constructed of non-magnetic materials.

# Parts of a Compass



Indexed card to read direction.

# Parts of a Compass



Lubber line pins to align compass with boat.

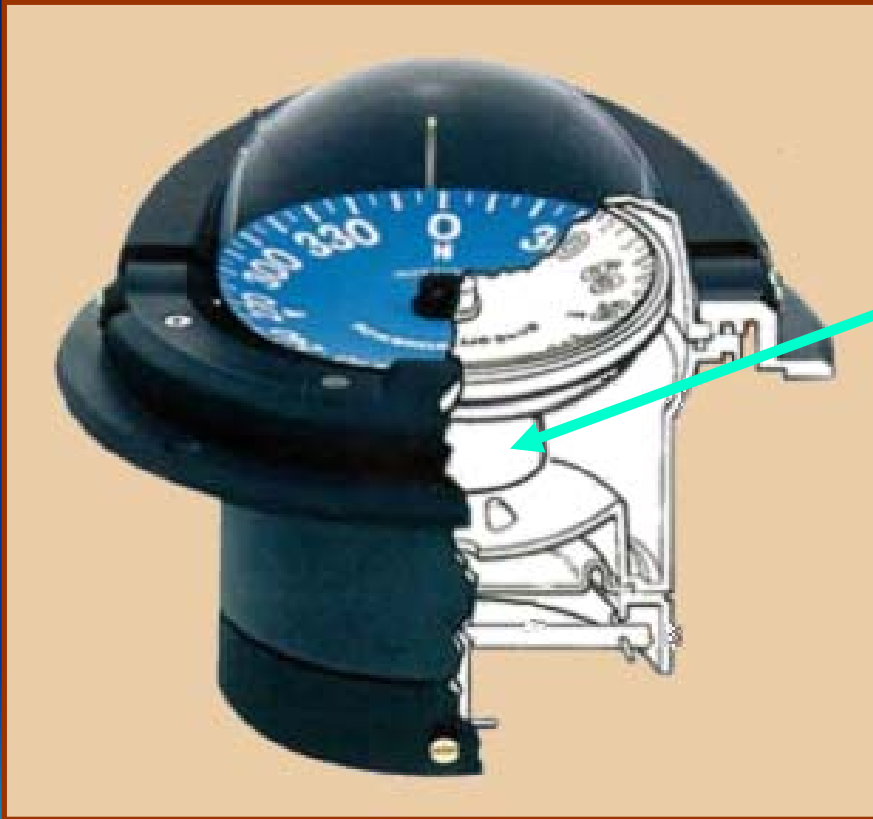
# Parts of a Compass



Gimbal system to keep card level when ship heels and pitches.

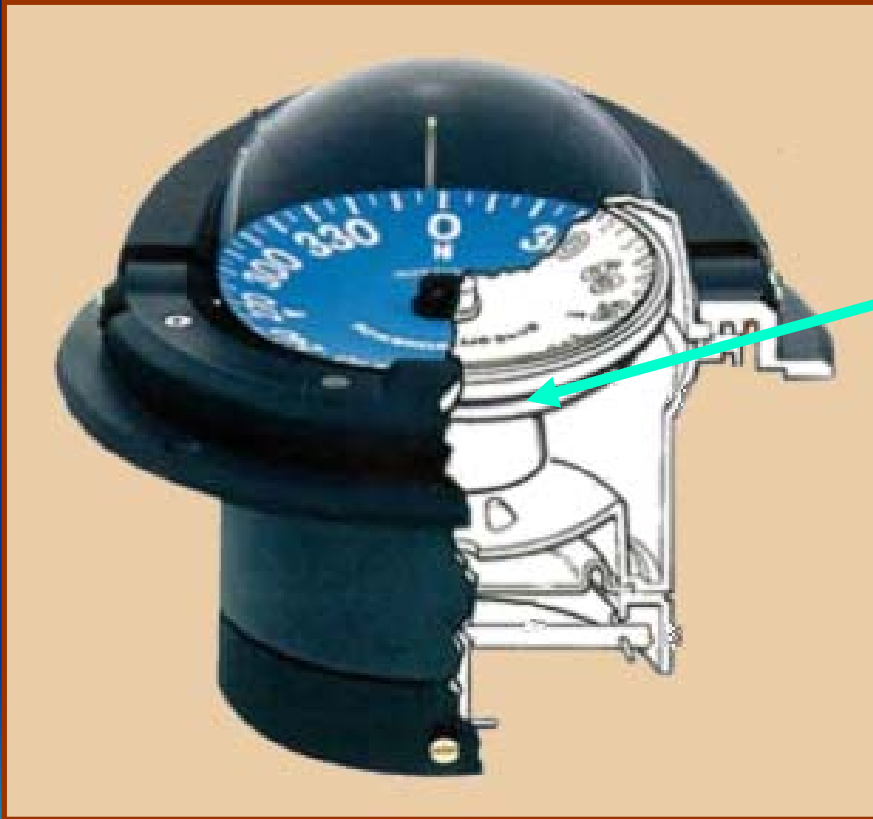


# Parts of a Compass



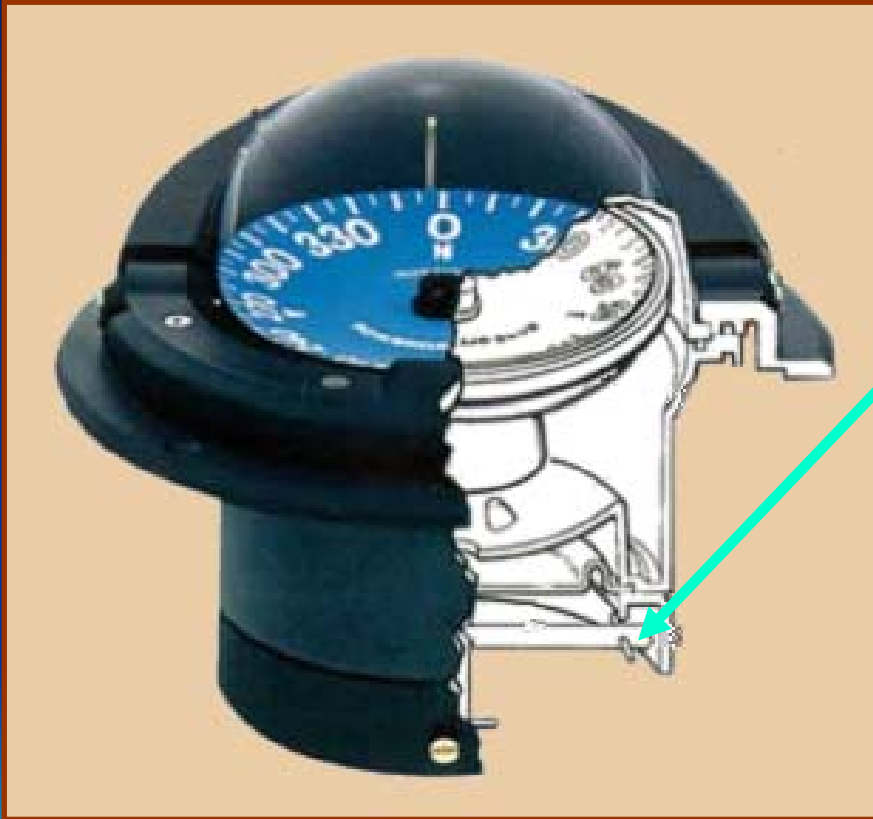
Spherical bowl with expansion diaphragm.

# Parts of a Compass



Fluid filled damping system to impede rapid card movement.

# Parts of a Compass



Compensation system  
to reduce deviation  
error.

# Steering Compass Styles



## Top Reading Card

Usually used in binnacle steering stations.

**Front Reading Card**  
Used when compass mounted on bulkhead.



# Hand Bearing Compass Styles

Front/Top Reading



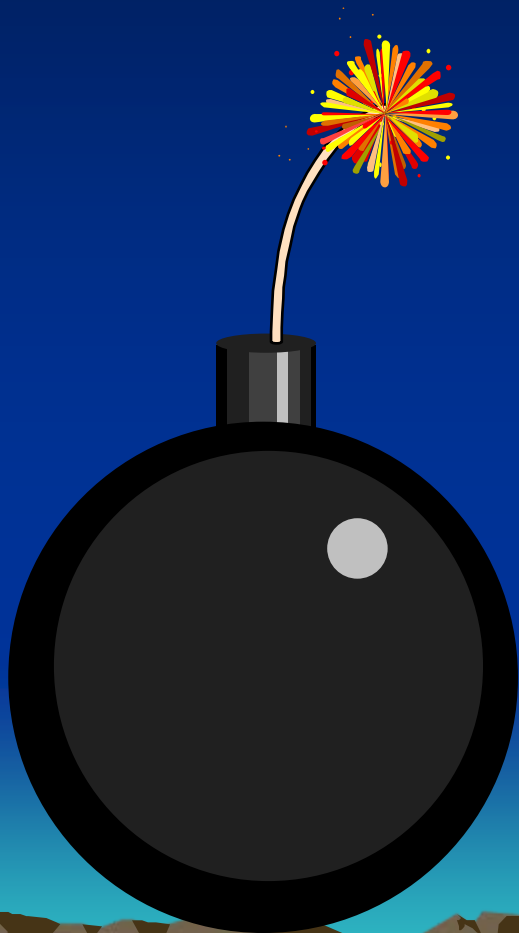
# Compass Card

- Graduated in degrees from 000 to 359.
- Graduated in 1, 2, 5 degree increments.
- Numbers spaced every 10-30 degrees.
- Usually show cardinal points: N, S, E & W.
- May show intercardinal points: NE, SE, SW & NW.



# Compass Errors

## Deviation and Variation



The unattractive Truth

...

Compasses don't

point to True North!

# Compass Errors

- Variation: (Magnetic rose)

It is the difference at any location between the directions of the magnetic and true meridians.

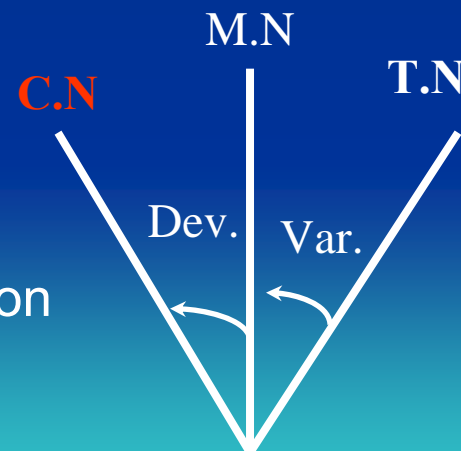
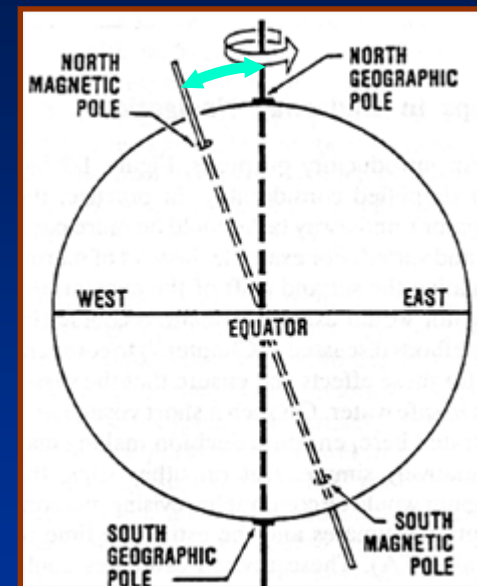
- Geographic (true) vs. magnetic north.
- Common to all parts of the globe.
- Identified on every chart's compass rose's.

- Deviation: (From deviation tables)

It is the divergence between the N-S axis of the compass card and the magnetic meridian.

- Caused by shipboard magnetic influences.
- Exists on all vessels; different for each vessel.
- It varies widely.

**The Compass Errors:** The algebraic sum of variation and deviation





# Example:

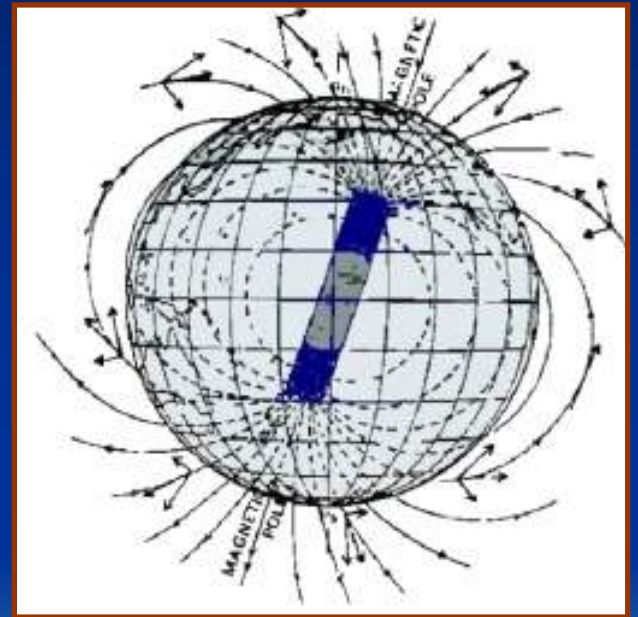
- If the variation was  $05^{\circ} 55' W$  (in 1979), decreasing about  $4'$  annually, calculate variation in year 2008.

Solution:

$$\begin{array}{r} 2008 \\ 1979 \\ \hline 0029 \text{ years} \times 4' = 116' = 01^{\circ} 56' \\ \text{Then: Var. (1979)} = 05^{\circ} 55' W \\ \qquad \qquad \qquad -01^{\circ} 56' \\ \qquad \qquad \qquad \hline \qquad \qquad \qquad 03^{\circ} 59' W \end{array}$$

# Variation: Earth - A Magnet

- Locating exact source of magnetism difficult.
  - Alignment of magnetism changes.
  - Strength of pull varies over earth.



# Deviation Table (1)

Compass Course	Deviation	Compass Course	Deviation
000° C	4.0° E	180° C	3.1° E
010° C	3.0° E	190° C	2.2° E
020° C	2.0° E	200° C	0.6° E
030° C	0.4° E	210° C	2.0° W
040° C	1.2° W	220° C	3.2° W
050° C	2.2° W	230° C	4.4° W
060° C	3.0° W	240° C	5.6° W
070° C	4.2° W	250° C	4.0° W
080° C	5.4° W	260° C	3.4° W
090° C	4.3° W	270° C	2.1° W

# Example (1)

- Find the deviation of course  $217^\circ$ .

Solution:

Compass C.	Deviation
$210^\circ$	$2.0^\circ$ W
$220^\circ$	$3.2^\circ$ W
<hr/>	
10	1.2
03	X

Then Difference of Dev. =  $3 \times 1.2 / (10) = 0.36^\circ$

So, Deviation of Course  $217^\circ = 3.2 - 0.36 = 2.84^\circ$ W

# Examples (2 & 3)

- If the variation is  $3^{\circ}\text{E}$ , and the deviation is  $2^{\circ}\text{E}$ . Calculate the compass error?

Solution:

Variation =  $3^{\circ}\text{E}$

Deviation =  $2^{\circ}\text{E}$

Compass error =  $\Sigma\text{Variation} + \text{Deviation} = 3 + 2 = 5^{\circ}\text{E}$

- If the variation is  $4^{\circ}\text{W}$ , and the deviation is  $2^{\circ}\text{E}$ . Calculate the compass error?

Solution:

Variation =  $4^{\circ}\text{W}$

Deviation =  $2^{\circ}\text{E}$

Compass error =  $-4 + 2 = 2^{\circ}\text{W}$



# Examples (4 & 5)

- If the C Bearing =  $052^{\circ}\text{C}$ , Var.  $4^{\circ}\text{W}$  and the Dev. =  $1^{\circ}\text{E}$ . Calculate True Bearing.

Solution:

Variation =  $4^{\circ}\text{W}$

Deviation =  $1^{\circ}\text{E}$

Compass error =  $3^{\circ}\text{W}$

C. Bearing =  $052^{\circ}\text{C}$

C. error =  $3^{\circ}\text{W}$

T. Brg. =  $049^{\circ}$

- If the compass Bearing is  $028^{\circ}\text{C}$ , and the true Bearing is  $025^{\circ}\text{T}$ , Find the Compass error.

Solution:

T. Brg. =  $025^{\circ}\text{T}$

C. Brg. =  $028^{\circ}\text{C}$

Compass error =  $003^{\circ}\text{W}$

Note: (If C less than T the error is East and if C greater than T is West.)

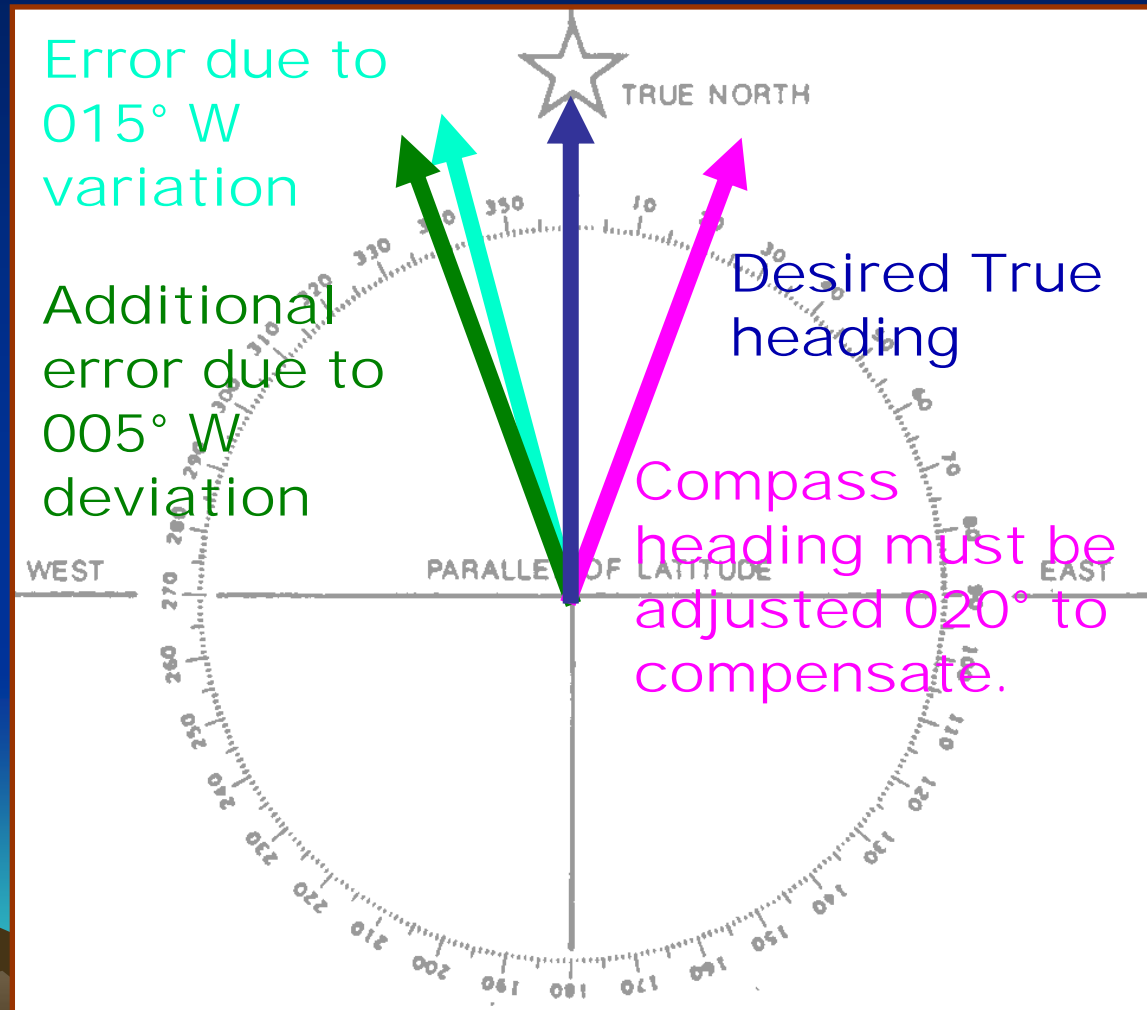


# Deviation: Ship-Specific Error

- Due to on-board magnetic influences:
  - Magnetic items
  - Items to which magnets are attracted.
  - Wires carrying DC electrical current.
- Reduce effects as much as possible:
  - Keep compass away from influences
  - Twist nearby DC wire pairs.
- Usually can't eliminate them all.



# Additive Effect of Compass Errors





# Measuring Deviation Yourself

- By using Deviation table or Curve we can obtain the deviation value of a specific Compass course.
- First you have to know how to do some compass calculations.



# Compensation

- Deviation often greater than  $10^\circ$ .
- Special magnets (compensators) installed in compasses to reduce error.
- Most compasses come with instructions.
- Can still have significant deviation error after compensation.



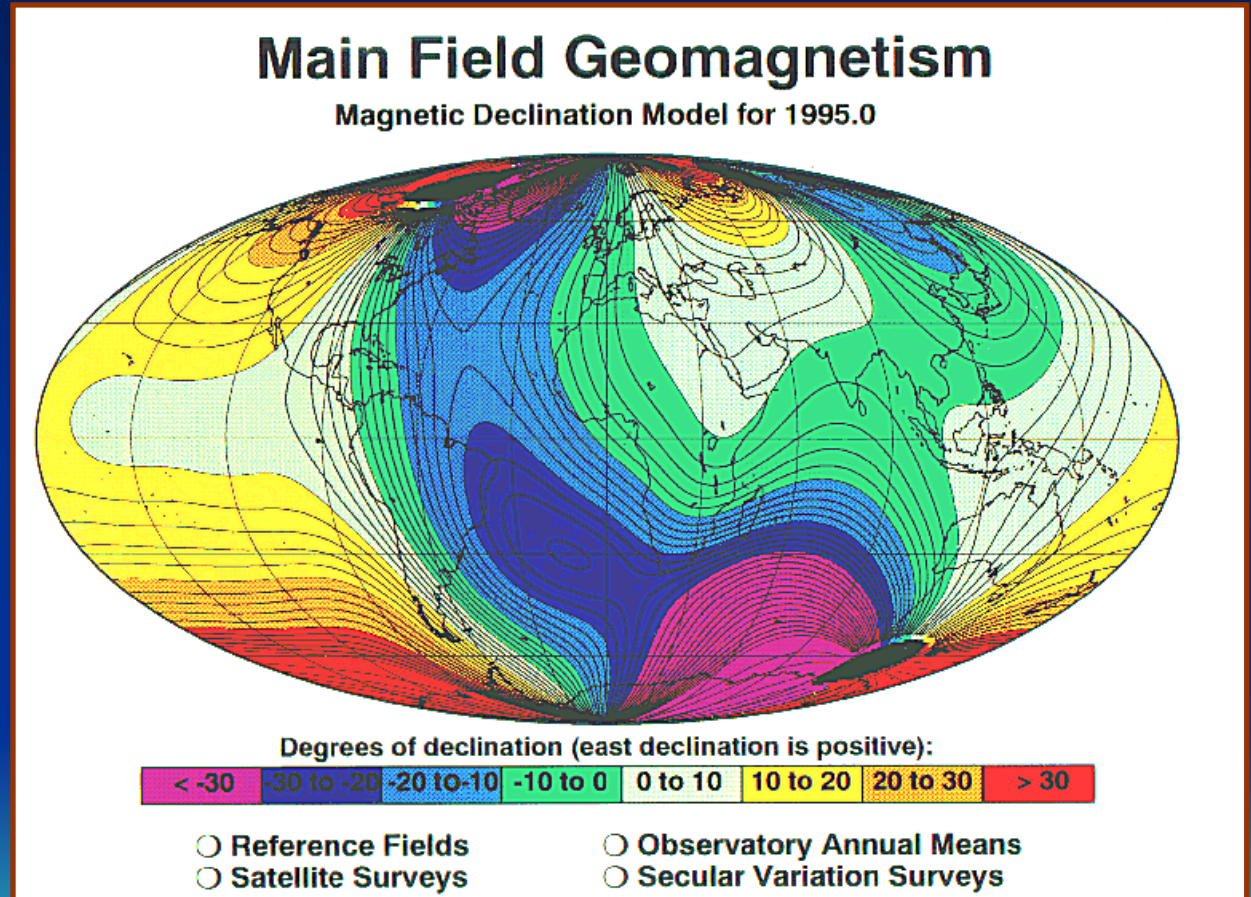
# Computing Compass Corrections



T	True Heading	000
V	Variation on Chart	015 W
M	Magnetic Heading	015
D	Deviation	005 W
C	Compass Course	020

# World-Wide Variation

- Isogonic Chart
- Illustrates magnetic variation (1995)



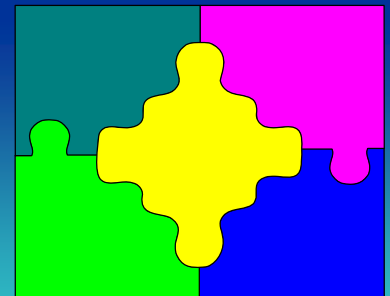
# “Swinging Ship”

- Process of measuring residual deviation error after compensation.
- Usually determined in  $15^\circ$  -  $30^\circ$  heading increments.
- Recorded in form of deviation table.
- Compass adjuster can provide service.
- Or, you can do it yourself ...



# Back to Measuring Deviation

- For each  $15^\circ - 30^\circ$ , you need to:
  - Know exactly what direction (magnetic) your boat is pointed.
  - Compare with compass reading.
  - Compute deviation.
- Key to puzzle is knowing exactly what direction you're headed.
- There are several ways ...



# Example Way to Know Your Heading

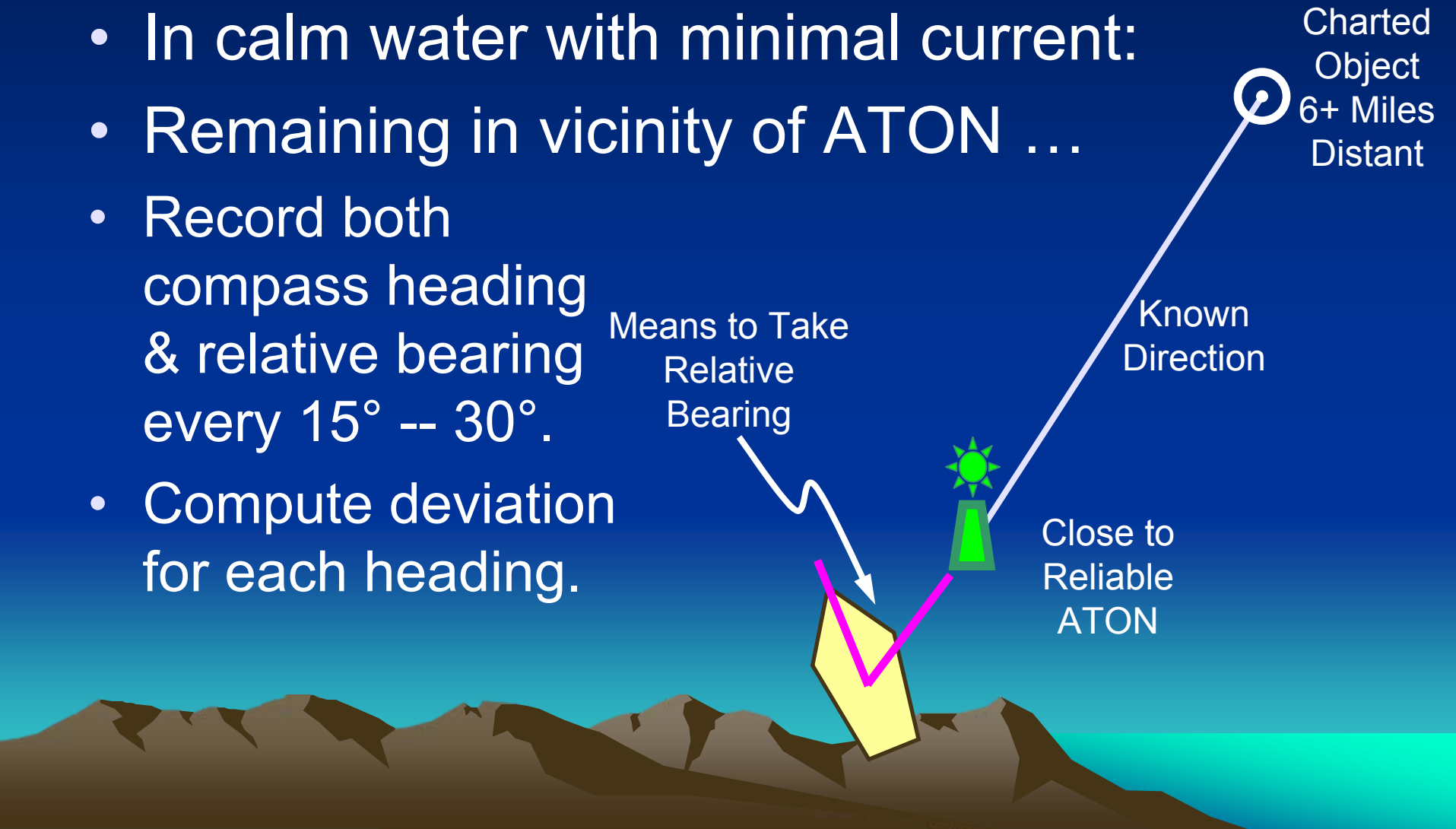
- In calm water with minimal current:
- Remaining in vicinity of ATON ...
- Record both compass heading & relative bearing every  $15^\circ$  --  $30^\circ$ .
- Compute deviation for each heading.

Means to Take  
Relative  
Bearing

Known  
Direction

Charted  
Object  
6+ Miles  
Distant

Close to  
Reliable  
ATON



# Measuring Relative Bearings

- Mounted parallel to vessel's keel with all-around view.
- $0^\circ$  aligned with keel.
- Align targets in sights.
- Read relative bearing on scale.





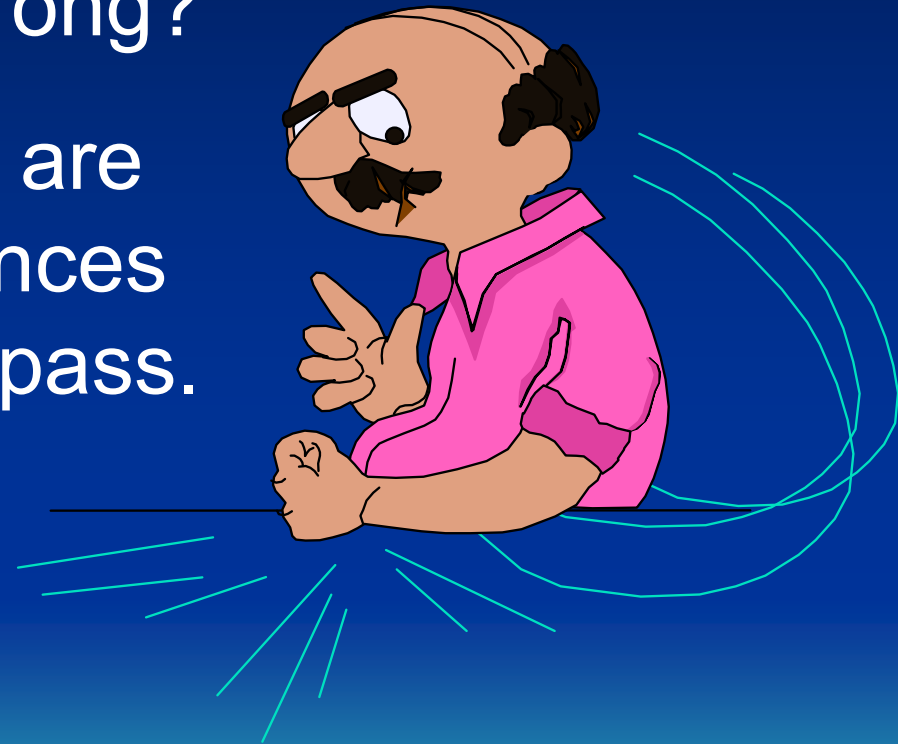
# Electronic Steering Compasses

Feature automated  
deviation elimination!



# Local Magnetic Disturbances

- Compass still seems wrong?
- In some locations there are local magnetic disturbances that can affect your compass.
- Often noted on charts.



# All this sound complex?

Perhaps, but the best solution is:

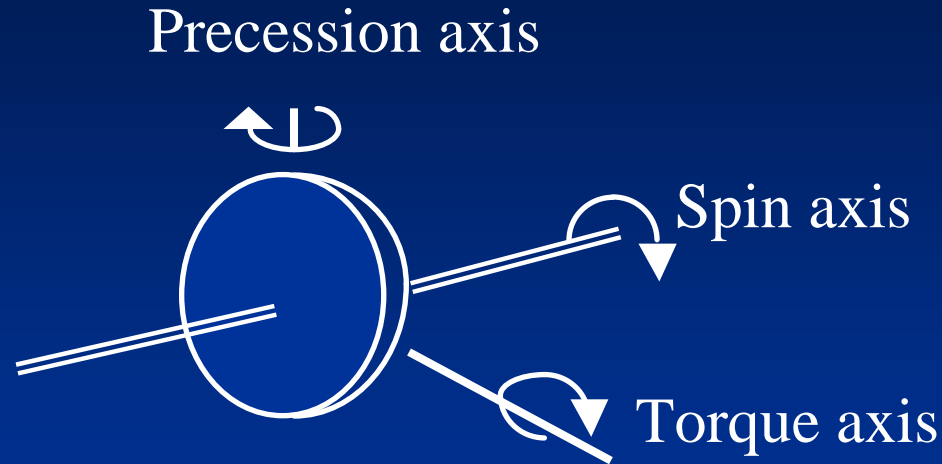
Practice ...

Practice ...

Practice!



# Shipboard Compasses



–The gyrocompass has three axes: the *spin axis*, *torque axis*, and *precession axis*.

–As centrifugal force of the earth's rotation (tangential velocity), acts upon the gyro, the torque and precession axis will react, and keep the spin axis oriented to a terrestrial meridian.

# *Shipboard Compasses*

- The Gyro-compass (cont'd)
  - The gyrocompass has several advantages over the magnetic compass:
    - **It seeks true or geographic meridian instead of magnetic meridian.**
    - It can be used near the earth's magnetic poles, where the magnetic compass is useless.
    - It is not affected by surrounding material.
    - Its signal can be fed into inertial navigation systems, automatic steering systems, and fire control systems.
  - Being a complicated electronic instrument, the gyrocompass has some disadvantages
    - It requires a constant source of electrical power and is sensitive to power fluctuations.
    - It requires periodic maintenance by qualified technicians.

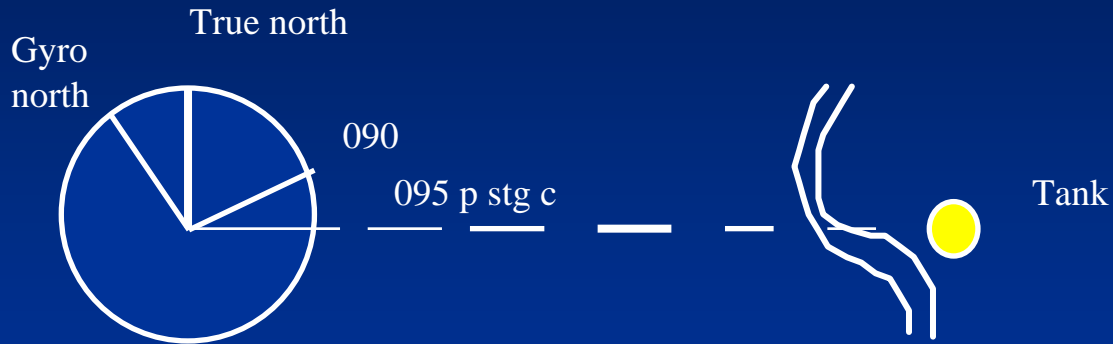
# *Shipboard Compasses*

- Methods of determining gyrocompass error
  - Although the gyrocompass is a very accurate instrument and normally has a very small error associated with its readings (less than  $.1^{\circ}$  to  $.2^{\circ}$ ).
  - The navigator is required to determine gyro error at least once a day.
  - Gyrocompass error like magnetic compass error, is measured in degrees east or west

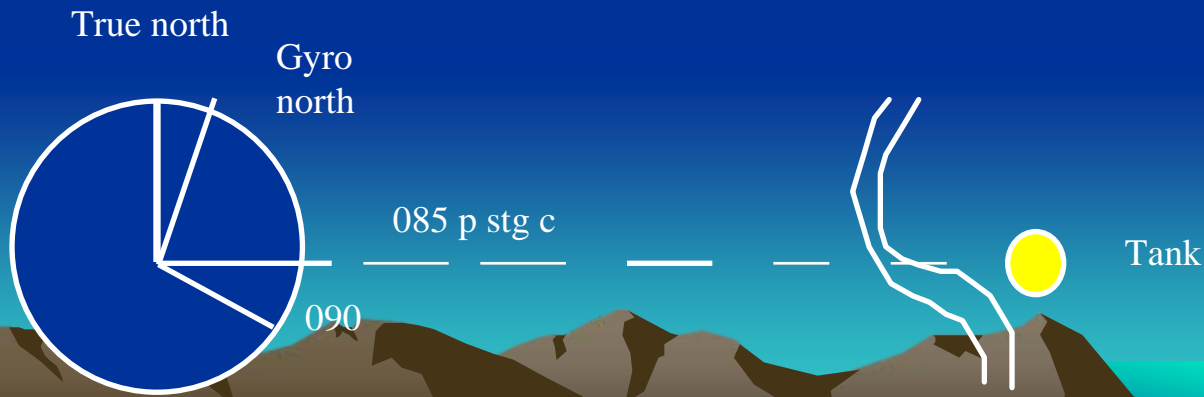


# Shipboard Compasses

- If the gyrocompass bearing is higher than the actual bearing, the error is west



- If the gyrocompass bearing is lower than the actual bearing, the error is east



# End Chapter 3

