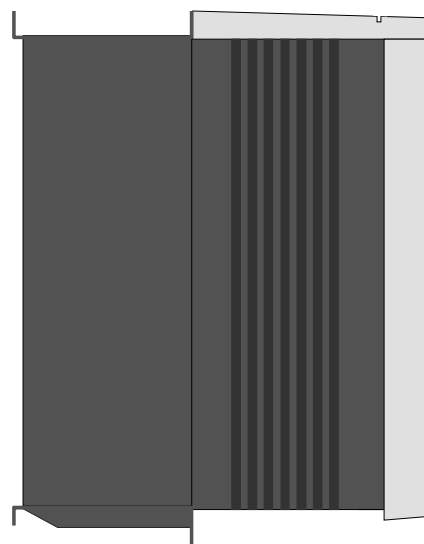
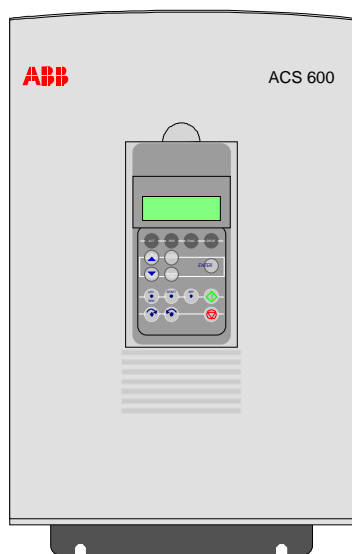


This manual includes

- Safety
- Installation
- Maintenance
- Product Information

## ACS/ACC/ACP 601 AC Drives 3 to 150 Hp (2.2 to 110 kW)





ACS/ACC/ACP 601 AC Drives  
3 to 150 Hp  
(2.2 to 110 kW)

**Hardware Manual**

This manual concerns the ACS 601, ACC 601 and ACP 601 AC Drives. In the text, they are collectively referred to as ACx 601.

ACS601-5.0-US-04  
3AUA 489002B4973 R0101 REV A

EFFECTIVE: 10/1/98  
SUPERSEDES: NONE

ACS601 Installation & Start-up Manual



# Safety Instructions

---

## Overview

This chapter states the safety instructions which must be followed when installing, operating and servicing the ACx 600. If neglected, physical injury and death may follow, or damage may occur to the AC drive, the motor and driven equipment. The material in this chapter must be studied before attempting any work on, or with, the unit.

## Warnings and Notes

This manual distinguishes two sorts of safety instructions. Warnings are used to inform of conditions which can, if proper steps are not taken, lead to a serious fault condition, physical injury and death. Notes are used when the reader is required to pay special attention or when there is additional information available on the subject. Notes are less crucial than Warnings, but should not be disregarded.

### Warnings

Warnings are provided in the instruction manuals and on labels attached to the AC drive. Readers are informed of situations that can result in serious physical injury and/or serious damage to equipment with the following symbols:



**Dangerous Voltage Warning:** warns of situations in which a high voltage can cause physical injury and/or damage equipment. The text next to this symbol describes ways to avoid the danger.



**General Warning:** warns of situations which can cause physical injury and/or damage equipment by means other than electrical. The text next to this symbol describes ways to avoid the danger.



**Electrostatic Discharge Warning:** warns of situations in which an electrostatic discharge can damage equipment. The text next to this symbol describes ways to avoid the danger.

### Notes

Notes are provided in the instruction manuals to notify readers of the need for special attention or additional information available on the subject with the following symbols:

#### CAUTION!

**Caution** aims to draw special attention to a particular issue.

#### Note:

**Note** gives additional information or points out more information available on the subject.

## Installation and Maintenance Safety

These safety instructions are intended for all work on the ACx 600. In addition to the instructions given below, there are more safety instructions on the first pages of the appropriate hardware manual.

---



**WARNING!** All electrical installation and maintenance work on the ACS 600 should be carried out by qualified electricians.

The ACS 600 and adjoining equipment must be properly grounded.

Do not attempt any work on a powered ACS 600. After switching off the power, always allow the intermediate circuit capacitors 5 minutes to discharge before working on the drive, the motor or the motor cable. It is good practice to check (with a voltage indicating instrument) that the drive is in fact discharged before beginning work.

The ACS 600 motor cable terminals are at a dangerously high voltage when power is applied, regardless of motor operation.

The brake control terminals (UDC+, UDC-, R+ and R- terminals) carry a dangerous DC voltage (over 500V).

There can be dangerous voltages inside the ACx 600 from external control circuits when the ACx 600 input power is shut off. Exercise appropriate care when working with the unit. Neglecting these instructions can cause physical injury and death.

---



**WARNING!** The ACS 600 introduces electric motors, drive train mechanisms and driven machines to an extended operating range. The ACS 600 can be adjusted to operate the motor at speeds above and below the speed provided by connecting the motor directly to the power line. Before adjusting the drive and putting it into service, make sure that the motor and all driven equipment is suitable for operation throughout the speed range provided by the AC drive.


---



**WARNING!** If an external source for start command is selected and it is ON, the ACS 600 will start immediately after fault reset unless the drive is configured for 3-wire Start/Stop.

---



**WARNING!** When the control location is not set to Local (L not shown in the status line of the display), the Stop key on the Control Panel will not stop the drive. To stop the drive using the Control Panel you must press the LOC/REM key and then the Stop key .

---



**WARNING!** The printed circuit boards contain integrated circuits that are extremely sensitive to electrostatic discharge. Exercise appropriate care when working on the unit to avoid permanent damage to the circuits. Do not touch the boards unnecessarily.

---






---

**WARNING!** There are several automatic reset functions in the ACx 600. If selected, they reset the unit and resume operation after a fault. These functions should not be selected if other equipment is not compatible with this kind of operation, or dangerous situations can be caused by such action.

---

### **Supply Connections**

The ACx 601 does not include a disconnecting means. An input power disconnecting means must be installed between the AC power source and the ACx 601. The disconnecting means must conform to the applicable safety regulations. The disconnecting means must be locked in the open position during installation and maintenance work.

The motor must not be controlled with the supply disconnecting means; instead, the  and  keys of the Control Panel or commands via the I/O board of the ACx 600 should be used. The maximum number of charging cycles of the d.c. capacitors of ACx 600 (i.e. power-ups by applying power) is five in ten minutes.




---

**WARNING!** Never connect the line power to the ACx 600 output terminals U<sub>2</sub>, V<sub>2</sub>, or W<sub>2</sub>. If frequent bypassing is required, mechanically interlocked switches or contactors should be employed. Line voltage applied to the output can result in permanent damage to the unit.

Operation outside the nominal input line voltage range should not be attempted, as overvoltages can result in permanent damage to the ACx 600.

---

If an ACx 601 with the integrated EMC filter (code 0 in the type code for EMC Filters) is connected to an ungrounded power system or high resistance grounded power system (over 30 Ohms), the power line will be connected to ground potential through the EMC filter capacitors of the ACx 601. This may cause danger or damage the unit. Disconnect the EMC filter capacitors before connecting the ACx 601 to an ungrounded power system. For detailed instructions on how to do this, please contact your local ABB distributor.

### **Ground Fault Protective Function**

The ACx 600 (with Standard and Motion Control Application Programs) is equipped with an internal ground fault protective function to protect the unit against ground faults in the drive, the motor and the motor cable. This is not a personal safety or a fire protection feature. The ground fault protective function of the ACS/ACP 600 can be disabled by Parameter 30.17 (ACC: 30.11).

The EMC filter of the ACx 600 includes capacitors connected between the power circuit and the chassis. These capacitors increase the ground leakage current from the AC line through the ground (PE) connection and may cause some ground fault current circuit breakers to trip.

### **Emergency Stop Devices**

The person responsible for the overall design and operation of the driven process must make sure that the installation includes emergency stop devices and any other safety equipment that may be needed. Pressing the STOP key on the Control Panel of ACx 600 does not generate an emergency stop of the motor or separate the drive from dangerous potential. A Line Contactor with provisions for a remote power cut-off switch is available as a factory installed option for the ACx 607. Cutting off power to the drive allows the motor to coast to a stop.

### **Ground Connections**

The ACS 600 and adjoining equipment must be properly grounded. The ACS 600 and the motor must be grounded at the installation site to ensure personnel safety in all circumstances and in addition to reduce electromagnetic emission and pick-up. Make sure that grounding conductors are adequately sized as required by safety regulations. In CE compliant installations and in other installations where EMC emissions must be minimized, 360 degree high frequency grounding of cable entries is done in order to suppress electromagnetic disturbances. In addition, power cable shields must be connected to the ground (PE) in order to meet safety regulations. Power cable shields are suitable for use as equipment grounding conductors only when the shield conductors are adequately sized as required by safety regulations. The ACS 600 ground terminals should not be connected in series in case of a multiple installation. Incorrect grounding can cause physical injury, death or equipment malfunction and increase electromagnetic interference.

### **Motor Connections**



---

**WARNING!** Operation is not allowed if the motor nominal voltage is less than one half of (ACP: 0.4 times) the ACx 600 nominal input voltage, or the motor nominal current is less than 1/6 of the ACx 600 nominal output current.

---



---

**WARNING!** Do not make any voltage tolerance or insulation resistance test (Hi-Pot or Megger) on any part of the ACx 600. Disconnect motor wires before making any tests of the motor or the cables between the drive and motor.

---

### **Motor Insulation Requirements**

As with all AC drives employing the most modern IGBT inverter technology, the output waveform of the ACx 600 consists of a series of rectangular voltage pulses. Regardless of the output frequency, the



voltage of the pulses is approximately 1.35 times the input line voltage with a very short rise time.

The voltage of the pulses can be almost double at the motor terminals, depending on the properties of the cable between the drive and the motor. This in turn can cause additional stress to the motor insulation. The motor manufacturer should be consulted regarding the characteristics of the motor insulation system. Failure of the motor to fulfill the following requirements may shorten its life.

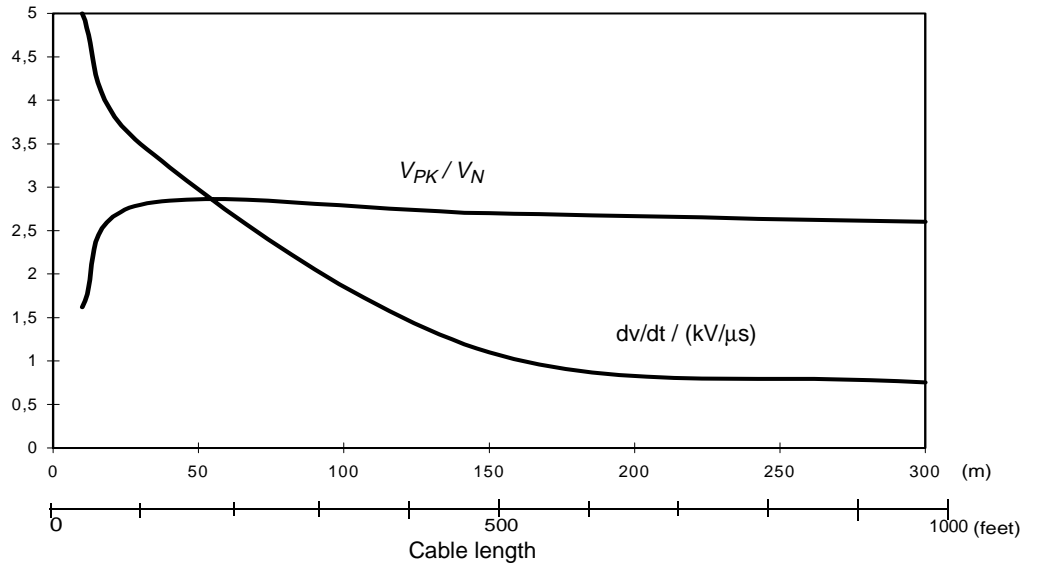
The following table lists the insulation requirements for motors used with ACx 600 AC drives.

Motor Type	Nominal AC Line Voltage	Motor Insulation Requirement
<b>ABB Motors</b> (manufactured from beginning of 1998)	$V_N < 500 \text{ V}$	Standard insulation system
	$525 \text{ V} \leq V_N \leq 690 \text{ V}$	Standard insulation and dv/dt filter or special insulation system
<b>Random-wound Motors</b>	$V_N \leq 420 \text{ V}$	Motor insulation system must withstand $V_{PK} = 1300 \text{ V}$ .
	$420 \text{ V} < V_N \leq 500 \text{ V}$	If motor insulation system withstands $V_{PK} = 1600 \text{ V}$ and $0.2 \mu\text{s}$ rise time, a dv/dt filter is not needed.  With a dv/dt filter at the output of the ACx 600, motor insulation system must withstand $V_{PK} = 1300 \text{ V}$ .
	$500 \text{ V} < V_N \leq 600 \text{ V}$	Motor insulation system must withstand $V_{PK} = 1600 \text{ V}$ . A dv/dt filter must be used at the output of the ACx 600.
	$600 \text{ V} < V_N \leq 690 \text{ V}$	Motor insulation system must withstand $V_{PK} = 1800 \text{ V}$ . A dv/dt filter must be used at the output of the ACx 600.
<b>Form-wound Motors</b>	$V_N \leq 690 \text{ V}$	If motor insulation system withstands $V_{PK} = 2000 \text{ V}$ and rise time $0.3 \mu\text{s}$ , no dv/dt filter is needed.

Symbol	Definition
$V_N$	nominal power line voltage
$V_{PK}$	peak line to line voltage at motor terminals
Rise time:  $\Delta t = 0.8 \cdot V_{PK} / (dv/dt)$	Rise time is line to line voltage change rate at motor terminals (the interval during which the voltage changes from 10 % to 90 % of the whole voltage range)  $V_{PK}$ and $\Delta t$ depend on cable length. Read the values of $V_{PK}$ and $dv/dt$ from the diagrams below.

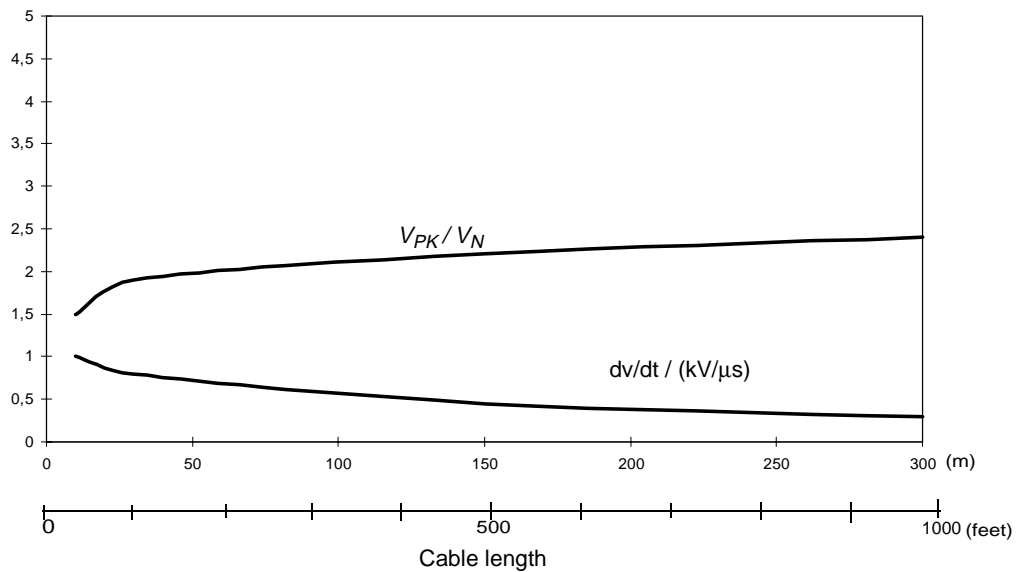
*Without Filter*

Below is a diagram of  $V_{PK}$  and  $dv/dt$  as a function of cable length when no  $dv/dt$  filter is used.



*With  $dv/dt$  Filter*

Below is a diagram of  $V_{PK}$  and  $dv/dt$  as a function of cable length with  $dv/dt$  filter at the output of the ACx 600.



**Power Factor Correction Capacitors**

Power factor correction capacitors and surge absorbers must not be connected between the drive and the motor. These devices are not designed to be used with AC drives, and will degrade motor control accuracy. They can cause permanent damage to the ACx 600 or themselves due to the rapid changes in the ACx 600 output voltage.

If there are power factor correction capacitors in parallel with the ACx

600 make sure that the capacitors and the ACx 600 are not charged simultaneously to avoid voltage surges which might damage the unit.

### **Output Contactors**

If a contactor is used between the output of the ACx 600 and the motor with DTC control mode selected, the output voltage of the ACx 600 must be controlled to zero before the contactor is opened: ACS 600 units via parameter 21.3 (ACP: 10.4), choose COAST. If RAMP is selected, the output of the ACS/ACP 600 must be reduced to zero using Parameter 16.1 by giving zero V DC to the selected digital input. Otherwise the contactor will be damaged. In scalar control the contactor can be opened with ACS/ACC 600 running.

Varistors or RC networks (AC) or diodes (DC) should be used to protect against voltage transients generated by contactor coils. The protective components should be mounted as close as possible to the contactor coils. Protective components should not be installed at the NIOC board terminal block.

### **EMC**

When used with inductive loads (relays, contactors, motors), the relay contacts of ACx 600 must be protected with varistors or RC networks (AC) or diodes (DC) against voltage transients. The protective components should not be installed at the NIOC board terminal block.

Installing control devices (contactors or relays) or control cables other than those of the ACS 600 inside the drive enclosure is not acceptable.

---

**Note:** If safety switches, contactors, connection boxes or similar equipment are installed between the drive and the motor, they should be installed in a metal enclosure in a way that the conduit or motor cable shielding runs consistently without breaks from the drive to the motor, so the emission level will be minimized.

---

### **Mechanical Installation**

**CAUTION!** The ACx 601 weighs a considerable amount, and should not be handled by the front cover. The unit should only be placed on its back. Exercise appropriate care when maneuvering the unit to avoid damage and injury. Lifting the ACx 601 is much easier and safer with two people working together.

**CAUTION!** Make sure that dust from drilling does not enter the ACx 600 when installing. Electrically conductive dust inside the unit may cause damage or lead to malfunction.

**CAUTION!** Do not fasten the ACx 600 by riveting or welding.



**WARNING!** The cooling air flows and space requirements must be fulfilled. Special attention must be paid to cooling if units are installed in confined spaces and user defined cabinets.

---

*Safety Instructions*

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# Chapter 1 – Introduction

---

## **General**

The ACS 600 product family of three phase AC drives includes

- the ACS 600 (for most applications)
- the ACP 600 (for positioning, synchronizing and other high-precision control applications)
- the ACC 600 (for crane drive applications)
- the ACS 600 MultiDrive (for multidrive applications)

The application programs are introduced in *Appendix – A*.

Study this manual carefully before installing, commissioning, operating or servicing the drive. We expect that you have a basic knowledge of physical and electrical fundamentals, electrical wiring practices, electrical components and electrical schematic symbols.

## **Delivery Check**

Check that there are no signs of damage. Before attempting installation and operation, check the information on the drive nameplate to verify that the unit is of the correct model.

**Nameplate** Each ACx 600 has a nameplate for identification purposes. See Figure 1-1. The nameplate data includes a type code and a serial number, which allow individual recognition of each unit.

**Type Code** The ACx 600 Type Code contains information on the properties and configuration of the drive. The Type Code Chart explains the significance of each digit or character in the Type Code.

**Frame Size** ACx 600 drives are manufactured in several different chassis sizes that are designated as Frame R2, R3, etc. Drives of several different ratings are manufactured in the same frame. The ACx 600 rating tables on page A-1 in Appendix A list the Frame Size used for each Type Code. The Frame Size is not marked on the nameplate.

**Serial Number** The first digit of the serial number refers to the manufacturing plant. The next three digits refer to the units manufacturing year and week, respectively. The remaining digits complete the serial number so that there are no two units with the same serial number.

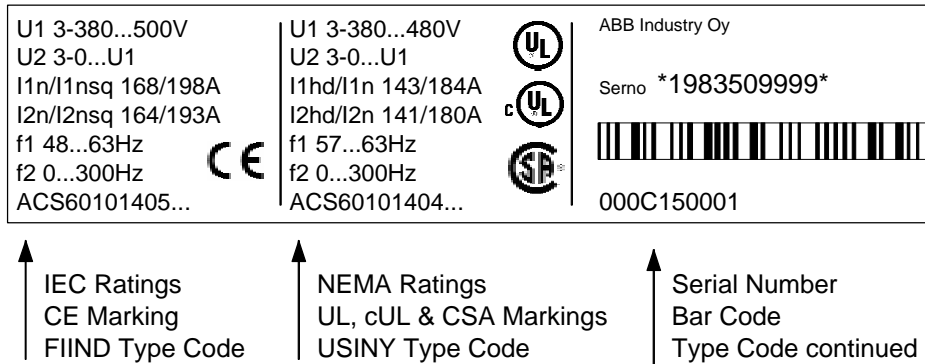


Figure 2-1. ACX 601 Nameplate

### ACx 601 Type Code

The meaning of main selections of ACx 601 type code characters is given in the table below. Not all selections are available for all types. More information on selections is available in ACS 600 price list.

Character no.	Meaning	Refer to
Example: ACS60701003000B1200901		
1	<b>Product Category</b> A = AC Drive	
2...3	<b>Product Type</b> CS = Standard, CC = Crane Drive, CP = MotionControl	
4	<b>Product Family</b> 6 = ACS 600	
5	<b>Input Bridge</b> 0 = 6-pulse rectifier, 2 = 12-pulse rectifier, 7 = Regenerative 4Q thyristor bridge	
6	<b>Construction</b> 1 = Wall mounted, 4 = Module, 7 = Drives-MNS Cabinet	
7...10	<b>Power Rating (kVA)</b>	Appendix A: Ratings
11	<b>Voltage Rating</b> 3 = 380/400/415 VAC 4 = 380/400/415/440/460/480/500 VAC 5 = 380/400/415/440/460/480/500 VAC 6 = 525/550/575/600/660/690 VAC	
12...14	<b>Option 1, Option 2, Option 3</b>	
15	<b>Application Software</b> x = Languages and Application Macro Options	Appendix A: Application Programs
16	<b>Control Panel</b> 0 = None, 1 = CDP 312 Control Panel included, 4 = Customer I/O Terminal Block X2, 5 = 1 + 4	

Character no.	Meaning	Refer to
17	<b>Degree of Protection</b> 0 = IP 00 (chassis), A = IP 21, 2 = IP 22, 4 = IP 42, 5 = IP 54, 6 = IP 00 with Coated Boards, 7 = IP 22 with Coated Boards, 8 = IP 42 with Coated Boards 9 = IP 54 with Coated Boards B = IP 21 with Coated Boards	<i>Appendix A: Enclosures</i>
18	<b>Line Input and Protection Options</b>	
19	<b>Starter for Auxiliary Motor Fan</b>	
20	<b>Filters</b> 0 = CE with EMC Filters (not for 690V or 12-pulse rectifier) 3 = CE with output dv/dt Filters + EMC Filters (not for 690V) 5 = Output dv/dt Filters + no EMC Filters 8 = US Standard, US conduit: No CE, no EMC filters, 9 = CE Low Voltage and Machinery Directives; No EMC (ACS 607 only, secondary of all transformers 220 VAC)	<i>Appendix A: CE marking</i>
21	<b>Braking Chopper and Cabling Direction</b> 0 = No Brake Chopper - Bottom Entry / Bottom Exit (BE/BE) 1 = Brake Chopper (BE / BE) 3 = Input Power Top Entry / Output Power Bottom Exit 4 = Input / Output Power Top Entry / Exit 5 = Option 1 and 3 6 = Option 1 and 4	
22	<b>Other Options</b> 0 = None, 1 = Version 5.0 Software	

### ***Inquiries***

Any inquiries about the product should be addressed to the local distributor or ABB representative, quoting the type code and the serial number of the unit. If the local ABB representative cannot be contacted, inquiries should be directed to the address and phone numbers on the back cover of this manual.



## Chapter 2 – Mechanical Installation

---

The ACx 601 should be installed in an upright position with the cooling section mounted against a flat surface. The mounting surface should be as close to vertical as possible and of non-flammable material.

Sufficient room around the ACx 601 is required to enable cooling air flow, service and maintenance. Refer to Enclosure space Requirements in Appendix A on page A-9. Be sure to also observe all requirements of applicable safety regulations.

### **Check The Installation Site**

Check the intended installation site to make sure that the environment is suitable. The service life and performance of the ACx 600 can be adversely affected if the drive is subjected to unsuitable environmental conditions. Complete environmental rating specifications are listed in Appendix A.

If unsuitable conditions are found at the intended installation site, select a different location, improve the environment at the selected site, or provide additional protection for the ACx 601.

### **Installation Site Checklist**

- Make sure that the ambient temperature is suitable for the type of enclosure provided and the output current required. (pages A-3 & A-4 and A-12)
- Make sure that the installation site altitude is suitable for the output current required. (A-12)
- Make sure that the ambient air is sufficiently clean and dry or that the drive is adequately protected from contaminants. (A-12)
- Make sure that the enclosure selected is adequate to protect the drive considering site conditions regarding access by unauthorized persons, liquids that might be splashed, sprayed or fall on the enclosure, or any other foreign material that might get into the enclosure.
- Do not mount the drive on any surface with temperature exceeding the allowable air temperature.
- Do not mount the drive in direct sunlight.
- Do not mount the drive where it will be subjected to excessive vibration. (A-12)

### Installation Procedure

Appendix B contains detailed dimensional drawings showing the overall dimensions of the ACx 601 drives and the sizes and locations of the mounting bolt holes or slots. The drives have four mounting holes or slots as shown in Figure 2-1.

---

**CAUTION!** Lift the ACx 601 by its chassis and not by its cover. (Frame R7 has lifting lugs to allow the use of a suitable lifting device).

---

1. Mark the locations of the mounting bolts by measuring to the dimensions shown in the drawings or by using the drive as a template.
2. Drill and tap or install appropriate anchors in the mounting surface.
3. Install the mounting bolts.
4. Position the ACx 601 onto the mounting bolts.
5. Tighten the bolts securely.

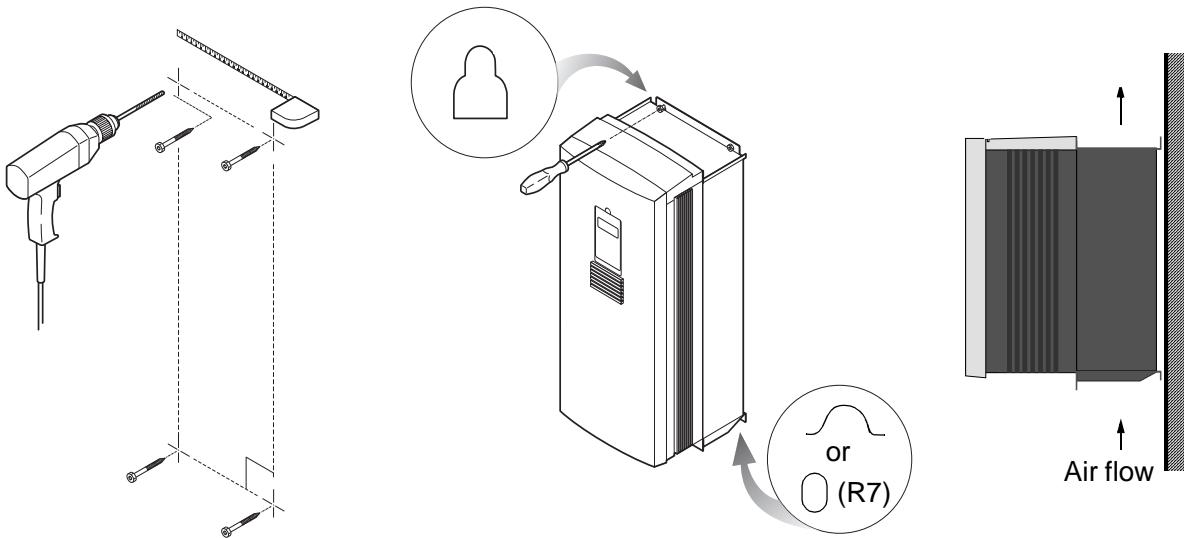


Figure 2-1 Installing the ACx 601 on a wall.

### Installation in a Cooling Air Duct

The ACx 601 design allows the unit to be recessed into a wall with the cooling section protruding into a special cooling air duct (frames R2 to R6). The cooling air grates in the bottom and the top of the unit must not be blocked by the wall or any other structure. Steps should be taken to enable service and maintenance access for the unit.

Refer to pages A-9 and A-10 for cooling air flow requirements and heat dissipation data.

The air in the cooling duct must meet the requirements stated on page

A-12 for ambient air. If the air in the cooling duct is not clean the enclosure class of the ACx 601 must be IP 54. Note the power ratings of the IP 54 units given on page A-4.

To install the ACx 601 in a cooling air duct, carry out the following steps:

1. See *Appendix B – Dimensional Drawings* for dimensions of the opening in the duct.
2. Cut the opening.
3. Drill and tap or install appropriate anchors in the mounting bolt locations at the top and bottom of the opening. It may be necessary to install angle iron or similar stiffeners to provide mounting points of sufficient strength and thickness.
4. Frame R2 and R3: Remove the two screws at the lower front edge of the unit. Lift the front cover somewhat and disconnect the Control Panel cable from the board fitted on the inside of the cover. Remove the front and top covers. (See Figure 3-1)
5. Frames R4 to R6: Remove the Control Panel. Remove the telephone connector. Remove the two screws at the lower front edge of the unit. Remove the front and top covers. (See Figure 3-2)
6. Follow the installation procedure in Figure 2-2.

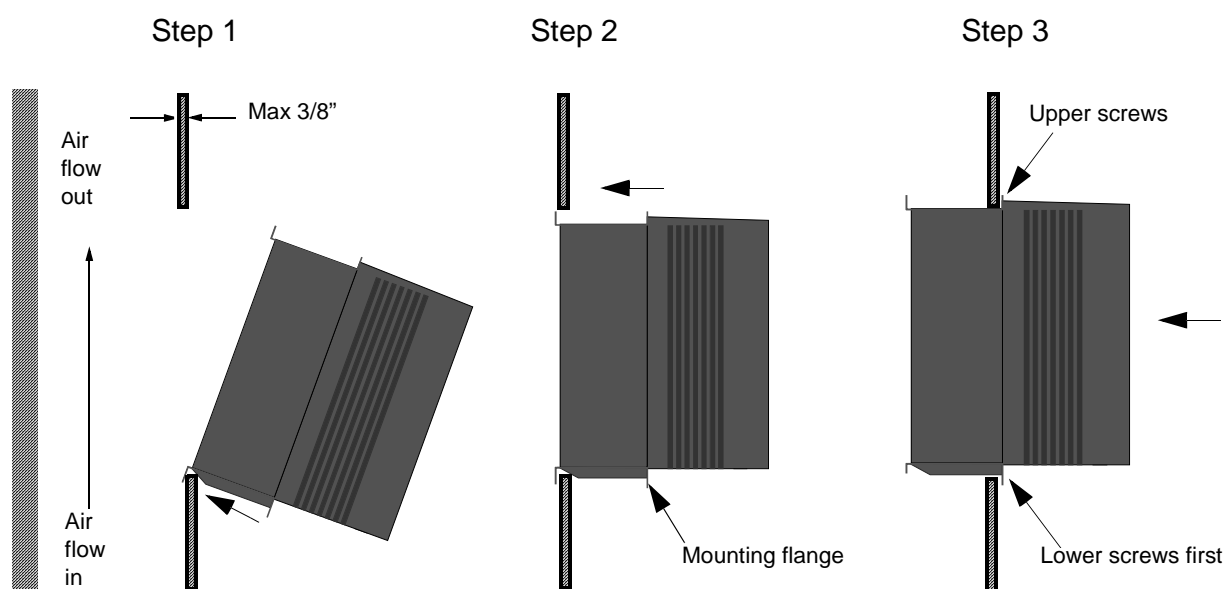


Figure 2-2 Installation procedure of the ACx 601 in a cooling air duct.





## Chapter 3 – Electrical Installation

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**WARNING!** The electrical installation described in this chapter should only be carried out by a qualified electrician. The *Safety Instructions* on the first pages of this manual must be followed. Negligence of these instructions can cause injury or death.

---

*Note:* The information presented in this chapter is primarily directed towards the North American market. For IEC installations, refer to Appendix C for additional information. For installations requiring CE compliance, refer also to the section entitled CE Marking in Appendix A.

### Insulation Checks

Before connecting the motor to the drive, check the insulation of the motor and the cable between the drive and the motor.

---



**WARNING!** Do not make any voltage tolerance or insulation resistance test (Hi Pot or Megger) on any part of the ACx 600.

---

A test (2500V rms, 50 Hz, 1 second) has been performed at the factory on every ACx 600 drive to verify the integrity of the insulation between the power circuitry and the chassis. To avoid damaging sensitive circuitry, this test is performed using a special procedure that can not easily be performed outside the factory.

Use the following procedure to check the insulation of the motor and the cable between the drive and the motor.

1. Disconnect all sources of power from the drive and motor.
- 



**WARNING!** Before proceeding with the insulation checks, make sure that the motor is disconnected from all sources of power including the drive and any bypass circuitry.

---



2. Check that the motor cable is disconnected from the ACx 601 output terminals U2, V2, and W2.
3. Check that the motor cable is disconnected from the motor and remove bridging connections at the motor.
4. Measure the insulation resistances of the motor between the phases and between each phase and Ground (PE). The voltage range of the resistance meter must be at least equal to the line voltage, but not higher than 1000V. The insulation resistance must

be greater than 1 M $\Omega$ .

5. Measure the insulation resistance of the motor cable between the phases and between each phase and Ground (PE). The insulation resistance must be greater than 1 M $\Omega$ .

### **Disconnecting Means**

The ACx 601 does not include a disconnecting means. An input power disconnecting means must be installed between the AC power source and the ACx 601. The disconnecting means must conform to the applicable safety regulations. The disconnecting means must be locked in the open position during installation and maintenance work.

The motor must not be controlled with the supply disconnecting means; instead, the  and  keys of the Control Panel or commands via the I/O board of the ACx 600 should be used. The maximum number of charging cycles of the d.c. capacitors of ACx 600 (i.e. power-ups by applying power) is five in ten minutes.

The drive disconnecting means can serve as the motor disconnecting means if it complies with applicable safety regulations.

### **Input Line Fuses**

Input line fuses are required to protect the input bridge of the ACx 600 in the event of an internal short circuit or ground fault. Fuses are not included in the drive and must be installed externally. The recommended ultrarapid fuses are listed in Appendix A. To ensure that adequate protection is maintained do not install slower types of fuses and do not allow blown fuses to be replaced with slower types.

The fuses recommended for input bridge protection can be installed as drive and motor branch-circuit short-circuit and ground fault protection if they comply with applicable safety regulations.

### **Motor Overload Protection**

The ACx 601 can provide overload protection for the motor by monitoring a thermostat or thermistor in the motor or by calculating the motor temperature from measured operating data. The overload protection provided by the drive complies with the requirements of UL508c. Additional overload protection is not required unless more than one motor is connected to the drive or unless additional protection is required by applicable safety regulations.

### **Power Cables**

The input power, motor and ground cables must be sized *according to local regulations*:

1. The cable must carry the ACx 600 load current.
2. The cable terminals of the ACx 600 warm up to 60 °C in use. The cable must be rated for at least 60 °C maximum operating temperature.

### **Cable Insulation Voltage Ratings**

As a minimum requirement, cable insulation voltage ratings must conform to all applicable safety regulations. In addition, motor

connecting cable insulation must accommodate the voltage peaks described under *Motor Insulation Requirements* on page vi of the Safety Instructions.

For drives that are rated up to 500 V, cables that have a 600 VAC insulation rating are suitable for both input power and motor wiring.

For drives that are rated over 500 V up to 600 V, cables that have a 600 VAC insulation rating are suitable for input power wiring. The motor wiring requires a higher voltage rating to accommodate the voltage peaks described under *Motor Insulation Requirements* on page vi of the Safety Instructions. As a general rule, the motor cable insulation should be rated for a minimum of 1000 V.

For drives that are rated over 600 V up to 690 V, cables that have a 1000 VAC insulation rating are suitable for both input power and motor wiring.

### **Wiring Practices**

---

**NOTE!** When installing the ACx 600 wiring, it is important to carefully follow the wiring practice recommendations presented in the following paragraphs. Following these recommendations will ensure reliable long term operation of the ACx 600 drive. If these recommendations are not followed, the drive may experience various problems such as:

- Improper drive performance
- Nuisance shutdown trips
- Damage to drive electronic circuits

Incorrect installation practices can also cause malfunctions or damage to other equipment through electromagnetic interference (EMI) and noise injected into the grounding system.

The drive warranty does not cover problems caused by improper installation.

---

When installing AC drive power wiring, wiring methods that provide shielding for the power cables reduce the possibility of electromagnetic interference (EMI). It is also important to ground the motor frame using a ground conductor connected to the grounding terminal in the drive. EMI reduction measures are most important for the motor wiring but are also applicable to the input power wiring.

Any wiring method that is in conformance with applicable safety regulations is acceptable for input power wiring. Metallic conduit or armored cable must be used for motor wiring. Detailed conduit and armored cable wiring practice guidelines are provided below.

Type MC continuous corrugated aluminum armor cable with

symmetrical grounds is the best type of wiring to provide a good low impedance high frequency ground return path between the motor and the drive. This helps to prevent high frequency ground current from flowing in a potentially damaging path through the motor bearings and connected load bearings. Type MC continuous corrugated aluminum armor cable with symmetrical grounds is highly recommended for motor connections to drives rated 490 KVA and larger.

**Conduit** Metallic conduit must be used for motor wiring unless armored cable is used. Where conduits must be coupled together, the joint must be bridged with a ground conductor bonded to the conduit on each side of the joint. The conduits must also be bonded to the drive enclosure. Use separate conduits for input power, motor, brake resistors and control wiring. The recommended wiring configuration is shown on page 3-8. Do not run motor wiring from more than one drive in the same conduit.

**Armored Cable** If metallic conduit is not used, type MC continuous corrugated aluminum armor cable with symmetrical grounds must be used for the motor cables. If type MC armor cables are used, the motor cables can be run in the same cable tray as other 480V or 600V power wiring. Control and signal cables must not be run in the same tray as power cables.

Six conductor (3 phases and 3 grounds) type MC continuous corrugated aluminum armor cable with symmetrical grounds is available from the following suppliers. Trade names are in parentheses.

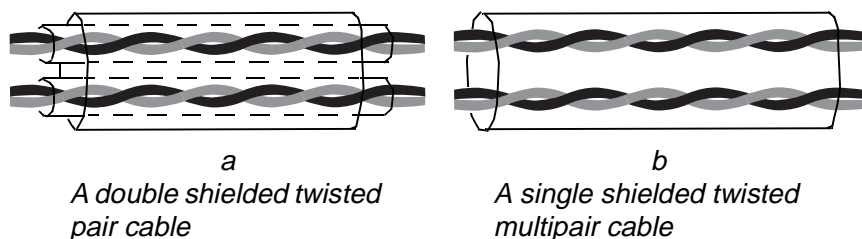
Anixter Wire & Cable (Philsheath)  
BICC Cables Corp. (Philsheath)  
Rockbestos Co. (Gardex)  
Oaknite (CLX)

### **Control Cables**

All control cables must be shielded. As a general rule, the control signal cable shield should be grounded directly in the ACx 600. The other end of the shield should be left unconnected. Twisting the signal wire with its return wire reduces disturbances caused by inductive coupling. Pairs should be twisted as close to terminals as possible.

A double shielded twisted pair cable (Figure a, e.g. Belden 9729) must be used for analog signals and is recommended for the pulse encoder signals. Employ one individually shielded pair for each signal. Do not use common return for different analog signals.

A double shielded cable is the best alternative for low voltage digital signals but single shielded twisted multipair cable (Figure b) is also usable.



The analog and digital input signals should be run in separate, shielded cables.

Relay-controlled signals, providing their voltage does not exceed 48 V, can be run in the same cables as digital input signals. It is recommended that the relay-controlled signals be run as twisted pairs.

**Never mix 24 VDC and 115 / 230 VAC signals in the same cable.**

#### *Encoder Cable (ACP 600)*

Min. 4 x 0.25 mm<sup>2</sup> (#22 AWG) + 2 x 0.5 mm<sup>2</sup> (#20AWG) min. single shielded twisted multipair cable, optical coverage ≥ 91 %. The maximum cable length is 150 m (500 ft.). Suitable cable recommendation is available from ABB.

#### *Control Panel Cable*

In remote use the cable connecting the Control Panel to the ACx 600 must not exceed 3 meters (10 ft). The cable type tested and approved by ABB is provided in Control Panel option kits.

### **Wiring Connections**



**WARNING!** This work should only be carried out by a qualified electrician. The *Safety Instructions* on the first pages of this manual must be followed. Negligence of these instructions can cause injury or death.

The input power and motor cables connect to the terminal block of the ACx 601 in the lower part of the frame. The control cables pass in front of the power terminals to the NIOC/NIOCP board.

To connect the input power, motor and control cables carry out the following procedure.



**WARNING!** Make sure that the ACx 601 is disconnected from the power network during installation. If the ACx 601 is already connected to the power, wait for 5 minutes after disconnecting power.

**Cover Removal** Remove the cover as illustrated in Figure 3-1 on page 3-6 (Frames R2 and R3), Figure 3-2 on page 3-7 (Frames R4 to R6), or Figure 3-3 on page 3-7 (Frame R7).

**Conduit Plate** Attach conduits to the conduit entry plate at the bottom of the drive. Knockout sizes and locations are shown on pages B-9 and B-10 in Appendix B. Terminal locations are shown on the dimensioned drawings in Appendix A. Select locations for input power, motor, brake resistor and control wiring according to terminal locations and size requirements.

**Wiring Connections** Connect the input power, motor, brake resistor and ground wires first and then connect the control wiring. Refer to Figure 3-4 on page 3-8 for the recommended wiring configuration. See Appendix B - ACS 601 Dimensional Drawings to locate the terminals on each ACS 601 type. See Appendix A page A-7 and A-8 for control connection details. Refer to the ACx 600 Firmware Manual for control I/O programming information.

**Option Modules** General installation instructions are provided on page 3-9. For specific instructions, refer to the Installation and Start-Up Guide for the option module.

**Cover Replacement** Replace the cover as shown in Figure 3-6 on page 3-9.

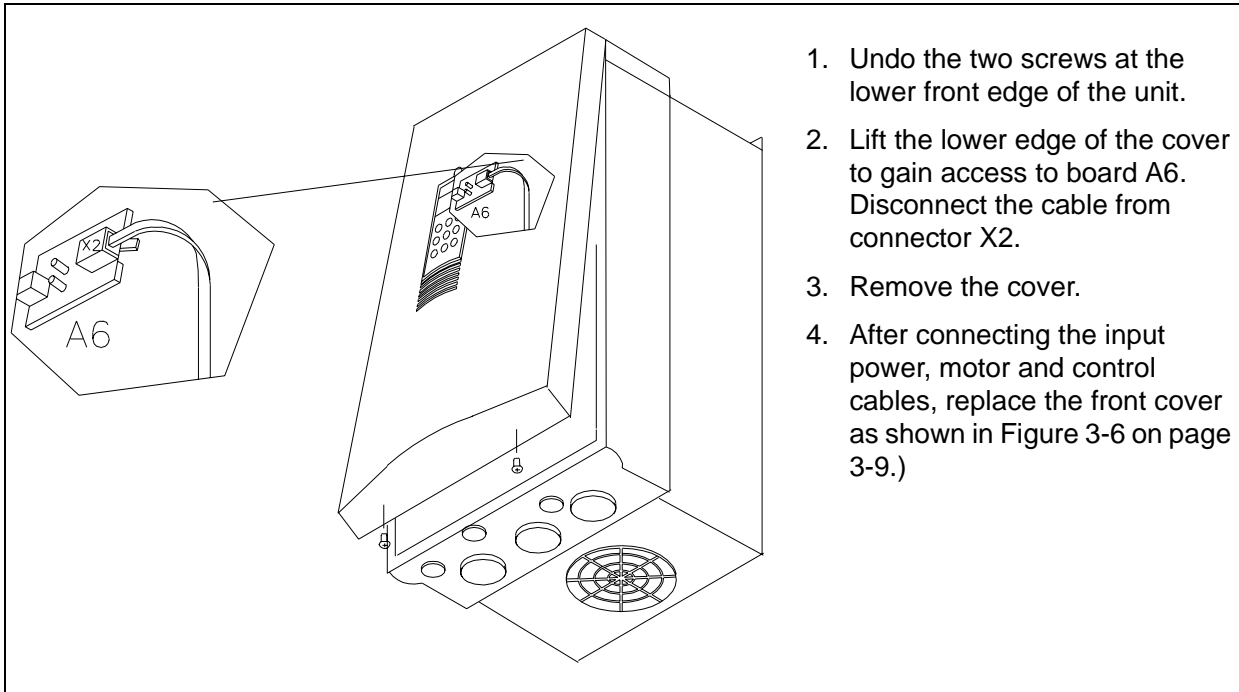
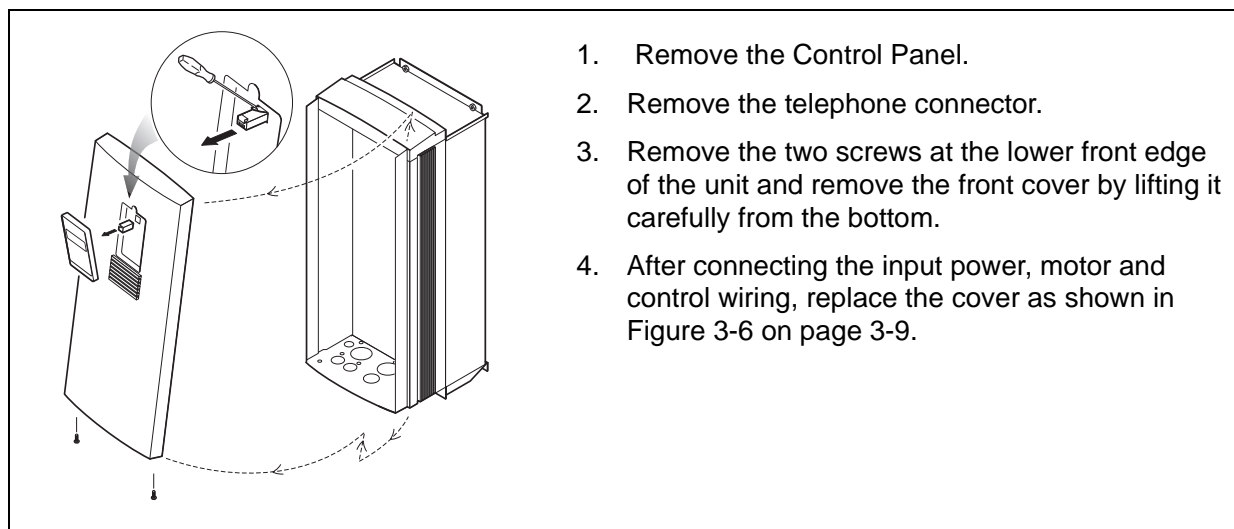
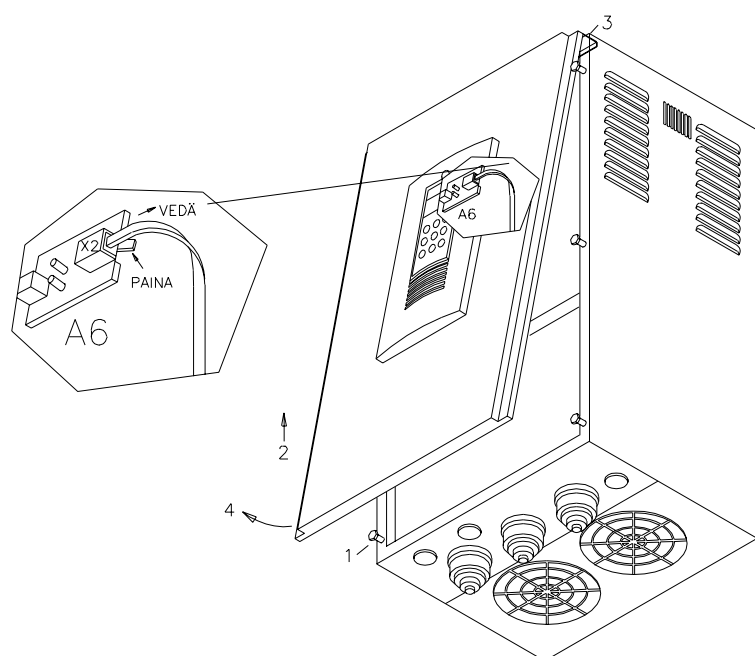


Figure 3-1 Frames R2 and R3: Removal of the cover



1. Remove the Control Panel.
2. Remove the telephone connector.
3. Remove the two screws at the lower front edge of the unit and remove the front cover by lifting it carefully from the bottom.
4. After connecting the input power, motor and control wiring, replace the cover as shown in Figure 3-6 on page 3-9.

Figure 3-2 Frames R4 to R6: removal of the cover



1. Loosen the screws of the cover.
2. Lift the cover somewhat upwards to release it from the screws.
3. Leave the cover hanging by its upper edge.
4. Lift the lower edge of the cover to gain access to board A6. Disconnect the cable from connector X2.
5. Remove the cover.
6. After connecting the input power, motor and control cables, replace the front cover as shown in Figure 3-6 on page 3-9.

Figure 3-3 Frame R7: Removal of the cover

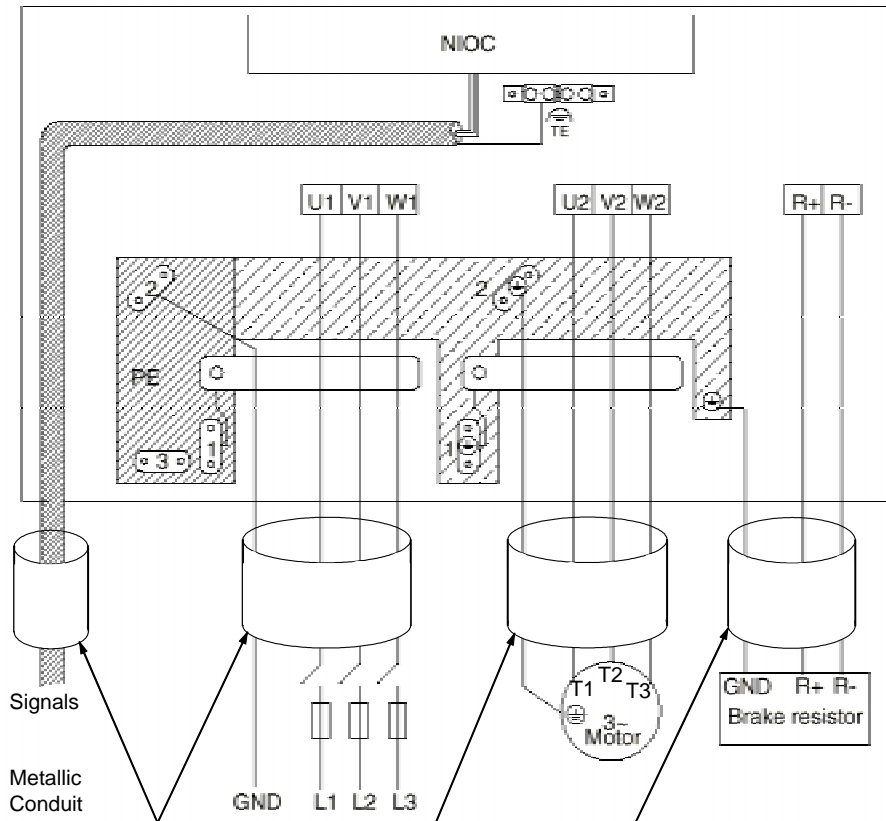
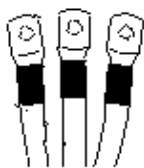


Figure 3-4 A view of the recommended wiring configuration.



In the R7 Frame, bolt connections are provided for connecting wires with ring lugs. Crimp ring lugs onto the phase conductors. Insulate the ends of the lugs using self-fusing (self-amalgamating) tape or shrink tubing.

Figure 3-5 Frame R7: Ring Lugs



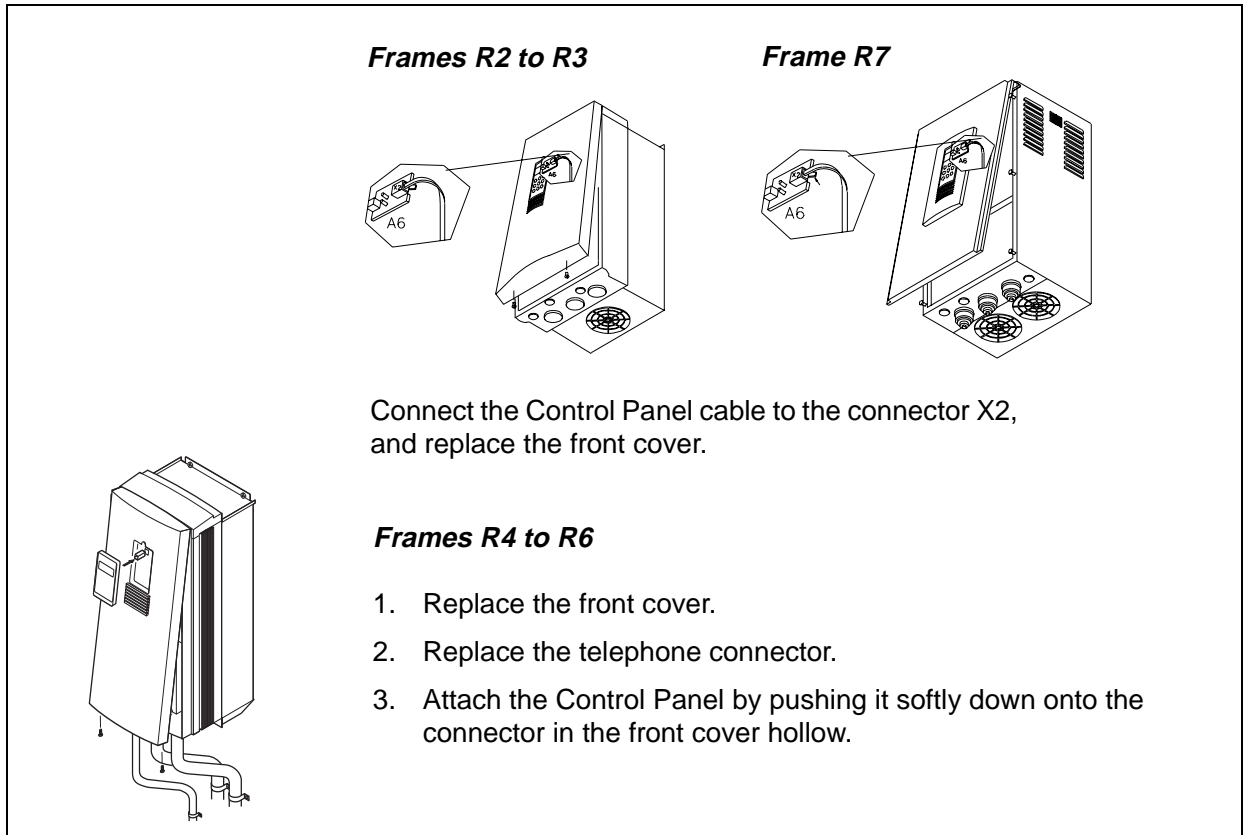
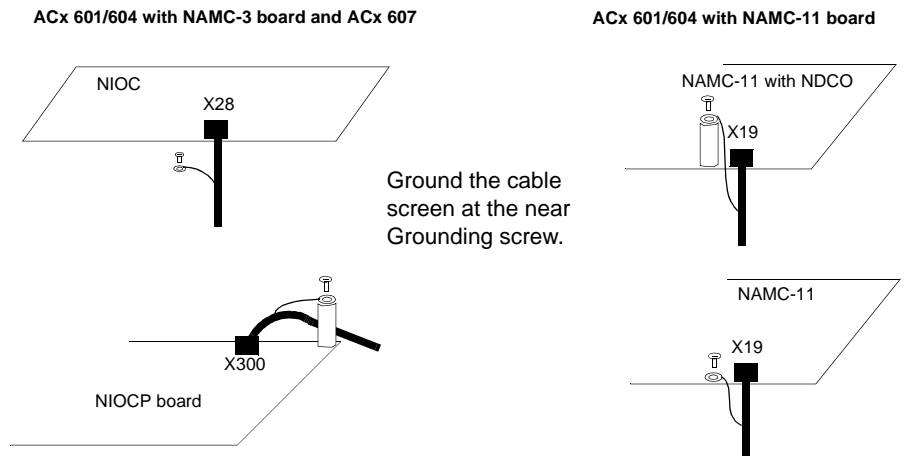


Figure 3-6 Replacing the front cover

**Control Panel in Remote Use**

Connect the Control Panel cable to terminal X19 of the NAMC-11, or with NAMC-03 board to terminal X28 of the NIOC board (X300 of the NIOCP board).



**Pulse Encoder Insulation (ACP 600)**

The pulse encoder shall be insulated electrically from stator or rotor to prevent forming of current path through the pulse encoder. The usual coupling-type encoder must have an electrically insulating coupling. When a hollow-shaft type pulse encoder is used, the insulation can be implemented by insulating the ball joints of the engaging arm, or insulating the bar of the engaging arm. Shield of the encoder cable should be insulated from the encoder frame. See *Appendix B* for grounding of the other end of the encoder cable shield.

**Installation of Optional Modules and DriveWindow**

This section gives general installation instructions for *DriveWindow* PC tool and ACx 600 optional modules, such as fieldbus adapters, I/O extension modules and the pulse encoder interface. Connection examples are given at the end of the section.

*Placement*

The module should be installed inside the unit on the location shown in the dimensional drawings (*Appendix B*). Option modules for the frame sizes R2 and R3 are installed outside the frequency converter. Follow the instructions given in the *Mechanical Installation* chapter of the module manual.

*Power Supply for the Module*

The 24 V d.c. supply for **one** optional module is provided by the NIOC/NIOCP board of the converter (NIOC: terminal X23, NIOCP: terminal X4). The location of the NIOC/NIOCP board is shown in the dimensional drawings (*Appendix B*).

*Fiber Optic Link*

Optional modules are connected via a DDCS fiber optic link to the NAMC board or NDCO board (both mounted on top of the NIOC board). The terminals on the NAMC/NDCO board to which the cables are connected are given in the table below. Channel CH1 is on NAMC-11 board. Channels CH0, CH2 and CH3 are on NDCO board. NAMC-3 board includes channels CH0 to CH3.

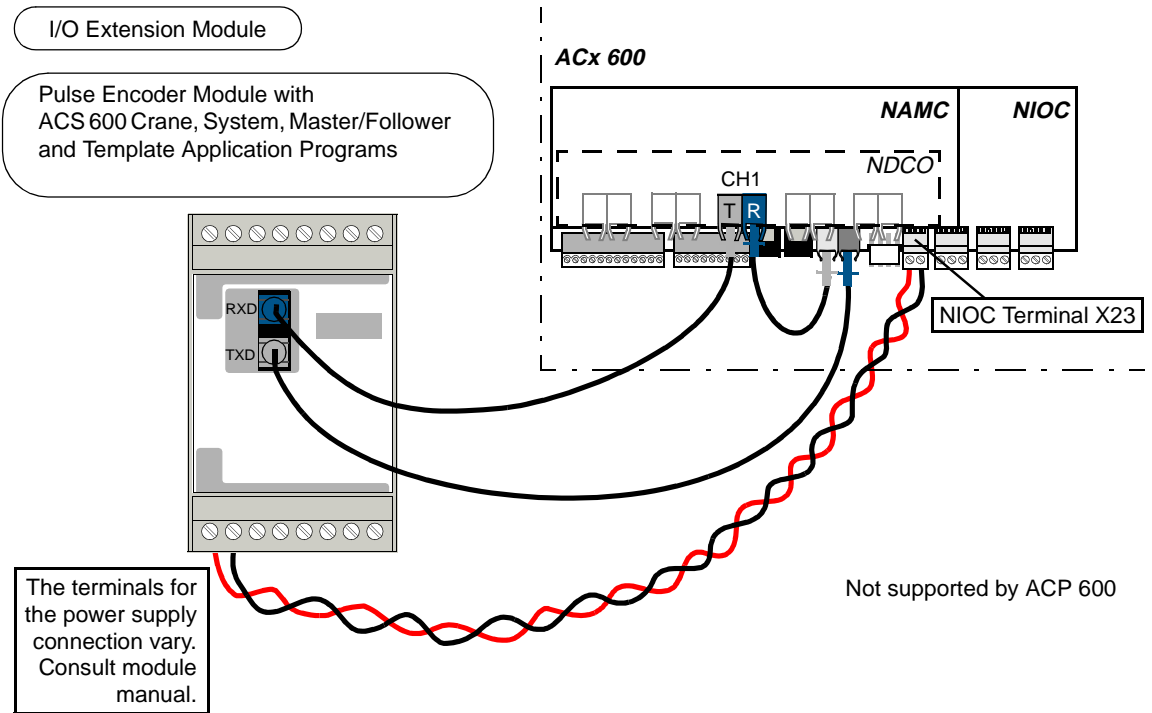
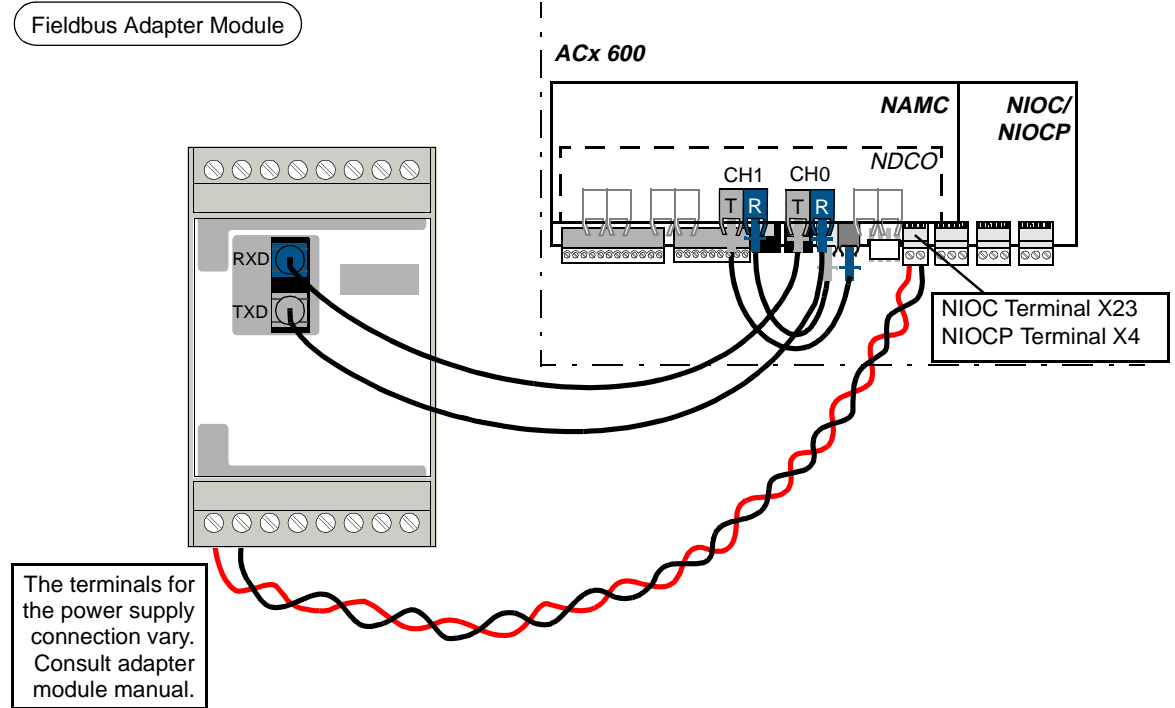
Module Type	Channel	Terminals
Fieldbus Adapter Modules	CH0*	V13*, V14*
I/O Extension Modules	CH1	V15, V16
Pulse Encoder Interface Module	CH2* with ACS 600 Standard Application Program 5.0	V17*, V18*
	CH1 with ACS 600 Crane Application Program 5.x	V15, V16
Double Pulse Encoder Interface Module (for ACP 600 only)	CH2*	V17*, V18*
<i>DriveWindow</i>	CH3*	V19*, V20*

\* on NDCO board when NAMC-11 board is used.

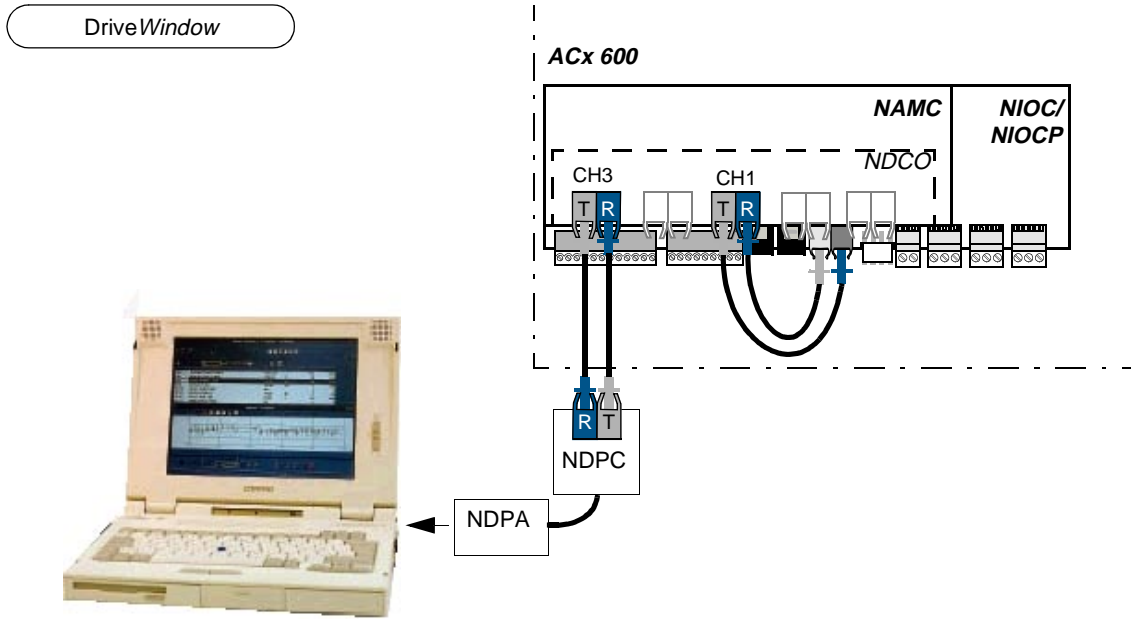
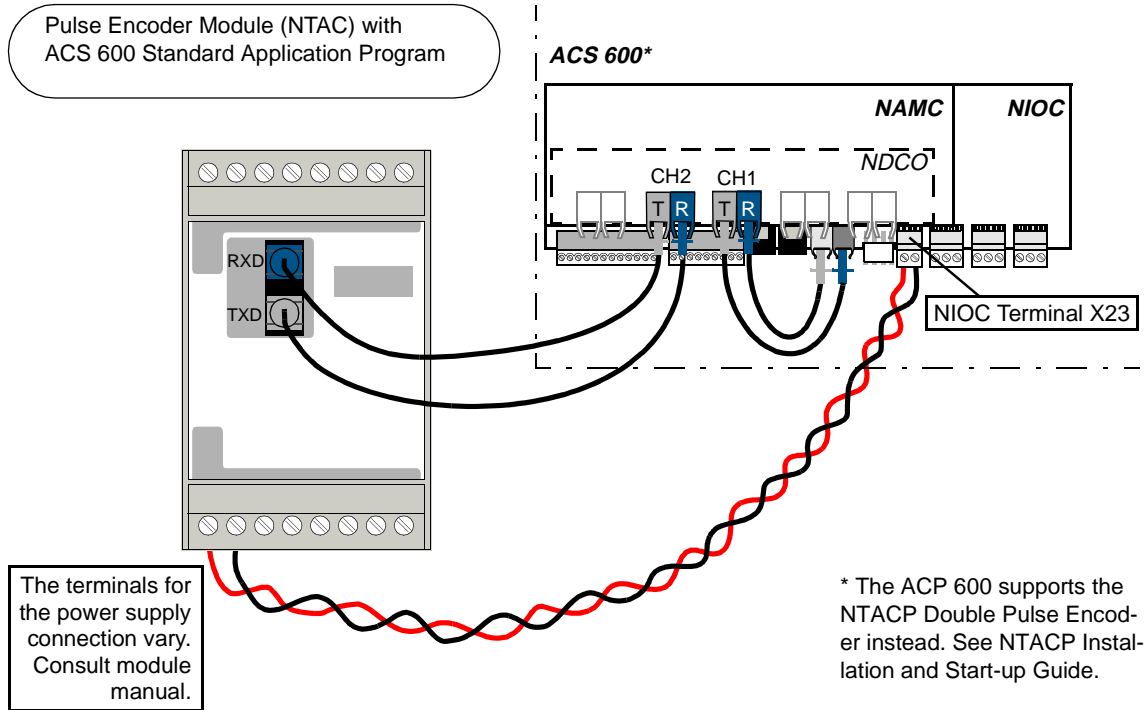
Observe color codes when installing fiber optic cables. Blue connectors should go to blue terminals, and grey connectors to grey terminals.

In case multiple modules are installed on the same channel, they must be connected in a ring.

Connection Examples



Connection Examples



**Braking Chopper**

Refer to the Braking Choppers Installation and Start-Up Guide for braking chopper installation and application information.



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**WARNING!** The brake control terminals (UDC+, UDC-, R+ and R-terminals) carry a dangerous DC voltage (over 500V).

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An external braking resistor must be connected to a terminal block that is supplied with the braking chopper.



## Chapter 4 – Installation Checklist

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### **Installation Checklist**

The ACx 600 mechanical and electrical installation should be checked before start-up. It is advisable to go through the checklist below together with another person. Study carefully the *Safety Instructions* on the first pages of this manual before attempting any work on, or with, the unit.

#### **MECHANICAL INSTALLATION**

- Check that the ambient operating conditions are suitable (see *Appendix A: environmental limits, cooling air flow requirements, free space requirements*).
- Check that the unit is mounted properly on a vertical non-flammable wall (see *Chapter 2 – Mechanical Installation*).
- Check that cooling air flows freely.
- Check the applicability of the motor and the driven equipment (see *Appendix A: Motor Connection*).

#### **ELECTRICAL INSTALLATION** (see *Chapter 3 – Electrical Installation*)

- If the ACx 600 is connected to an ungrounded power system or a high resistance grounded power system (over 30 Ohms), check that the EMC filter capacitors are disconnected.
- Check that the drive is grounded properly.
- Check that the input voltage matches the drive nominal input voltage.
- Check that input power connections at U1, V1 and W1 are OK.
- Check that appropriate input line fuses are installed.
- Check that motor connections at U2, V2 and W2 are OK.
- Check motor cable routing.
- Check that there are no power factor compensation capacitors connected between the drive and the motor.
- Check that control connections inside the drive are OK.
- Check that there are no tools or other foreign objects inside the drive.
- With bypass connection, check that input line voltage cannot be applied to the output of the ACx 600.





The ACx 600 requires minimum maintenance.



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**WARNING!** The *Safety Instructions* on the first pages of this manual must be followed.

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### **Heatsink**

The heatsink fins pick up dust from the cooling air. The ACx 600 can run into overtemperature Warnings and Faults if the heatsink is not cleaned regularly. In a normal environment, the heatsink should be checked and cleaned annually.

The dust should be removed gently with a soft brush if the cleaning is carried out in the same room where the unit is normally operated. Compressed air should not be used for cleaning unless the installation can be taken apart and the cleaning is carried out in another room (or outdoors). Fan rotation should be prevented (in order to prevent bearing wear) when using compressed air for heatsink cleaning.

### **Fan**

The cooling fan lifespan of ACx 601 units is about 60,000 hours. The actual lifespan depends on the AC drive usage and ambient temperature.

Fan failure can be predicted by the increasing noise from fan bearings and the gradual rise in the heatsink temperature in spite of heatsink cleaning. If the drive is operated in a critical part of a process, fan replacement is recommended once these symptoms start appearing. The fan can be withdrawn by removing the bottom of the frame.

Replacement fans are available from ABB. Do not attempt operation with other than ABB specified spare parts.

### **Capacitors**

The ACx 600 intermediate circuit employs several electrolytic capacitors. Their lifespan is approximately 100,000 hours, but dependent on the drive loading and the ambient temperature.

Capacitor life can be prolonged by lowering the ambient temperature. It is not possible to predict capacitor failure.

Capacitor failure is usually followed by an input line fuse failure or a Fault trip. Contact ABB if capacitor failure is suspected. Replacements are available from ABB. Do not attempt operation with other than ABB specified spare parts.

### **Reforming**

For more information on reforming (re-aging) spare part capacitors, contact Technical Support.



# Appendix A – ACS/ACC/ACP 601 Technical Data

## IEC Ratings for IP2/22 Enclosures

Below are the IEC ratings for ACS/ACC/ACP 601 with 50 Hz and 60 Hz supplies. ACx = ACS/ACC/ACP. The 690 V series is not available for ACP 600. Symbols are described following the table.

ACx 601 Type	Normal Use					Heavy-duty Use						Frame Size	
	Duty Cycle 1/10 min		S <sub>N</sub> [kVA]	P <sub>N</sub> [kW]	P <sub>N</sub> [HP]	Duty Cycle 1/10 min		Duty Cycle 1) 2/15 s		S <sub>hd</sub> [kVA]	P <sub>hd</sub> [kW]		P <sub>hd</sub> [HP]
	I <sub>2N</sub> 9/10min [A]	I <sub>2Nmax</sub> 1/10min [A]				I <sub>2hd</sub> 9/10min [A]	I <sub>2hdmax</sub> 1/10min [A]	I <sub>2hd</sub> 13/15s [A]	I <sub>2hdmax</sub> 2/15s [A]				
<b>Three-phase supply voltage 380 V, 400 V or 415 V</b>													
ACx 601-0005-3	7.6	8.4	5	3	3	6.2	9.3	6.2	12.4	4	2.2	3	R2
ACx 601-0006-3	11	12	6	4	5	7.6	11	7.6	15.2	5	3	3	
ACx 601-0009-3	15	17	9	5.5	7.5	11	17	11	22	6	4	5	
ACx 601-0011-3	18	20	11	7.5	10	15	23	15	30	9	5.5	7.5	R3
ACx 601-0016-3	24	26	16	11	15	18	27	18	36	11	7.5	10	
ACx 601-0020-3	32	35	20	15	20	24	36	24	48	16	11	15	R4
ACx 601-0025-3	41	45	25	18.5	25	32	48	32	64	20	15	20	
ACx 601-0030-3	47	52	30	22	30	41	62	41	82	25	18.5	25	R5
ACx 601-0040-3	62	68	40	30	40	47	71	47	94	30	22	30	
ACx 601-0050-3	76	84	50	37	50	62	93	62	124	40	30	40	R6
ACx 601-0060-3	89	98	60	45	60	76	114	76	152	50	37	50	
ACx 601-0070-3	112	123	70	55	75	89	134	89	178	60	45	60	R7
ACx 601-0100-3	147	162	100	75	100	112	168	112	224	70	55	75	
ACx 601-0120-3	178	196	120	90	125	147	221	147	294	100	75	100	
<b>Three-phase supply voltage 380 V, 400 V, 415 V, 440 V, 460 V, 480 V or 500 V</b>													
ACx 601-0006-5	7.6	8.4	6	4	5	6.2	9.3	6.2	12.4	5	3	3	R2
ACx 601-0009-5	11	12	9	5.5	7.5	7.6	11	7.6	15.2	6	4	5	
ACx 601-0011-5	15	17	11	7.5	10	11	17	11	22	9	5.5	7.5	
ACx 601-0016-5	18	20	16	11	10	15	23	15	30	11	7.5	10	R3
ACx 601-0020-5	24	26	20	15	15	18	27	18	36	16	11	10	
ACx 601-0025-5	31	34	25	18.5	20	24	36	24	48	20	15	15	R4
ACx 601-0030-5	41	45	30	22	30	31	47	31	62	25	18.5	20	
ACx 601-0040-5	47	52	40	30	30	41	62	41	82	30	22	30	R5
ACx 601-0050-5	58	64	50	37	40	47	71	47	94	40	30	30	
ACx 601-0060-5	65	72	60	45	50	58	87	58	116	50	37	40	R6
ACx 601-0070-5	84	92	70	55	60	65	98	65	130	60	45	50	
ACx 601-0100-5	112	123	100	75	75	84	126	84	168	70	55	60	R7
ACx 601-0120-5	135	149	120	90	100	112	168	112	224	100	75	75	
ACx 601-0140-5	164	180	140	110	125	135	203	135	270	120	90	100	
<b>Three-phase supply voltage 525 V, 550 V, 575 V, 600 V, 660 V or 690 V</b>													
ACx 601-0009-6	7.6	11	9	5.5	7.5	6.2	9	6.2	9	6	4	5.0	R3
ACx 601-0011-6	11	12	11	7.5	10	7.6	11	7.6	11	9	5.5	7.5	
ACx 601-0016-6	15	17	16	11	15	11	17	11	17	11	7.5	10	
ACx 601-0020-6	20	22	20	15	20	15	23	15	23	16	11	15	R4
ACx 601-0025-6	25	28	25	18.5	25	20	30	20	30	20	15	20	
ACx 601-0030-6	28	31	30	22	30	25	38	25	38	25	18.5	25	R5
ACx 601-0040-6	36	40	40	30	40	28	42	28	42	30	22	30	
ACx 601-0050-6	44	48	50	37	50	36	54	36	54	40	30	40	R6
ACx 601-0060-6	52	57	60	45	60	44	66	44	66	50	37	50	
ACx 601-0070-6	65	72	70	55	75	52	78	52	78	60	45	60	R7
ACx 601-0100-6	88	97	100	75	100	65	98	65	98	70	55	75	
ACx 601-0120-6	105	116	120	90	125	88	132	88	132	100	75	100	

The table continues on the next page

Rating table continued

ACx 601 Type	Pump and Fan Use (Squared Load)				Frame Size
	$I_{2Nsq}$	$S_N$	$P_N$	$P_N$	
	[A]	[kVA]	[kW]	[HP]	
<b>Three-phase supply voltage 380 V, 400 V or 415 V</b>					
ACx 601-0005-3	7.6	5	3	3	R2
ACx 601-0006-3	11	6	4	5	
ACx 601-0009-3	15	9	5.5	7.5	
ACx 601-0011-3	18	11	7.5	10	R3
ACx 601-0016-3	24	16	11	15	
ACx 601-0021-3	41	20	15	20	R4
ACx 601-0026-3	47	25	18.5	25	
ACx 601-0031-3	62	30	22	30	R5
ACx 601-0041-3	76	40	30	40	
ACx 601-0051-3	89	50	37	50	
ACx 601-0061-3	112	60	45	60	R6
ACx 601-0071-3	124	70	55	75	
ACx 601-0101-3	178	100	75	100	R7
ACx 601-0121-3	200	120	90	125	
<b>Three-phase supply voltage 380 V, 400 V, 415 V, 440 V, 460 V, 480 V or 500 V</b>					
ACx 601-0006-5	7.6	6	4	5	R2
ACx 601-0009-5	11	9	5.5	7.5	
ACx 601-0011-5	15	11	7.5	10	
ACx 601-0016-5	18	16	11	10	R3
ACx 601-0020-5	24	20	15	15	
ACx 601-0026-5	41	25	18.5	20	R4
ACx 601-0031-5	47	30	22	30	
ACx 601-0041-5	58	40	30	30	R5
ACx 601-0051-5	65	50	37	40	
ACx 601-0061-5	84	60	45	50	
ACx 601-0071-5	112	70	55	60	R6
ACx 601-0101-5	124	100	75	75	
ACx 601-0121-5	164	120	90	100	R7
ACx 601-0141-5	200	140	110	125	

Current ratings are for drives in IP 20/21 enclosures. For drives in IP 54 enclosures, see page A-4. For output current temperature derating, see page A-3.

The current ratings are the same regardless of the supply voltage within one voltage range. The rated current of the ACx 60x must be higher than or equal to the rated motor current to achieve the rated motor power given in the table.

**Note 1:** The maximum allowed motor shaft power is limited to  $1.5 \cdot P_{hd}$ . If the limit is exceeded, the motor torque and the  $I_{hdmax}$  2 s current is automatically restricted. The function protects the input bridge of the ACS 600 against overload.

**Note 2:** The load capacity (current and power) decreases if the installation site altitude exceeds 1000 meters (3300 ft.), or if the ambient temperature exceeds 40 °C (104 °F/35 °C/95 °F for ACx 601-0120-03 units).

**Note 3:** The Pump and Fan rating is not to be used with dv/dt filters.

Usually dv/dt filters are needed at the output of 525 V to 690 V units with random wound motors. No dv/dt filters are usually required with form wound motors.

**Normal use** (10 % overload capacity):

- $I_{2N}$  rated RMS output current
- $I_{2Nmax}$  short term rms overload current (allowed for one minute every 10 minutes).
- $S_N$  rated apparent output power
- $P_N$  typical motor power. The power ratings in kW apply to most IEC 34 motors. The power ratings in HP apply to most four pole NEMA rated motors.

**Heavy-duty use** (50 % or 100 % overload capacity):

- $I_{2hd}$  rated RMS output current
- $I_{2hdmax}$  rms overload current (allowed for one minute every 10 minutes or 2 seconds every 15 seconds) Maximum current depends on parameter setting, refer to Firmware Manual.
- $S_{hd}$  rated apparent output power
- $P_{hd}$  typical motor power. The power ratings in kW apply to most IEC 34 motors. The power ratings in HP apply to most four pole NEMA rated motors..

**Pump and Fan use** (squared load): no overload capacity

- $I_{2Nsq}$  rated RMS output current
- $S_N$  rated apparent output power
- $P_N$  typical motor power. The power ratings in kW apply to most IEC 34 motors. The power ratings in HP apply to most four pole NEMA rated motors.

Rating table continued

ACx 601 Type	Normal Use			Heavy-duty Use					Frame Type
	Duty Cycle 1/10 min		$P_N$ [HP]	Duty Cycle 1/10 min		Duty Cycle <sup>1)</sup> 2/15 s		$P_{hd}$ [HP]	
	$I_{2N}$ 9/10min [A]	$I_{2Nmax}$ 1/10min [A]		$I_{2hd}$ 9/10min [A]	$I_{2hdmax}$ 1/10min [A]	$I_{2hd}$ 13/15s [A]	$I_{2hdmax}$ 2/15s [A]		
<b>Three-phase supply voltage 380 V, 400 V, 415 V, 440 V, 460 V, 480 V or 500 V</b>									
ACx 601-0006-4	7.6	8.4	5	6.2	9.3	6.2	12.4	3	R2
ACx 601-0009-4	11	12	7.5	7.6	11	7.6	15.2	5	
ACx 601-0011-4	15	17	10	11	17	11	22	7.5	R3
ACx 601-0016-4	21	23	15	15	23	15	30	10	
ACx 601-0020-4	27	30	20	19	27	19	36	10	R4
ACx 601-0025-4	34	37	25	24	36	24	48	15	
ACx 601-0030-4	41	45	30	31	47	31	62	20	R5
ACx 601-0040-4	52	57	40	41	62	41	82	30	
ACx 601-0050-4	65	72	50	47	71	47	94	30	R6
ACx 601-0060-4	77	85	60	58	87	58	116	40	
ACx 601-0070-4	96	106	75	68	98	68	130	50	R7
ACx 601-0100-4	124	136	100	86	126	86	168	60	
ACx 601-0120-4	156	172	125	113	168	113	224	75	R7
ACx 601-0140-4	180	198	150	141	203	141	270	100	

**Note:** The US manufactured units are labeled as -4 types. The information in this manual concerning the corresponding -5 types applies to them.

**Output Current  
Temperature Derating**

The output current is calculated by multiplying the current given in the rating table by the derating factor.

Temperature derating factor for degree of protection IP 21/22:

- *General rule:* Above +40 °C (104 °F), the rated output current is decreased 3.5 % for every additional 1 °C up to +50 °C (1.94% for every additional 1 °F up to 122 °F).
- *Example 1.* If the ambient temperature is 50 °C the derating factor is  $100\% - 3.5\% \cdot 10\text{ °C} = 65\%$  or 0.65. The output current is then  $0.65 \cdot I_{2N}$  or  $I_{2hd}^{\text{°C}}$ .

Derating factor for ACx 600 in Pump and Fan Use ( $I_{Nsq}$  rating):

- Above +40 °C (104 °F) (+35 °C/95 °F for ACx 601-120-03 units), the rated output current is decreased 5 % for every additional 1 °C up to +50 °C (2.78% for every additional 1 °F up to 122 °F).

Derating factor for ACx 601 with degree of protection IP 54:

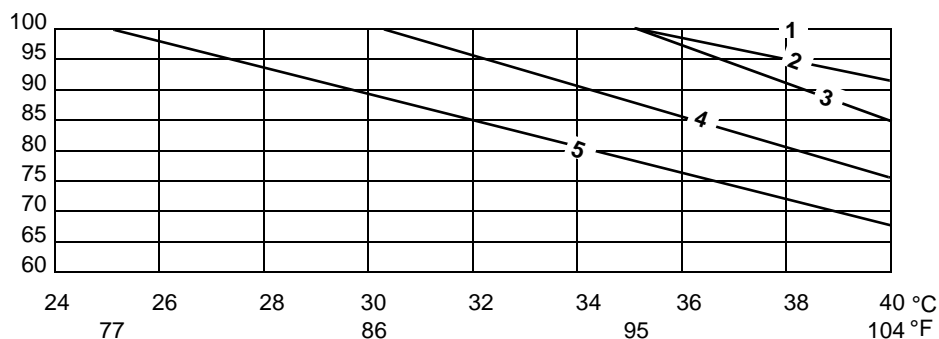
- From +25 °C (77°F) to +40 °C (104 °F), the output current is calculated using the table below.
- Above +40 °C (104 °F), the output current is decreased 3.5 % for every additional 1 °C up to +50 °C (1.94% for every additional 1 °F up to 122 °F).
- *Example 1.* If the ambient temperature is 38 °C, the derating factor for ACx 601-0006-3 is 95 % or 0.95 (Curve 2). The output current is then  $0.95 \cdot I_{2N}$  or  $I_{2hd}$ .

- *Example 2.* If the ambient temperature is 122 °F, the output current for ACx 601-0006-3 is first calculated at 104 °F (derating factor 92 % or 0.92 from Curve 2) and the result is multiplied by factor 0.65 (See *Example 1* (IP 21/22)). The output current is then  $0.92 \cdot 0.65 \cdot I_{2N}$  or  $0.92 \cdot 0.65 \cdot I_{2hd}$ .

**Output Current Ratings for IP54 Enclosures**

Output current for ACS/ACC/ACP 601 with degree of protection IP 54 and with ambient temperature from 25 °C to 40 °C is presented in the diagram below.  $I_{2N}$  total rms output current for normal use,  $I_{2hd}$  total rms output current for heavy-duty use,  $t$  ambient temperature.

% of  $I_{2N}$  and  $I_{2hd}$



Curve 1 (100 % no derating)	Curve 2	Curve 3	Curve 4	Curve 5
ACx 601-0005-3	ACx 601-0006-3	ACx 601-0011-3	ACx 601-0009-3	ACx 601-0016-3
ACx 601-0006-5	ACx 601-0009-5	ACx 601-0020-3	ACx 601-0040-3	ACx 601-0070-3
ACx 601-0009-6	ACx 601-0025-5	ACx 601-0025-3	ACx 601-0050-3	ACx 601-0020-5
ACx 601-0011-6	ACx 601-0070-5	ACx 601-0030-3	ACx 601-0011-5	ACx 601-0100-5
ACx 601-0100-6	ACx 601-0016-6	ACx 601-0060-3	ACx 601-0050-5	ACx 601-0070-6
ACx 601-0120-6		ACx 601-0016-5	ACx 601-0060-5	
		ACx 601-0030-5	ACx 601-0040-6	
		ACx 601-0040-5	ACx 601-0050-6	
		ACx 601-0020-6		
		ACx 601-0025-6		
		ACx 601-0030-6		
		ACx 601-0060-6		

**Fuses**

Recommended input fuse ratings of the ACS/ACC/ACP 601 are below. A minimum rated current in amperes, A<sup>2</sup>s maximum I<sup>2</sup>t value, V rated voltage in volts. Only ultra rapid fuses guarantee proper protection for the rectifier semiconductors.

ACx 601 Type	Fuses							
	A	A <sup>2</sup> s	V	Manufacturer	Type DIN 43620	Size	Type DIN 43653	Size
ACx 601-0005-3 ACx 601-0006-4 ACx 601-0006-5	16	48	660	Bussmann	170M1559	000	170M1359	000/80
ACx 601-0006-3 ACx 601-0009-4 ACx 601-0009-5	16	48	660	Bussmann	170M1559	000	170M1359	000/80
ACx 601-0009-3 ACx 601-0011-4 ACx 601-0011-5	25	130	660	Bussmann	170M1561	000	170M1361	000/80
ACx 601-0011-3 ACx 601-0016-4 ACx 601-0016-5	32	270	660	Bussmann	170M1562	000	170M1362	000/80
ACx 601-0016-3 ACx 601-0020-4 ACx 601-0020-5	40	460	660	Bussmann	170M1563	000	170M1363	000/80
ACx 601-0020-3 ACx 601-0025-4 ACx 601-0025-5	50	770	660	Bussmann	170M1564	000	170M1364	000/80
ACx 601-0025-3 ACx 601-0030-4 ACx 601-0030-5	63	1450	660	Bussmann	170M1565	000	170M1365	000/80
ACx 601-0030-3 ACx 601-0040-3 ACx 601-0040-4 ACx 601-0040-5 ACx 601-0050-5	80	1250	660	Bussmann	170M3811	1	170M3011	1/80
ACx 601-0050-3 ACx 601-0050-4 ACx 601-0060-5	125	3700	660	Bussmann	170M3813	1	170M3013	1/80
ACx 601-0060-3 ACx 601-0070-5	160	7500	660	Bussmann	170M3814	1	170M3014	1/80
ACx 601-0060-4 ACx 601-0070-3 ACx 601-0070-4 ACx 601-0100-4 ACx 601-0100-5	200	28000	660	Bussmann	170M1570	000	170M1370	000/80
ACx 601-0100-3 ACx 601-0120-3 ACx 601-0120-4 ACx 601-0120-5 ACx 601-0140-4 ACx 601-0140-5	400	105000	660	Bussmann	170M3819	1	170M3019	1/80
ACx 601-0009-6	16	48	660	Bussmann	170M1559	000	170M1359	000/80
ACx 601-0011-6	16	48	660	Bussmann	170M1559	000	170M1359	000/80
ACx 601-0016-6	16	48	660	Bussmann	170M1559	000	170M1359	000/80
ACx 601-0020-6	25	130	660	Bussmann	170M1561	000	170M1361	000/80
ACx 601-0025-6	40	460	660	Bussmann	170M1563	000	170M1363	000/80
ACx 601-0030-6	50	770	660	Bussmann	170M1564	000	170M1364	000/80

ACx 601 Type	Fuses							
	A	A <sup>2</sup> s	V	Manufacturer	Type DIN 43620	Size	Type DIN 43653	Size
ACx 601-0040-6	50	770	660	Bussmann	170M1564	000	170M1364	000/80
ACx 601-0050-6	63	1450	660	Bussmann	170M1565	000	170M1365	000/80
ACx 601-0060-6	100	4650	660	Bussmann	170M1567	000	170M1367	000/80
ACx 601-0070-6	100	4650	660	Bussmann	170M1567	000	170M1367	000/80
ACx 601-0100-6	125	8500	660	Bussmann	170M1568	000	170M1368	000/80
ACx 601-0120-6	200	28000	660	Bussmann	170M1570	000	170M1370	000/80

**Note:** Fuses from other manufacturers can be used if they meet the ratings given in the table. Only ultra rapid fuses guarantee the proper protection for the rectifier semiconductors. The fuses recommended in the table are UL recognized.

**Example** For ACS 601-0120-3, the recommended fuses for the input bridge protection are 400 A ultrarapid fuses.

The values  $I_{1N}$  and  $I_{1hg}$  for ACS 601-0120-3 are 175 A and 145 A respectively.  $1.1 \cdot 175 \text{ A} = 192.5 \text{ A}$  and  $1.5 \cdot 145 \text{ A} = 217 \text{ A}$ . Normal fuses with nominal currents higher than 192.5 A or 217 A can be used to protect the input cable; thus, 200 A or 250 A fuses are selected depending on the use (normal or heavy-duty, respectively).

**Cable Entries**

Power and motor cable terminal sizes and tightening torques for the ACS/ACC/ACP 601 with cable diameters accepted by the rubber glands are given below. All power wiring must be rated for 60 °C minimum.

ACx 600 Type	U1,V1,W1 / U2,V2,W2			Ground (PE)	
	Maximum Wire Size	Cable Ø mm 2)	Tightening Torque	Maximum Wire Size	Cable Ø mm
ACx 601-0005-3/0006-5	6mm <sup>2</sup> #10 AWG	14...20	1.5...1.8 Nm 13-18 lb.-in.	6mm <sup>2</sup> #10 AWG	10...14
ACx 601-0006-3/0009-5		14...20			10...14
ACx 601-0009-3/0011-5		14...20			10...14
ACx 601-0009-6/0011-6	10mm <sup>2</sup> #8 AWG	14...20		10mm <sup>2</sup> #8 AWG	10...14
ACx 601-0011-3/0016-5/0016-6		14...20			10...14
ACx 601-0016-3/0020-5/0020-6		14...20			10...14
ACx 601-0020-3/0025-5/0025-6	16mm <sup>2</sup> #6 AWG	14...20	16mm <sup>2</sup> #6 AWG	10...14	
ACx 601-0025-3/0030-5/0030-6		14...20		10...14	
ACx 601-0030-3/0040-5/0040-6	Cu 35mm <sup>2</sup> #2 AWG Al 50mm <sup>2</sup> #1 AWG	20...26	8Nm 5.9 lb.-ft.	35mm <sup>2</sup> #2 AWG	10...14
ACx 601-0040-3/0050-5/0050-6		20...26			10...14
ACx 601-0050-3/0060-5		20...26			10...14
ACx 601-0060-3/0070-5/0060-6	70mm <sup>2</sup> #00 AWG	26...35			10...14
ACx 601-0070-3/0100-5/0070-6		26...35			10...14
ACx 601-0100-3/0120-5/0100-6	1)		30 Nm 22 lb.-ft.	70mm <sup>2</sup> #00 AWG	
ACx 601-0120-3/0140-5/0120-6					

1)The terminals are 10mm (13/32") bolts for attaching ring lugs (lugs not furnished).

2)IEC version. Range of cable diameters accepted by gland plate holes. For USA version conduit plate drawings, see pages B-9 and B-10.



### External Control Connections (NIOC)

External control connections of ACS 600 with standard application software (Factory Macro) are below. External control connections are different with other application macros and softwares (see *Firmware Manual*).

#### Terminal Block Size

X21, X22, X23, X25, X26, X27: cables 0.5 to 1.5 mm<sup>2</sup> (#20 to #16 AWG)

X2: cables 0.5 to 2.5 mm<sup>2</sup> (#20 to #14 AWG)

#### Control Cable Lead-through Size:

Ø: 2 x 3x2...11 mm (IEC units)

Factory settings of application software selection B (type code):

DI1: Start, DI2: Stop, DI3: Reverse, DI4: Acc/Dec 2, DI5,6: Constant speed 1 to 3 select.

1) Parameter 10.3 must be set to REQUEST.

2) Operation: 0 = Open, 1 = Closed

DI 5	DI 6	Output
0	0	Set speed through AI1
1	0	Constant Speed 1
0	1	Constant Speed 2
1	1	Constant Speed 3

Connector X28 for RS 485 connection

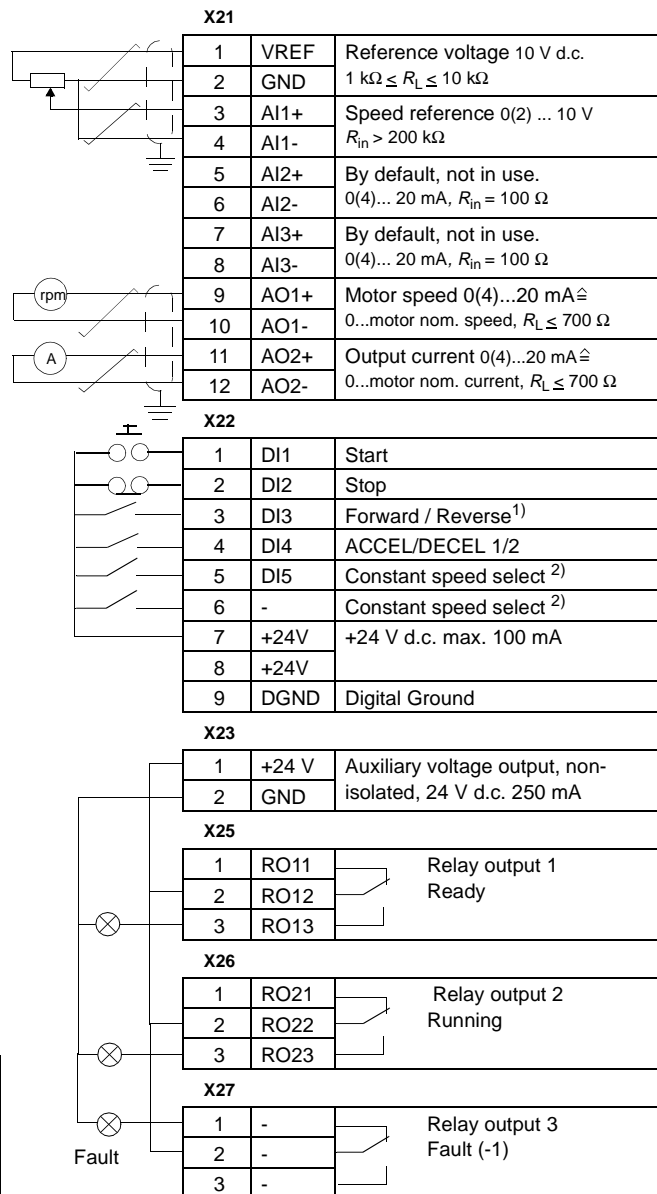
1	TRANS	Link Connections
2	GND	
3	B-	
4	A+	
5	GND	Power to link
6	+24 V	

Connector X29 for RS 485 connection

1	TRANS	Link Connections
2	FAULT	
3	B-	
4	A+	
5	GND	Power to link
6	+24 V	

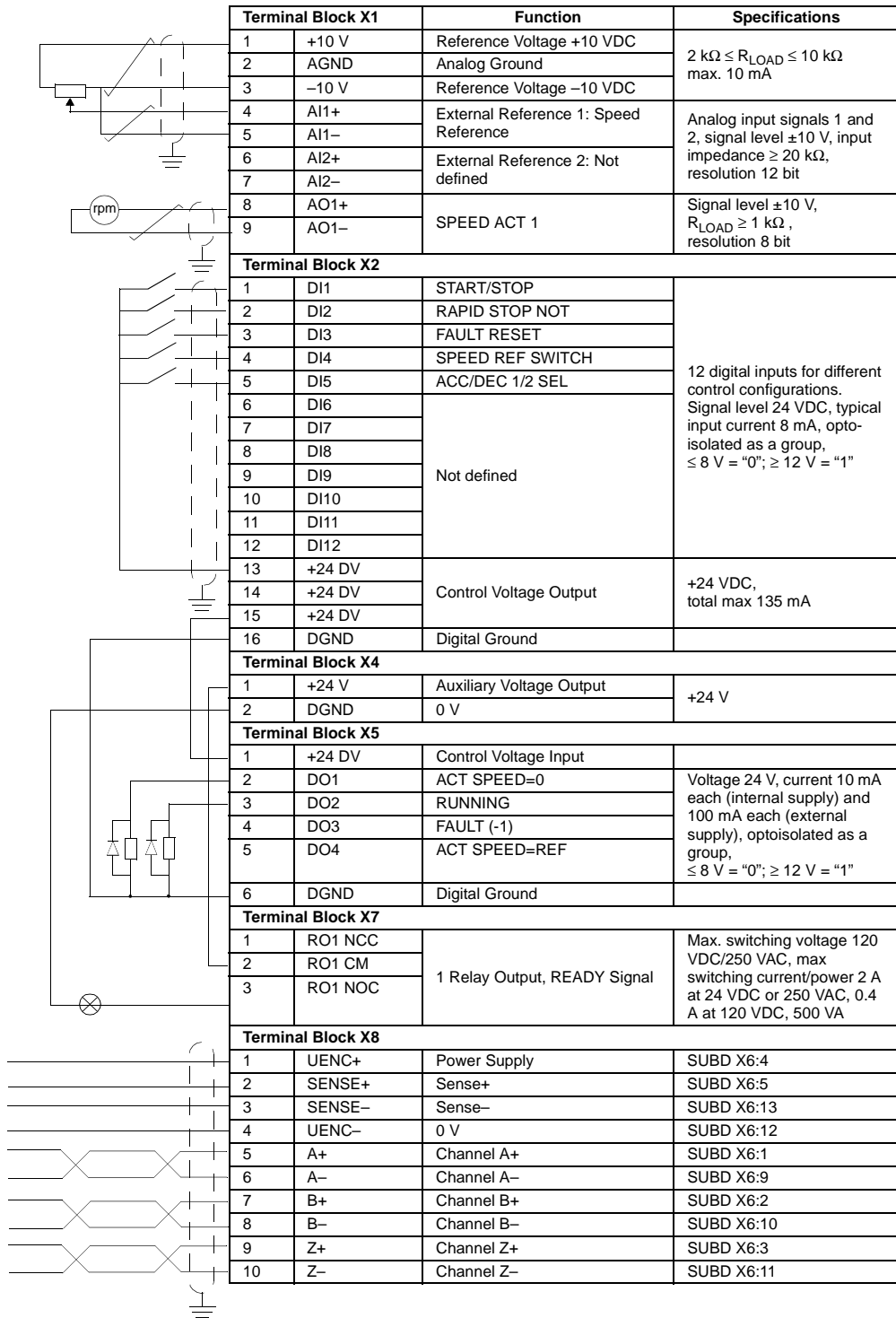
ACS 601/604/607  
NIOC Board  
(A2)

#### Programmable I/O Factory Settings



**External Control Connections (NIOCP)**

External control connections of ACP 600 with NIOCP board are below.



Terminal Block X1		Function	Specifications
1	+10 V	Reference Voltage +10 VDC	2 kΩ ≤ R <sub>LOAD</sub> ≤ 10 kΩ max. 10 mA
2	AGND	Analog Ground	
3	-10 V	Reference Voltage -10 VDC	
4	AI1+	External Reference 1: Speed Reference	Analog input signals 1 and 2, signal level ±10 V, input impedance ≥ 20 kΩ, resolution 12 bit
5	AI1-		
6	AI2+	External Reference 2: Not defined	
7	AI2-		
8	AO1+	SPEED ACT 1	Signal level ±10 V, R <sub>LOAD</sub> ≥ 1 kΩ, resolution 8 bit
9	AO1-		
Terminal Block X2			
1	DI1	START/STOP	12 digital inputs for different control configurations. Signal level 24 VDC, typical input current 8 mA, opto-isolated as a group, ≤ 8 V = "0"; ≥ 12 V = "1"
2	DI2	RAPID STOP NOT	
3	DI3	FAULT RESET	
4	DI4	SPEED REF SWITCH	
5	DI5	ACC/DEC 1/2 SEL	
6	DI6	Not defined	
7	DI7		
8	DI8		
9	DI9		
10	DI10		
11	DI11		
12	DI12		
13	+24 DV	Control Voltage Output	+24 VDC, total max 135 mA
14	+24 DV		
15	+24 DV		
16	DGND	Digital Ground	
Terminal Block X4			
1	+24 V	Auxiliary Voltage Output	+24 V
2	DGND	0 V	
Terminal Block X5			
1	+24 DV	Control Voltage Input	Voltage 24 V, current 10 mA each (internal supply) and 100 mA each (external supply), optoisolated as a group, ≤ 8 V = "0"; ≥ 12 V = "1"
2	DO1	ACT SPEED=0	
3	DO2	RUNNING	
4	DO3	FAULT (-1)	
5	DO4	ACT SPEED=REF	
6	DGND	Digital Ground	
Terminal Block X7			
1	RO1 NCC	1 Relay Output, READY Signal	Max. switching voltage 120 VDC/250 VAC, max switching current/power 2 A at 24 VDC or 250 VAC, 0.4 A at 120 VDC, 500 VA
2	RO1 CM		
3	RO1 NOC		
Terminal Block X8			
1	UENC+	Power Supply	SUBD X6:4
2	SENSE+	Sense+	SUBD X6:5
3	SENSE-	Sense-	SUBD X6:13
4	UENC-	0 V	SUBD X6:12
5	A+	Channel A+	SUBD X6:1
6	A-	Channel A-	SUBD X6:9
7	B+	Channel B+	SUBD X6:2
8	B-	Channel B-	SUBD X6:10
9	Z+	Channel Z+	SUBD X6:3
10	Z-	Channel Z-	SUBD X6:11

**Enclosures, Space Requirements**

The cabinets, degrees of protection and free space requirements of ACx 600 types are given below.

ACx 600 Type	Enclosure	Degree of Protection <sup>2)</sup>	Space above	Space below	Space on left/right	Space in front/back
601	wall-mounted metal frame	IP 22 /IP 54 <sup>1)</sup>	12in / 300mm	12in / 300mm	2/2in 50/50mm	0.8/0in 20/0mm

1) not for ACP 601 units

2) The degrees of protection is specified by listing the IEC standard IP (Ingress Protection) number. The first digit of the IP number specifies the protection against solid objects and dirt. The second digit specifies the protection against liquids. IP 00 is an open chassis. NEMA 1 enclosures are comparable to approximately IP 20 and IP 33. NEMA 3R enclosures are comparable to IP 32. NEMA 12 and NEMA 13 enclosures are comparable to IP 54 to IP 65. NEMA 4 enclosures are comparable to IP 65 or 66.

	First digit of IP number (protection against solid objects)	Second digit of IP number (protection against liquids)
0	Not protected	Not protected
1	Protected against solid objects larger than 50 mm (2 in.) dia.	Protected against dripping water
2	Protected against solid objects larger than 12 mm (1/2 in.) dia.	Protected against downward sprays of water up to 15 degrees from vertical.
3	Protected against solid objects larger than 2.5 mm (0.1 in.) dia.	Protected against downward sprays of water up to 60 degrees from vertical.
4	Protected against solid objects larger than 1.0 mm (0.04 in.) dia.	Protected against light sprays or splashing water from all directions - water shall not enter the enclosure in harmful quantities.
5	Dust protected - dust shall not enter the enclosure in sufficient quantity to interfere with satisfactory operation of equipment.	Protected against low pressure sprays of water from all directions - water shall not enter the enclosure in harmful quantities.
6	Dust tight	Protected against heavy seas on shipdecks or strong sprays of water from all directions - water shall not enter the enclosure in harmful quantities.

**Heat Dissipation Requirements**

ACx 601 drives are self-cooled. The table below gives the heat dissipated into the hot air exhausted from the drives. If the drives are installed in a confined space, the heat must be removed from the area by ventilation or air conditioning equipment.

ACx 601 Type	Heat Dissipation	
	Watts	BTU/Hr
ACx 601-0005	150	512
ACx 601-0006	180	615
ACx 601-0009	270	922
ACx 601-0011	330	1130
ACx 601-0016	480	1640
ACx 601-0020	600	2050
ACx 601-0025	750	2560
ACx 601-0030	900	3070
ACx 601-0040	1200	4100
ACx 601-0050	1500	5120
ACx 601-0060	1800	6150
ACx 601-0070	2100	7170
ACx 601-0100	3000	10200
ACx 601-0120	3600	12300
ACx 601-0140	4200	14300

**Cooling Air Flow Requirements**

Cooling air flow requirements are given below.

<b>ACx 601</b>	<b>Flow m<sup>3</sup>/h</b>	<b>Flow ft<sup>3</sup>/h</b>
ACx 601-0005-3/0006-5	40	25
ACx 601-0006-3/0009-5	40	25
ACx 601-0009-3/0011-5	40	25
ACx 601-0011-3/0016-5/0009-6/0011-6	60	35
ACx 601-0016-3/0020-5/0016-6/0020-6	60	35
ACx 601-0020-3/0025-5/0025-6	70	40
ACx 601-0025-3/0030-5/0030-6	100	60
ACx 601-0030-3/0040-5/0040-6	260	155
ACx 601-0040-3/0050-5/0050-6	260	155
ACx 601-0050-3/0060-5	260	155
ACx 601-0060-3/0070-5/0060-6	280	165
ACx 601-0070-3/0100-5/0070-6	280	165
ACx 601-0100-3/0120-5/0100-6	660	390
ACx 601-0120-3/0140-5/0120-6	660	390

**Cooling Air Duct** Heat dissipations and cooling air flows of ACx 601 in a cooling air duct installation are below.

<b>Degree of protection</b>	<b>Heat Dissipation</b>		<b>Degree of protection</b>	<b>Cooling Air Flow Out</b>	
	<b>Heatsink</b>	<b>Front Section</b>		<b>Heatsink</b>	<b>Front Section</b>
IP 22	85 % of ACx 600 losses	15 % of ACx 600 losses	IP 22	80 % of air flow	20 % of air flow
IP 54	90 % of ACx 600 losses	10 % of ACx 600 losses	IP 54	100 % of air flow	0 % of air flow

## Dimensions and Weights

Dimensions and weights of the wall-mounted ACS/ACC/ACP 601 units are given below.



ACS 601 Type			Height mm/in	Width mm/in	Depth mm/in	Weight kg/lb
0005-3	0006-5		420/16.5	220/8.7	292/11.5	14/31
0006-3	0009-5		420/16.5	220/8.7	292/11.5	14/31
0009-3	0011-5		420/16.5	220/8.7	292/11.5	14/31
0011-3	0016-5	0009-6/0011-6	420/16.5	260/10.2	298/11.7	17.5/39
0016-3	0020-5	0016-6/0020-6	420/16.5	260/10.2	298/11.7	17.5/39
0020-3	0025-5	0025-6	526/20.7	306/12.0	310/12.2	25/55
0025-3	0030-5	0030-6	526/20.7	306/12.0	310/12.2	25/55
0030-3	0040-5	0040-6	715/27.8	306/12.0	360/14.2	35/77
0040-3	0050-5	0050-6	715/27.8	306/12.0	360/14.2	35/77
0050-3	0060-5		715/27.8	306/12.0	360/14.2	35/77
0060-3	0070-5	0060-6	715/27.8	306/12.0	432/17.0	50/110
0070-3	0100-5	0070-6	715	306/12.0	432/17.0	50/110
0100-3	0120-5	0100-6	860/33.9	480/18.9	428/16.9	88/194
0120-3	0140-5	0120-6	860/33.9	480/18.9	428/16.9	88/194

### Input Power Connection

#### Voltage ( $U_1$ ):

380/400/415 VAC 3-phase  $\pm 10\%$  for 400 VAC units  
 380/400/415/440/460/480/500 VAC 3-phase  $\pm 10\%$  for 500 VAC units  
 525/550/575/600/660 VAC 3-phase  $\pm 10\%$  for 690 VAC units  
 690 VAC 3-phase  $\pm 5\%$  for ACx 607 units

**Short Circuit Capability:** The rated short time withstand current of ACx 600 is 50 kA 1s.

**Frequency:** 48 to 63 Hz, maximum rate of change 17 %/s

**Imbalance:** Max.  $\pm 3\%$  of nominal phase to phase input voltage

**Fundamental Power Factor ( $\cos \phi_1$ ):** 0.97 (at nominal load)

### Motor Connection

**Voltage ( $U_2$ ):** 0 to  $U_1$ , 3-phase symmetrical

**Frequency:** DTC mode: 0 to  $3.2 \cdot f_{FWP}$ . Maximum frequency 300 Hz.

$$f_{FWP} = \frac{U_{Nmains}}{U_{Nmotor}} \cdot f_{Nmotor}$$

$f_{FWP}$ : Frequency at field weakening point;  $U_{Nmains}$ : Mains voltage;

$U_{Nmotor}$ : Rated motor voltage;  $f_{Nmotor}$ : Rated motor frequency

Scalar Control mode (not for ACP 600): 0 to 300 Hz  
With du/dt Filter (DTC and Scalar Control modes): 0 to 120 Hz

**Frequency Resolution:** 0.01 Hz

**Continuous Current:**  $1.0 \cdot I_{2N}$  (normal use)  
 $1.0 \cdot I_{2hd}$  (heavy-duty use)

**Short Term Overload Capacity (1 min/10 min):**  $I_{2Nmax} = 1.1 \cdot I_{2N}$   
 $I_{2hdmax} = 1.5 \cdot I_{2hd}$

**Peak Overload Capacity (2 s/15 s):**

$1.5 \cdot I_{2N}$  (400 and 500 VAC units)  
 $2.0 \cdot I_{2hd}$  (400 and 500 VAC units)  
 $1.5 \cdot I_{2hd}$  (690 VAC units)

$1.0 \cdot I_{NSQ}$

**Power Limit:**  $1.5 \cdot P_{hd}$

**Overcurrent Trip:**  $3.5 \cdot I_{2hd}$

**Field Weakening Point:** 8 to 300 Hz

**Switching Frequency:** 3 kHz (average). In 690 V units 2 kHz (average).

**Maximum Recommended Motor Cable Length:** 300 m (980 ft.). This is the cumulative length in case of parallel connected motors. For ACx 601-0005-3 to ACx 601-0016-3, ACx 601-0006-5 to ACx 601-0020-5, ACx 601-0009-6 to ACx 601-0020-6, if the motor cable length exceeds 70 meters (230 ft.), an ABB representative should be consulted.

**Bearings of motors larger than 90 kW (125 Hp):** Insulated bearing at non-driven end is recommended.

**Efficiency and Cooling** **Efficiency:** Approximately 98 % at nominal power level

**Cooling Method:** Internal fan, flow direction from the bottom to the top

**Ambient Conditions**

ACx 600 AC drives are to be used in a heated, indoor controlled environment as specified below.

ACS/ACC/ACP 600	Operation installed for stationary use	Storage in the protective package	Transportation in the protective package
<b>Installation Site Altitude</b>	Nominal output power at 0 to 1000 m (3300') above sea level. <sup>1)</sup>	-	-
<b>Air Temperature</b>	0 to +40 °C (32 to 104 °F) <sup>2)</sup> (IP 21/22 and ACx 607 with IP 54) 0 to +25 °C (32 to 77 °F) <sup>2)</sup> (ACx 601 with IP 54)	-40 to +70 °C -40 to +158 °F	-40 to +70 °C -40 to +158 °F
<b>Relative Humidity</b>	5 to 95 %	Max. 95 %	Max. 95 %
	No condensation allowed. Maximum allowed relative humidity is 60 % in the presence of corrosive gases.		
<b>Contamination Levels</b> (IEC 721-3-3)	No conductive dust allowed.		
	<b>Boards without coating:</b> Chemical gases: Class 3C2 Solid particles: Class 3S2  <b>Boards with coating:</b> Chemical gases: Class 3C3 Solid particles: Class 3S2	<b>Boards without coating:</b> Chemical gases: Class 1C2 Solid particles: Class 1S3  <b>Boards with coating:</b> Chemical gases: Class 1C2 Solid particles: Class 1S3	<b>Boards without coating:</b> Chemical gases: Class 2C2 Solid particles: Class 2S2  <b>Boards with coating:</b> Chemical gases: Class 2C2 Solid particles: Class 2S2
<b>Atmospheric Pressure</b>	70 to 106 kPa 0.7 to 1.05 atmospheres	70 to 106 kPa 0.7 to 1.05 atmospheres	60 to 106 kPa 0.6 to 1.05 atmospheres
<b>Vibration</b> (IEC 68-2-6)	Max. 0.3 mm (0.01 in) (2 to 9 Hz), max. 1 m/s <sup>2</sup> (3.3 ft/s <sup>2</sup> )(9 to 200 Hz) sinusoidal	Max. 1.5 mm (0.06 in) (2 to 9 Hz), max. 5 m/s <sup>2</sup> (16.4 ft/s <sup>2</sup> ) (9 to 200 Hz) sinusoidal	Max. 3.5 mm (0.14 in) (2 to 9 Hz), max. 15 m/s <sup>2</sup> 49.2 ft/s <sup>2</sup> ) (9 to 200 Hz) sinusoidal
<b>Shock</b> (IEC 68-2-29)	Not allowed	Max. 100 m/s <sup>2</sup> , 11 ms (330 ft/s <sup>2</sup> )	Max. 100 m/s <sup>2</sup> , 11 ms (330 ft/s <sup>2</sup> )
<b>Free Fall</b>	Not allowed	250 mm (10in) (weight under 100 kg) (220 lbs) 100 mm (4 in)(weight over 100 kg) (220 lbs)	250 mm (10in) (weight under 100 kg) (220 lbs) 100 mm (4 in)(weight over 100 kg) (220 lbs)

<sup>1)</sup> At sites over 1000 m (3300 ft) above sea level, the maximum output current is derated 1 % for every additional 100 m (330 ft). If the installation site is higher than 2000 m (6600 ft) above sea level, please contact your local ABB distributor or office for further information.

<sup>2)</sup> See subsection *Output Current Temperature Derating*, page A-3.

**External Control Connections**

Data of the external control connection boards of the ACS 600 product family are given below.

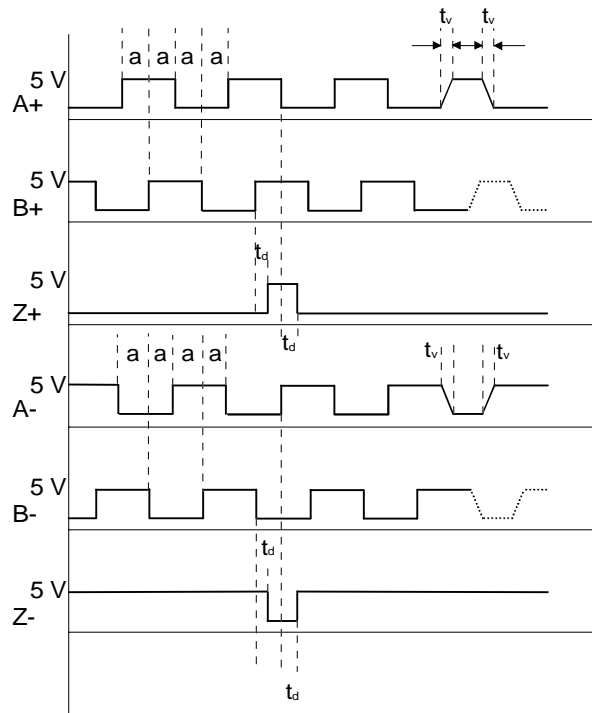
	<b>ACS/ACC/ACP 600 NIOC-01 Board</b>	<b>ACP 600 NIOCP-01 Board</b>
<p><b>Analog Inputs</b></p> <p>The advantage of the differential analog input is that the ground potential of the device or transmitter sending an analog signal can differ up to ± 15 V from the ground potential of the ACx 600 chassis without disturbing the signal. Differential input also efficiently attenuates common mode disturbances coupled to control cables.</p>	<p><b>ACS 600: Two Programmable Differential Current Inputs:</b> 0 (4) to 20 mA, <math>R_{in} = 100 \Omega</math></p> <p><b>ACC 600: Two Differential Current Inputs:</b> 0 to 20 mA, <math>R_{in} = 100 \Omega</math></p> <p><b>ACP 600: One Programmable Differential Current Input:</b> 0 to 20 mA, <math>R_{in} = 100 \Omega</math></p> <p><b>ACS/ACP 600: One Programmable Differential Voltage Input:</b> ACS 600: 0 (2) to 10 V, <math>R_{in} &gt; 200 \text{ k}\Omega</math>; ACP 600: 0 to 10 V, <math>R_{in} &gt; 200 \text{ k}\Omega</math></p> <p><b>ACC 600: One Differential Voltage Input:</b> 0 to 10 V, <math>R_{in} &gt; 200 \text{ k}\Omega</math></p> <p><b>Common Mode Voltage:</b> ± 15 VDC, max.</p> <p><b>Common Mode Rejection Ratio:</b> ≥ 60 dB at 50 Hz</p> <p><b>Resolution:</b> 0.1 % (10 bit)</p> <p><b>Inaccuracy:</b> ± 0.5 % (Full Scale Range) at 25 °C (77 °F). Temperature Coefficient: ± 100 ppm/°C (56 ppm/ °F), max.</p> <p><b>Input Updating Time:</b> 12 ms (ACS 600), 44 ms (ACC 600), 1 ms (ACP 600)</p>	<p><b>Two Bipolar Differential Voltage Inputs:</b> ± 10 V, <math>R_{in} = 20 \text{ k}\Omega</math></p> <p><b>Common Mode Voltage:</b> ± 20 VDC, max.</p> <p><b>Common Mode Rejection Ratio:</b> ≥ 60 dB at 50 Hz</p> <p><b>Resolution:</b> 0.02 % (12 bit)</p> <p><b>Accuracy:</b> 11 bit</p> <p><b>Inaccuracy:</b> ± 0.1 % (Full Scale Range) at 25 °C (77 °F). Temperature Coefficient: ± 100 ppm/°C (56 ppm/ °F), max.</p> <p><b>Input Updating Time:</b> 1 ms</p>
<p><b>Constant Voltage Output</b></p>	<p><b>Voltage:</b> 10 VDC ± 0.5 % (Full Scale Range) at 25 °C (77 °F). Temperature Coefficient: ± 100 ppm/°C (56 ppm/ °F), max.</p> <p><b>Maximum Load:</b> 10 mA</p> <p><b>Applicable Potentiometer:</b> 1 kΩ to 10 kΩ</p>	<p><b>Voltage:</b> ± 10 VDC ± 0.5 % (Full Scale Range) at 25 °C ( °F). Temperature Coefficient: ± 100 ppm/°C (56 ppm/ °F), max.</p> <p><b>Maximum Load:</b> 10 mA</p> <p><b>Applicable Potentiometer:</b> ≥ 1 kΩ</p>
<p><b>Auxiliary Power Output</b></p>	<p><b>Voltage:</b> 24 VDC ± 10 %, Short circuit proof</p> <p><b>Maximum Current:</b> 250 mA (130 mA with NLMD-01 option)</p>	<p><b>Voltage:</b> 24 VDC ± 10 %, Short circuit proof</p> <p><b>Maximum Current:</b> 250 mA</p>
<p><b>Analog Outputs</b></p>	<p><b>ACS/ACC 600: Two Programmable Current Outputs:</b> 0 (4) to 20 mA, <math>R_L \leq 700 \Omega</math></p> <p><b>ACP 600: One Programmable Current Output:</b> 0 to 20 mA, <math>R_L \leq 700 \Omega</math></p> <p><b>Resolution:</b> 0.1 % (10 bit)</p> <p><b>Inaccuracy:</b> ± 1 % (Full Scale Range) at 25 °C. Temperature Coefficient: ± 200 ppm/°C (110 ppm/ °F), max.</p> <p><b>Output Updating Time:</b> 24 or 100 ms (ACS 600), 44 ms (ACC 600), 8 ms (ACP 600)</p>	<p><b>One Bipolar Programmable Voltage Output:</b> ± 10 V, <math>R_L \geq 10 \text{ k}\Omega</math></p> <p><b>Resolution:</b> 0.02 % (12 bit)</p> <p><b>Accuracy:</b> 10 bit</p> <p><b>Inaccuracy:</b> ± 0.1 % (Full Scale Range) at 25 °C (77 °F). Temperature Coefficient: ± 200 ppm/°C (110 ppm/ °F), max.</p> <p><b>Output Updating Time:</b> 2 ms</p>



	<b>ACS/ACC/ACP 600 NIOC-01 Board</b>	<b>ACP 600 NIOCP-01 Board</b>
<b>Digital Inputs</b>	<p><b>ACS/ACP 600: Six Programmable Digital Inputs (Common Ground):</b> 24 VDC, -15 % to +20 %</p> <p><b>ACC 600: Six Digital Inputs (Common Ground):</b> 24 VDC, -15 % to +20 %</p> <p><b>Logical Thresholds:</b> &lt; 8 VDC <math>\hat{=}</math> "0", &gt; 12 VDC <math>\hat{=}</math> "1"</p> <p><b>Input Current:</b> DI1 to DI 5: 10 mA, DI6: 5 mA</p> <p><b>Filtering Time Constant:</b> 1 ms</p> <p><b>Thermistor Input:</b> 5 mA, &lt; 1.5 k<math>\Omega</math> <math>\hat{=}</math> "1" (normal temperature), &gt; 4 k<math>\Omega</math> <math>\hat{=}</math> "0" (high temperature), Open Circuit <math>\hat{=}</math> "0" (high temperature)</p> <p><b>Internal Supply For Digital Inputs (+24 VDC):</b> Short circuit proof, group isolated</p> <p><b>Isolation Test Voltage:</b> 500 VAC, 1 minute</p> <p><b>Input Updating Time:</b> 12 ms (ACS 600), 44 ms (ACC 600), 4 ms (ACP 600)</p> <p><b>An external 24 VDC supply can be used instead of the internal supply.</b></p>	<p><b>12 Programmable Digital Inputs (Common Ground):</b> 24 VDC, -15 % to +20 %</p> <p><b>Logical Thresholds:</b> &lt; 8 VDC <math>\hat{=}</math> "0", &gt; 12 VDC <math>\hat{=}</math> "1"</p> <p><b>Filtering Time Constant:</b> <math>\leq</math> 50 <math>\mu</math>s</p> <p><b>DI 11 and DI 12 can be used for time measurement between two external events (PROBE1 and PROBE2).</b></p> <p><b>Internal Supply For Digital Inputs (+24 VDC):</b> Short circuit proof, group isolated</p> <p><b>Isolation Test Voltage:</b> 500 VAC, 1 minute</p> <p><b>Input Updating Time:</b> 1 ms</p> <p><b>An external 24 VDC supply can be used instead of the internal supply.</b></p>
<b>Digital Outputs</b>		<p><b>Four Programmable Digital Outputs:</b> Short circuit proof, Overload protection</p> <p><b>Maximum Load:</b> 10 mA with internal 24 V supply, 100 mA with external supply</p> <p><b>Output Updating Time:</b> 2 ms</p>
<b>Relay Outputs</b>	<p><b>Three Programmable Relay Outputs</b></p> <p><b>Switching Capacity:</b> 8 A at 24 VDC or 250 VAC, 0.4 A at 120 VDC</p> <p><b>Maximum Continuous Current:</b> 2 A rms</p> <p><b>Contact Material:</b> Silver Cadmium Oxide (AgCdO)</p> <p><b>Isolation Test Voltage:</b> 4 kVAC, 1 minute</p> <p><b>Output Updating Time:</b> 100 ms (ACS 600), 44 ms (ACC 600), 8 ms (ACP 600)</p>	<p><b>One Relay Output</b></p> <p><b>Switching Capacity:</b> 8 A at 24 VDC or 250 VAC, 0.4 A at 120 VDC</p> <p><b>Max Continuous Current:</b> 2 A rms</p> <p><b>Contact Material:</b> Silver Cadmium Oxide (AgCdO)</p> <p><b>Isolation Test Voltage:</b> 4 kVAC, 1 minute</p> <p><b>Output Updating Time:</b> 2 ms</p>
<b>DDCS Fiber Optic Link</b>	<b>Protocol:</b> DDCS (ABB Distributed Drives Communication System)	

	ACS/ACC/ACP 600 NIOC-01 Board	ACP 600 NIOCP-01 Board
<b>Encoder Input</b>		<p><b>One Encoder Input:</b> 3 channel differential, +5 V encoder supply, frequency <math>\leq 200</math> kHz, supply cable resistance compensation. COMBICON connector, 15 pins. Meets the EIA standard RS 422.</p> <p><b>Required Encoder Type:</b> Contact ABB Application Engineer or your local ABB Representative for assistance.</p> <p><b>Encoder Signals:</b> Signal level/Load capacity: 5 V rectangular-pulse signals; Time between edges: <math>a &gt; 0,8 \mu s</math> at <math>f_{max}</math> ; Edge steepness: <math>t_v \leq 120</math> ns; Delay of reference signal Z (zero pulse): <math>t_d \leq 60</math> ns; Sampling frequency: <math>f_{max} = 200</math> kHz.</p>

**Encoder Signals** Characteristic of incremental encoder signals in applications using the incremental encoder (for clockwise rotation, viewed from the drive end) is presented below.



**Application Program**

Various application programs are available for the ACS 600 AC drives. In the tables of this section, the ACS 600 product family program selections are referred to with the following abbreviations. Not all selections are available for all types. One application program at a time can be loaded in the memory of the drive.

ACS 600 Application Program	Abbreviation
Standard	ACS
CraneDrive	ACC
MotionControl	ACP
System	MultiDrive

**Application Macros** The macros of the ACS/ACC/ACP application programs are below.

ACS	ACC	ACP
FACTORY for basic industrial applications	CRANE for normal crane drive	SPEED CONTROL for closed loop speed control
HAND/AUTO for local and remote operation	M/F CTRL for two crane drive applications with Master/Follower operation	POSITIONING for point-to-point positioning
PID CONTROL for closed loop processes	USER MACRO 1 & 2 for user's own customized parameter settings	SYNCHRONIZING for positioning to moving target
TORQUE CONTROL for processes that require torque control		TORQUE CONTROL for processes that require torque control
SEQUENTIAL CONTROL for operation at preset constant speeds		USER MACRO 1 & 2 for user's own customized parameter settings
USER MACRO 1 & 2 for user's own customized parameter settings		

**Languages** Languages and application macros included in the ACx 600 software are shown below. Not all selections are available for all types.

Code	Application Macros	Languages
B*	Factory, Hand/Auto, PID Control, Torque Control, Sequential Control	English (UK & Am), French, Spanish, Portuguese
C	Factory, Hand/Auto, PID Control, Torque Control, Sequential Control	English (UK & Am), German, Italian, Dutch
D	Factory, Hand/Auto, PID Control, Torque Control, Sequential Control	English (UK & Am), Danish, Swedish, Finnish
E	Factory, Hand/Auto, PID Control, Torque Control, Sequential Control	English (UK & Am), French, Spanish, Portuguese
F	PFC (Pump and Fan Control)	English (UK & Am), German, Italian, Dutch
G	PFC (Pump and Fan Control)	English (UK & Am), Danish, Swedish, Finnish
H	PFC (Pump and Fan Control)	English (UK & Am), French, Spanish, Portuguese
J	Master/Follower + Macros included in selection C	English (UK & Am), German, Italian, Dutch
K	Master/Follower + Macros included in selection D	English (UK & Am), Danish, Swedish, Finnish
L	Master/Follower + Macros included in selection E	English (UK & Am), French, Spanish, Portuguese
M*	Master/Follower + Macros included in selection B	English (UK & Am), French, Spanish, Portuguese
N	System application (ACS 600 MultiDrive software)	English
P	ACP 600: Torque Control, Speed Control, Positioning, Synchronizing	English, German
Q	ACP 600: Torque Control, Speed Control	English, German
S	ACC 600 software	English
T	Template application (FCB Programmable)	English
Y	Special software	English

\*This selection is for the North American market. The default parameter settings in the standard application macros include minor changes to fulfil the local regulations.

**Protection Features** Application program dependent features of the ACx 600 are listed below. ● available as standard, ○ optional

Preprogrammed Faults	ACS	ACC	ACP	Multi Drive	Programmable Fault Functions	ACS	ACC	ACP	Multi Drive	Programm. Supervision Functions	ACS	ACC	ACP	Multi Drive
ACx 600 temperature	●	●	●	●	Analog input below minimum value	●				Speed	2			2
Overcurrent	●	●	●	●	Loss of Control Panel	●	●		●	Motor current	●			●
Short circuit	●	●	●	●	External fault	●	●	●	●	Motor torque	2			2
DC overvoltage	●	●	●	●	Motor overtemperature	●	●	●	●	Motor speed	●			●
Supply phase	●	●	●	●	Thermistor/Pt 100	●	●	●	●	Reference 1	●			
DC undervoltage	●	●	●	●	Motor stalled	●		●	●	Reference 2	●			
Overfrequency	●	●		●	Motor underload	●		●	●	Actual value 1	●			
Overspeed			●		Loss of motor phase	●	●	●	●	Speed threshold				●
Internal fault	●	●	●	●	Ground fault	●	●	●	●	Torque threshold				●
Internal fault on the I/O control board	●	●	●	●	Speed measurement			●		Position error				●
Ambient temperature	●	●	●	●	Motor overspeed		●			Position threshold				●
User Macro	●	●	●		Torque		●			Joystick		●		
Braking chopper (in fieldbus mode)		●			Torque proving		●			Brake long falling time		●		
Inverter overload		●			Brake		●							
No motor data	●				Communication test		●							
ID Run fail	●				Following error			●						
					Position limits			●						
					Maximum speed alteration			●						
					Speed difference			●						
					Communication error	○	○	●	○					
					Encoder interface module	○	○	●	○					

**Preprogrammed Warnings:** ACS 600 temperature, Motor Identification Run, Drive Identification Number change, User Macro, Target position (ACP), Positioning speed (ACP).

**Programmable Automatic Reset Functions (ACS 600 only):** after overcurrent, overvoltage, undervoltage and analog input below minimum value

**Information Functions:** ACx 600 control software version, ACx 600 application software version, ACx 600 test date.

**Applicable Standards**

The ACS 600 complies with the following standards:

- EN 60204-1: 1992 + Corr. 1993 (IEC 204-1). Safety of machinery. Electrical equipment of machines. Part 1: General requirements. *Provisions for compliance:* The final assembler of the machine is responsible for installing
  - an emergency-stop device
  - a supply disconnecting device (ACx 601 and ACx 604)
  - the ACx 604 (IP 00) into a separate casing.
- EN 60529: 1991 (IEC 529), IEC 664-1: 1992. Degrees of protection provided by enclosures (IP code).
- EN 61800-3 (1996): EMC product standard including specific test methods.

**Materials**

Enclosure (ACx 601)	Thickness of Coating	Color
PS (polystyrene) 3 mm (0.12 in)		NCS 1502-Y (RAL 90021 / PMS 420 C)
hot-dip zinc coated steel sheet 1.5 to 2 mm(0.06 to 0.08 in) painted with epoxy polyester powder paint	60 µm	NCS 8502-Y (RAL 9004 / PMS 426 C) semigloss
anodized aluminium profile (R2 to R6)		black ES 900
<b>Package (ACx 601)</b>		
corrugated board (frames R2 to R5 and option modules), plywood (R6). Plastic covering of the package: PE-LD, bands PP or steel.		

**Disposal**

ACx 600 contains raw materials that should be recycled, thus preserving energy and natural resources. Package materials of ACx 600 units and options are environmentally compatible and recyclable. All metal parts can be recycled. The plastic parts can either be recycled or burned under controlled circumstances, according to local regulations. If recycling is not feasible, all parts excluding electrolytic capacitors can be landfilled. The DC capacitors of the unit contain electrolyte which is classified as hazardous waste. (Location of the electrolytic capacitors is shown on a sticker in the back of the front cover, C11 to C13.) They must be removed and handled according to local regulations.

For further information on environmental aspects, please contact your local ABB distributor.

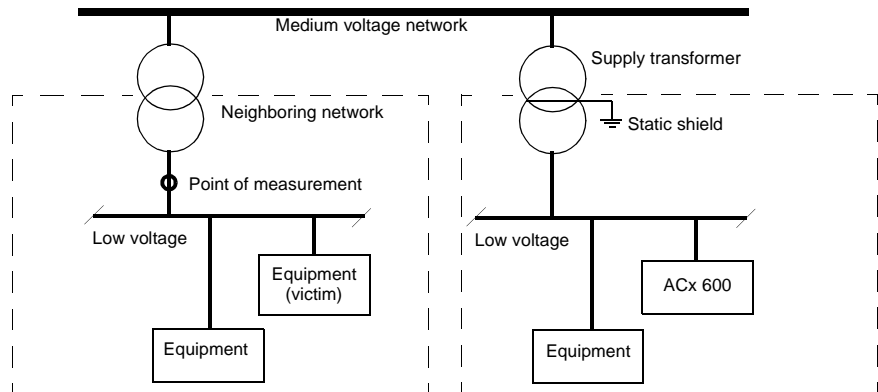
**CE Marking**

A CE mark is attached to ACx 601/607 drives to verify that the unit follows the provisions of the European Low Voltage and EMC Directives (Directive 73/23/EEC, as amended by 93/68/EEC and Directive 89/336/EEC, as amended by 93/68/EEC).

**Compliance with the EMC Directive**

EMC stands for **Electromagnetic Compatibility**. It is the ability of electrical/electronic equipment to operate without problems within an electromagnetic environment. Likewise, the equipment must not disturb or interfere with any other product or system within its locality.





Use of the ACx 600 in Second Environment without EMC filtering (EN 61800-3: second environment includes all establishments other than those directly connected to a low-voltage power supply network which supplies buildings used for domestic purposes.)

**Public Low-Voltage Network**

1. The ACx 600 is equipped with EMC filtering (refer to Table A-1).
2. The ACx 601 is installed with motor and control cables as specified in this manual.
3. Maximum cable length is 100 meters.

Without considering the EMC requirements, do not use the ACx 600 on a low voltage public network supplying domestic premises. This kind of use might cause radio frequency interference.

**Ungrounded Power (IT Network)**

1. It is ensured that no excessive emission is propagated to neighboring low-voltage networks. In some cases, the natural suppression in transformers and cables is sufficient. If in doubt, the supply transformer with static shielding between the primary and secondary windings can be used.
2. The ACx 601 is installed with motor and control cables as specified in this manual.

**Note:** The ACx 600 must not be equipped with EMC filtering (refer to Table A-1) when installed to floating networks. The power becomes connected to ground potential through the EMC filter capacitors. In floating networks this may cause danger or damage the unit.

**Machinery Directive**

ACx 601/604/607 drives comply with the European Union Machinery Directive (89/392/EEC) requirements for an equipment intended to be incorporated into machinery.

**UL/CSA Markings**

The UL/UL<sub>C</sub>/CSA markings of the ACS 600 drives are listed below (x).

ACx 600 Type	UL	UL <sub>C</sub>	CSA
ACS 601 (IP 22) 400 V, 500 V and 600 <sup>1)</sup> V ranges	x	x	x
ACS 601 (IP 54)	x	x	pending
ACS 604 frame sizes R7 to R9 400 V, 500 V and 600 <sup>1)</sup> V ranges	x	x	x
ACS 604 600 V parallel connected units	pending	pending	pending

1) the approval is valid up to 600 V



**UL** ACS 600 is suitable for use in a circuit capable of delivering not more than 65 kA rms symmetrical amperes at 480 V maximum (500 V units), and at 600 V maximum (690 V units).

ACS 600 provides overload protection (if selected) in accordance with the National Electrical Code (US). See *ACS 600 Firmware Manual*

ACS 600 drives are to be used in a heated indoor controlled environment. See subsection *Ambient Conditions* for specific limits.

## **Equipment Warranty and Liability**

General: ABB warrants the Equipment supplied by ABB against defects in material and workmanship for a period of twelve (12) months after installation or twenty four (24) months from date of shipment from factory, whichever first occurs.

Should any failure to conform with the applicable warranties appear during the specified periods under normal and proper use and provided the Equipment has been properly stored, installed, operated and maintained, and if given prompt notice by Purchaser, ABB shall correct such nonconformity, at its option; by (1) repair or replacement of the nonconforming equipment or parts thereof. Repairs or replacements pursuant to warranty shall not renew or extend the applicable original equipment warranty period, provided however, that any such repairs or replacement of equipment or parts thereof shall be warranted for the time remaining of the original warranty period or 30 days, whichever is longer.

ABB shall not be responsible for providing working access to the defect, including disassembly and reassembly of equipment or for providing transportation to and from repair or factory facility, all of which shall be at Purchaser's risk and expense.

These warranties shall not apply to any Equipment or parts thereof which (1) have been improperly repaired or altered; (2) have been subjected to misuse, negligence or accident; (3) have been used in a manner contrary to ABB's instructions; (4) are comprised of materials provided or designed stipulated by Purchaser; or (5) are used equipment.

The foregoing warranties are exclusive and in lieu of all other warranties of quality and performance, written, oral or implied, and all other warranties including any implied warranties of merchantability or fitness for a particular purpose are hereby disclaimed by ABB and all equipment manufacturers.

Correction of nonconformities in the manner and for the period of time provided above shall be the Purchaser's exclusive remedy and shall constitute fulfilment of all liabilities of ABB and any Equipment manufacturer (including any liability for direct, indirect, special, incidental or consequential damages) whether in warranty, contract, negligence, tort, strict liability, or otherwise with respect to any nonconformance of or defect or deficiency in the equipment supplied or services furnished hereunder.

## **Limitation of Liability**

**IN NO EVENT SHALL ABB, ITS SUPPLIERS OR SUBCONTRACTORS BE LIABLE FOR SPECIAL, INDIRECT, INCIDENTAL OR CONSEQUENTIAL DAMAGES, WHETHER IN CONTRACT, WARRANTY, TORT, NEGLIGENCE, STRICT LIABILITY OR OTHERWISE**, including, but not limited to loss of profits or revenue, loss of use of the Equipment or any associated equipment, cost of capital, cost of substitute equipment, facilities or services, downtime costs, delays, or claims of customers of the Purchaser or other third parties for such or other damages. ABB's liability on any claim whether in contract, warranty, negligence, tort, strict liability, or otherwise for any loss or damage arising out of, connected with, or resulting from the contract or the performance or breach thereof, or from the design, manufacture, sale, delivery, resale, repair, replacement, installation, technical direction of installation, inspection, operation or use of any equipment covered by or in connection therewith, shall in no case exceed the purchase price of the Equipment or part thereof or services which give rise to the Claim.

All clauses of action against ABB arising out of or relating to the contract or the

performance or breach hereof shall expire unless brought within one year of the time of accrual thereof.

In no event, regardless of cause, shall ABB assume responsibility for or be liable for penalties or penalty clauses of any description or for indemnification of customer or others for costs, damages, or expenses each arising out of or related to the goods or services of the order.

Your local distributor or ABB office may hold different guarantee details, which are specified in the sales terms, conditions, or guarantee terms. These terms are available on request.

If you have any questions concerning your ABB drive, please contact the local distributor or ABB office. The technical data, information and specifications are valid at the time of printing. The manufacturer reserves the right to modifications without prior notice.

## Appendix B – ACS/ACC/ACP 601 Dimensional Drawings

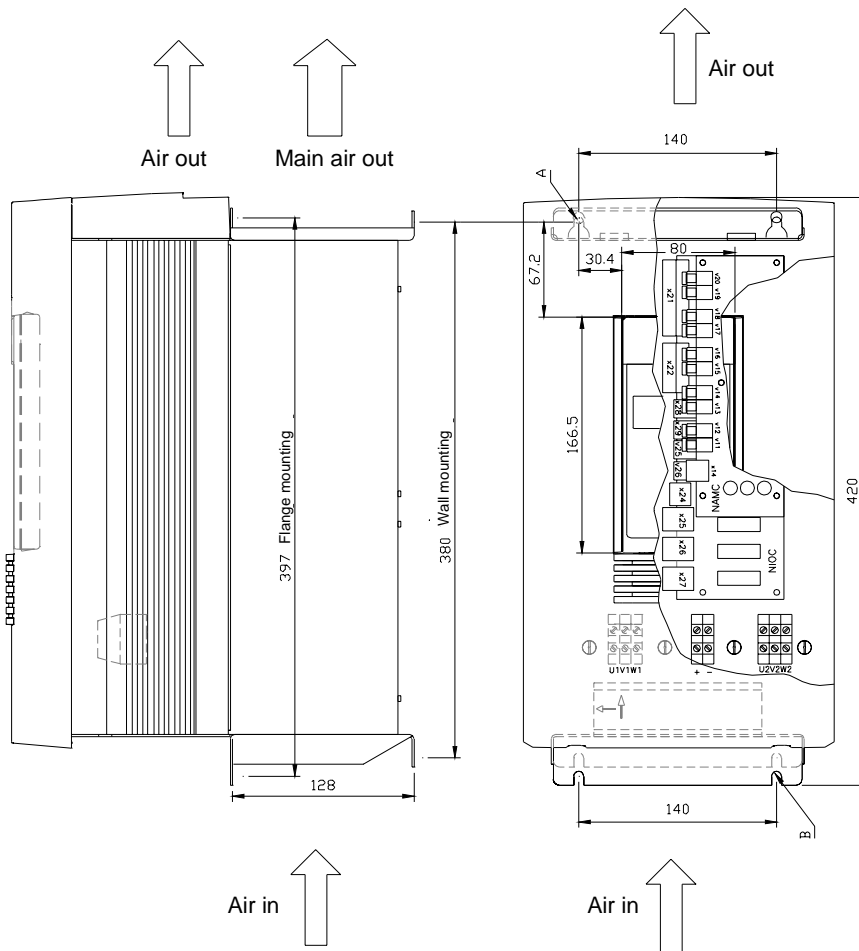
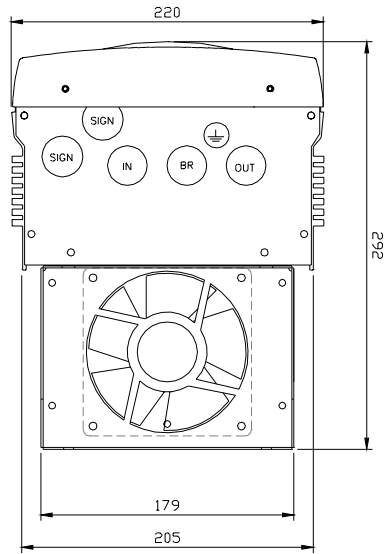
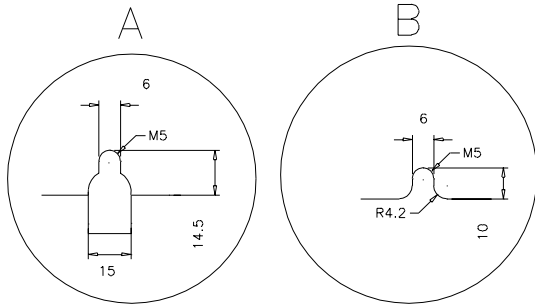
The following drawing package is effective from 5/10/98.

### Gland Plate Holes (IEC Units)

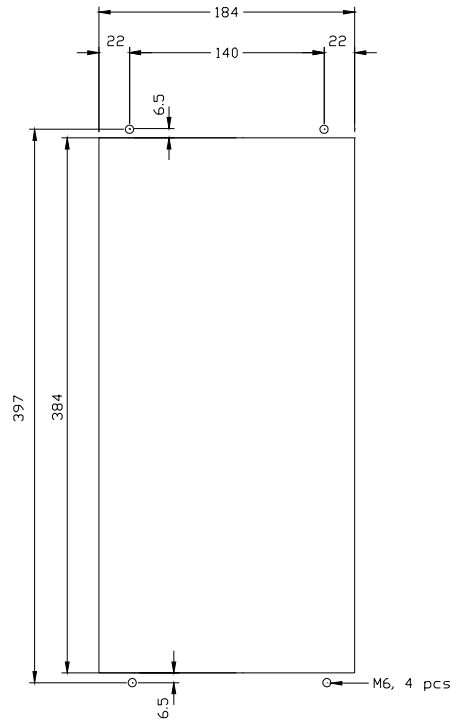
Frame	R2 ACx = ACS/ACC/ACP	R3 ACx = ACS/ACC/ACP	R4 ACx = ACS/ACC/ACP	R5 ACx = ACS/ACC/ACP	R6 ACx = ACS/ACC/ACP	R7 ACx = ACS/ACC/ACP
Hole	ACx 601-0005-3 ACx 601-0006-3 ACx 601-0009-3 ACx 601-0006-5 ACx 601-0009-5 ACx 601-0011-5  mm	ACx 601-0009-6 ACx 601-0011-3/-6 ACx 601-0016-3 ACx 601-0016-5/-6 ACx 601-0020-5/-6  mm	ACx 601-0020-3 ACx 601-0025-3/-6 ACx 601-0025-5 ACx 601-0030-5/-6  mm	ACx 601-0030-3 ACx 601-0040-3 ACx 601-0050-3 ACx 601-0040-5/-6 ACx 601-0050-5/-6 ACx 601-0060-5  mm	ACx 601-0060-3/-6 ACx 601-0070-3 ACx 601-0070-5/-6 ACx 601-0100-5  mm	ACx 601-0100-3/-6 ACx 601-0120-3 ACx 601-0120-5/-6 ACx 601-0140-5  mm
SIGN	23	23	29	29	29	29
IN/OUT	29	29	37	37	48	60
BR	29	29	29	37	37	60
⏏	23	23	23	23	23	29

**Frame R2**

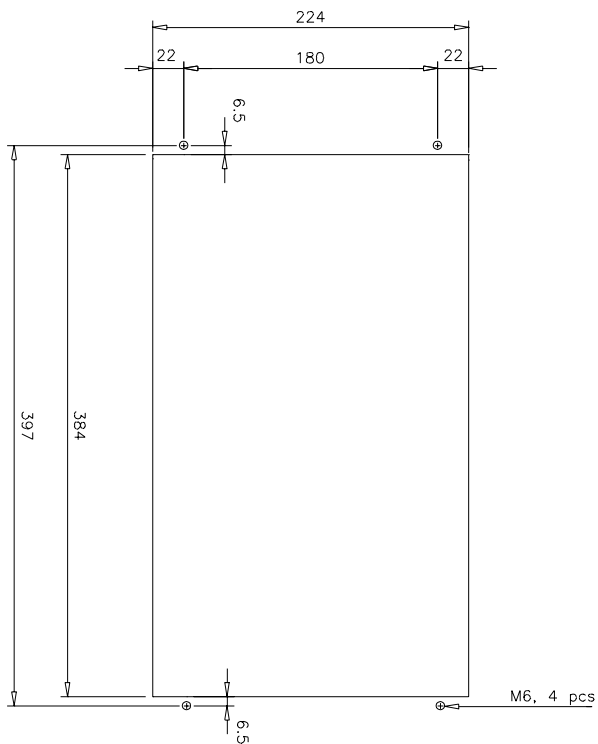
TYPE (ACx = ACS/ACC/ACP)	WEIGHT
ACx 601-0005-3	14 kg
ACx 601-0006-3	14 kg
ACx 601-0009-3	14 kg
ACx 601-0006-5	14 kg
ACx 601-0009-5	14 kg
ACx 601-0011-5	14 kg



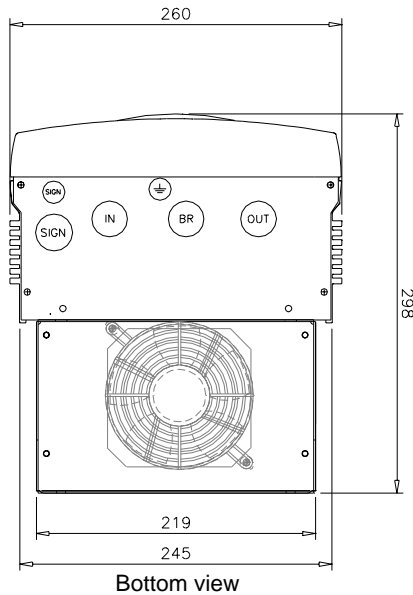
### Frame R2 Flange Mounting



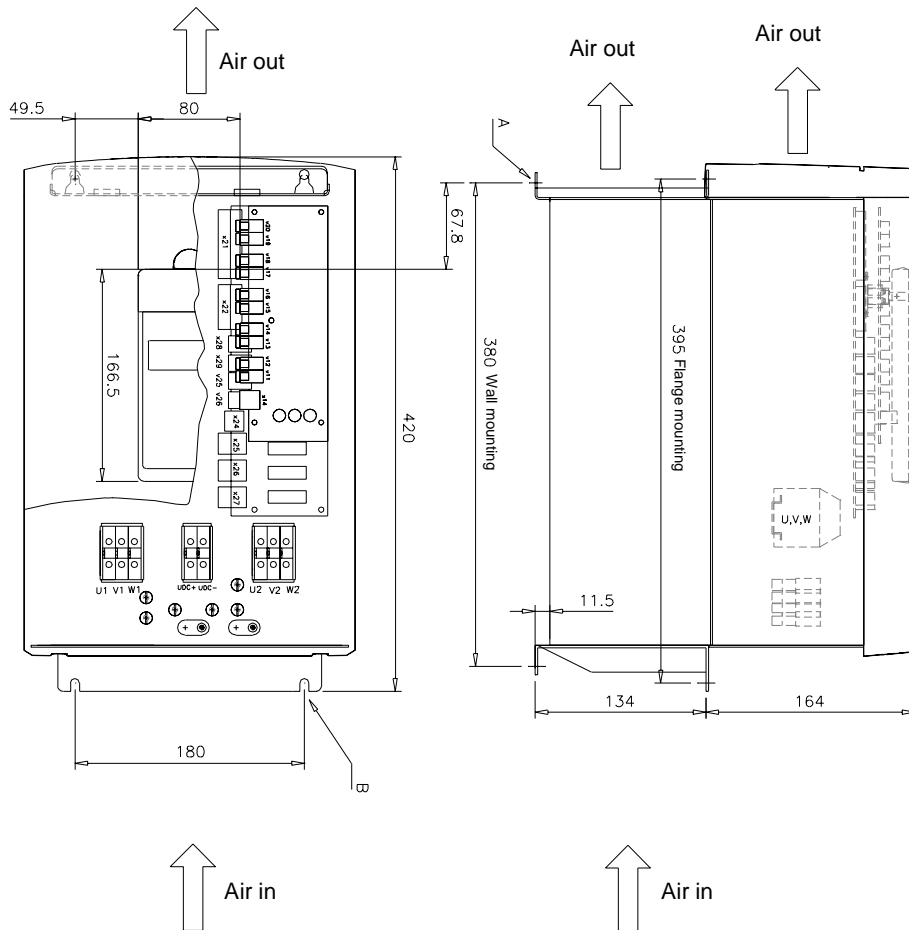
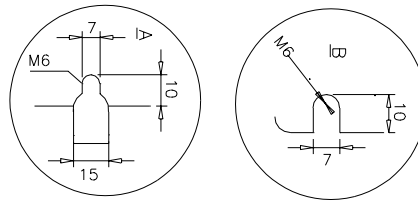
### Frame R3 Flange Mounting



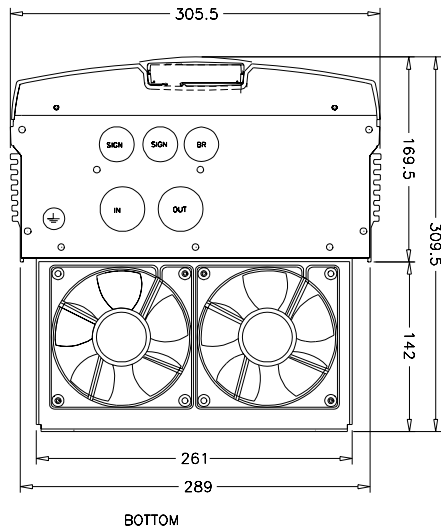
**Frame R3**



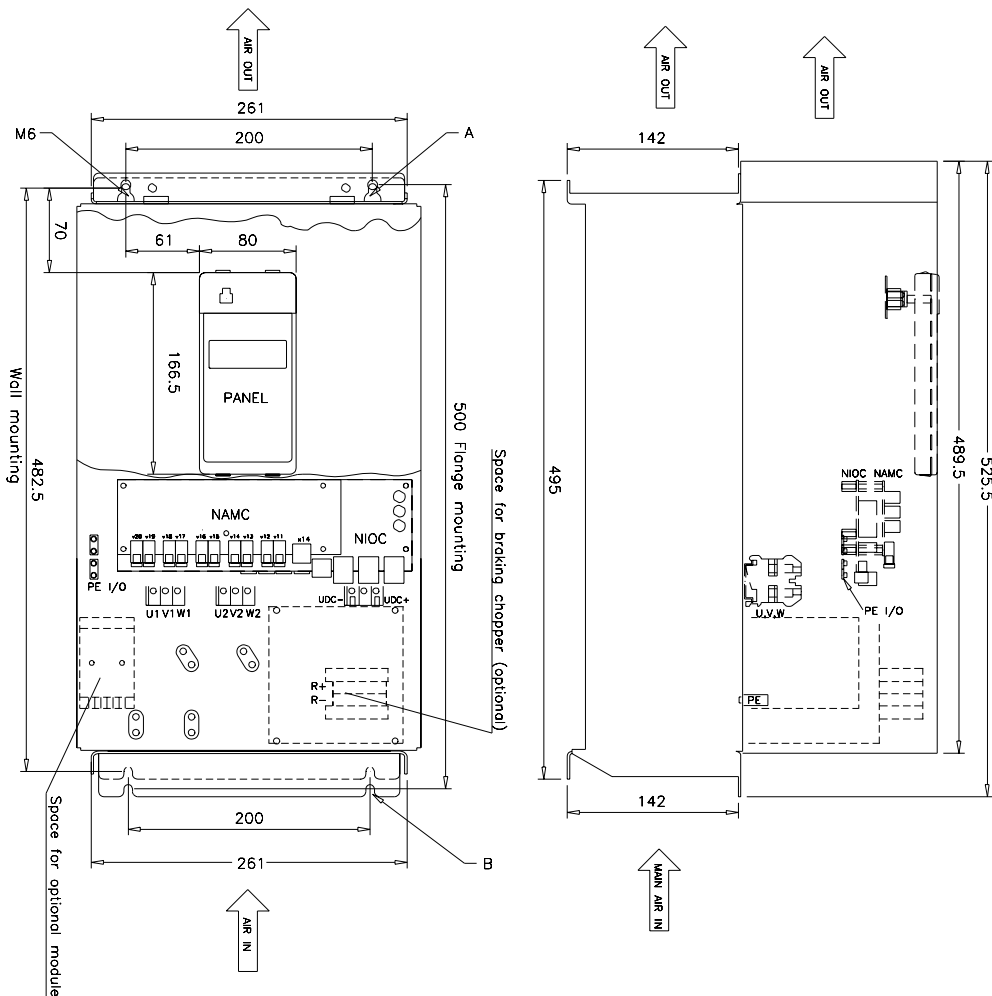
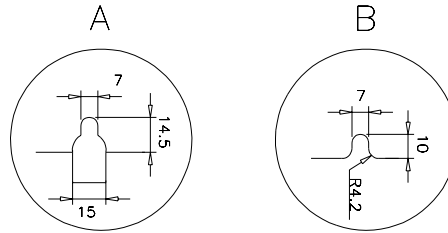
TYPE (ACx = ACS/ACC/ACP)	WEIGHT
ACx 601-0011-3	17.5 kg
ACx 601-0016-3	17.5 kg
ACx 601-0016-5	17.5 kg
ACx 601-0020-5	17.5 kg
ACx 601-0009-6/0011-6	17.5 kg
ACx 601-0009-6/0020-6	17.5 kg



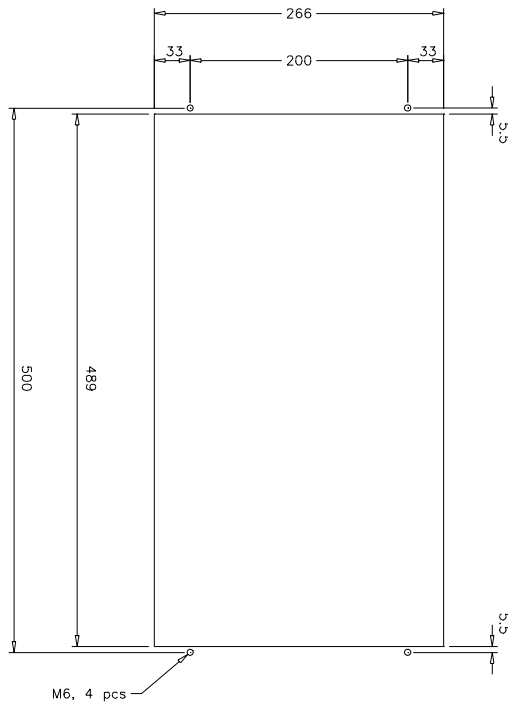
**Frame R4**



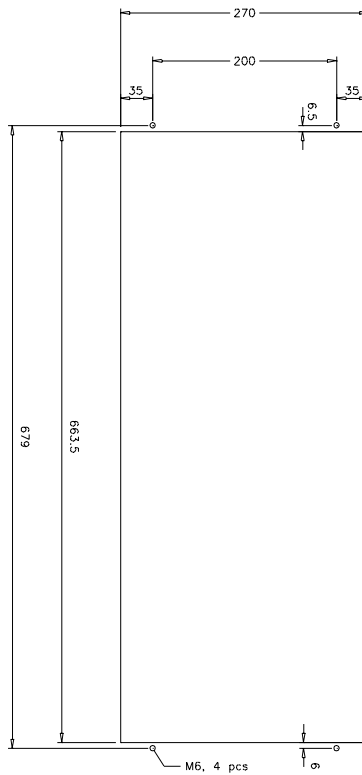
TYPE (ACx = ACS/ACC/ACP)	WEIGHT
ACx 601-0020-3	25 kg
ACx 601-0025-3	25 kg
ACx 601-0025-5	25 kg
ACx 601-0030-5	25 kg
ACx 601-0025-6	25 kg
ACx 601-0030-6	25 kg



**Frame R4 Flange Mounting**

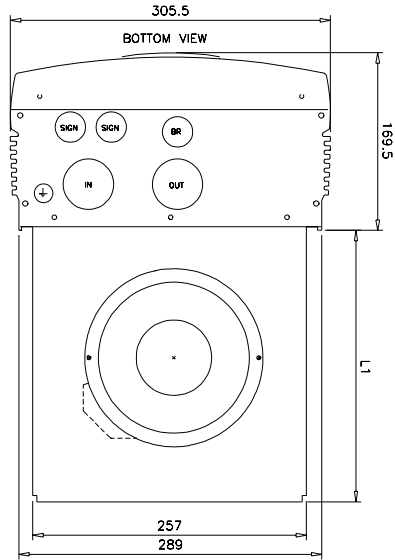


**Frame R5/R6 Flange Mounting**

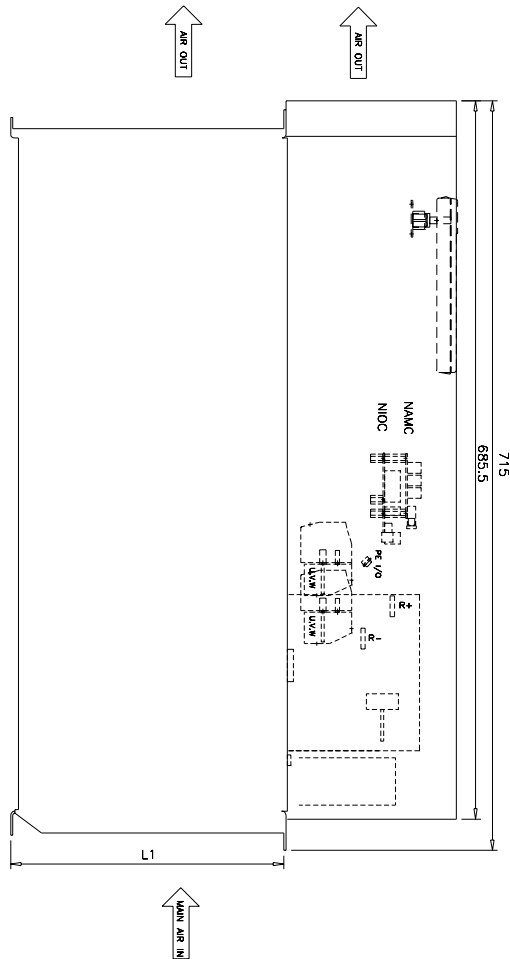
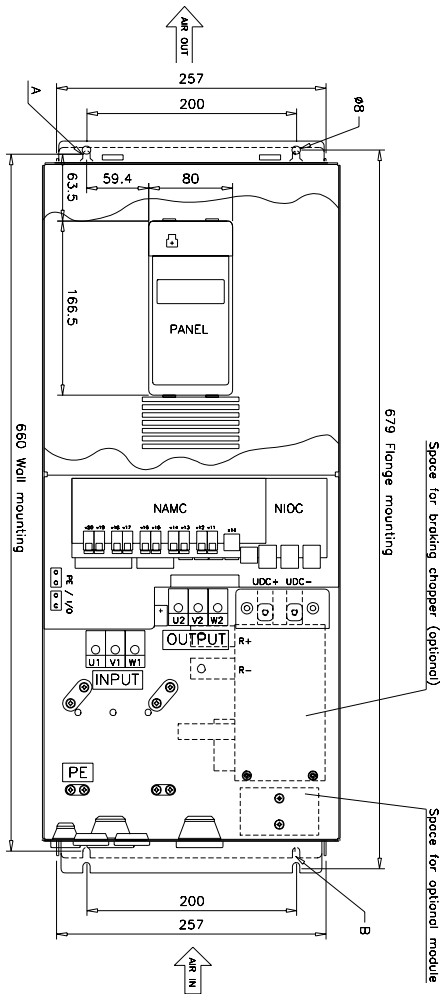
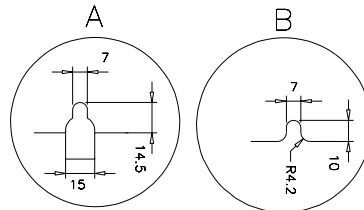




Frame R5/R6

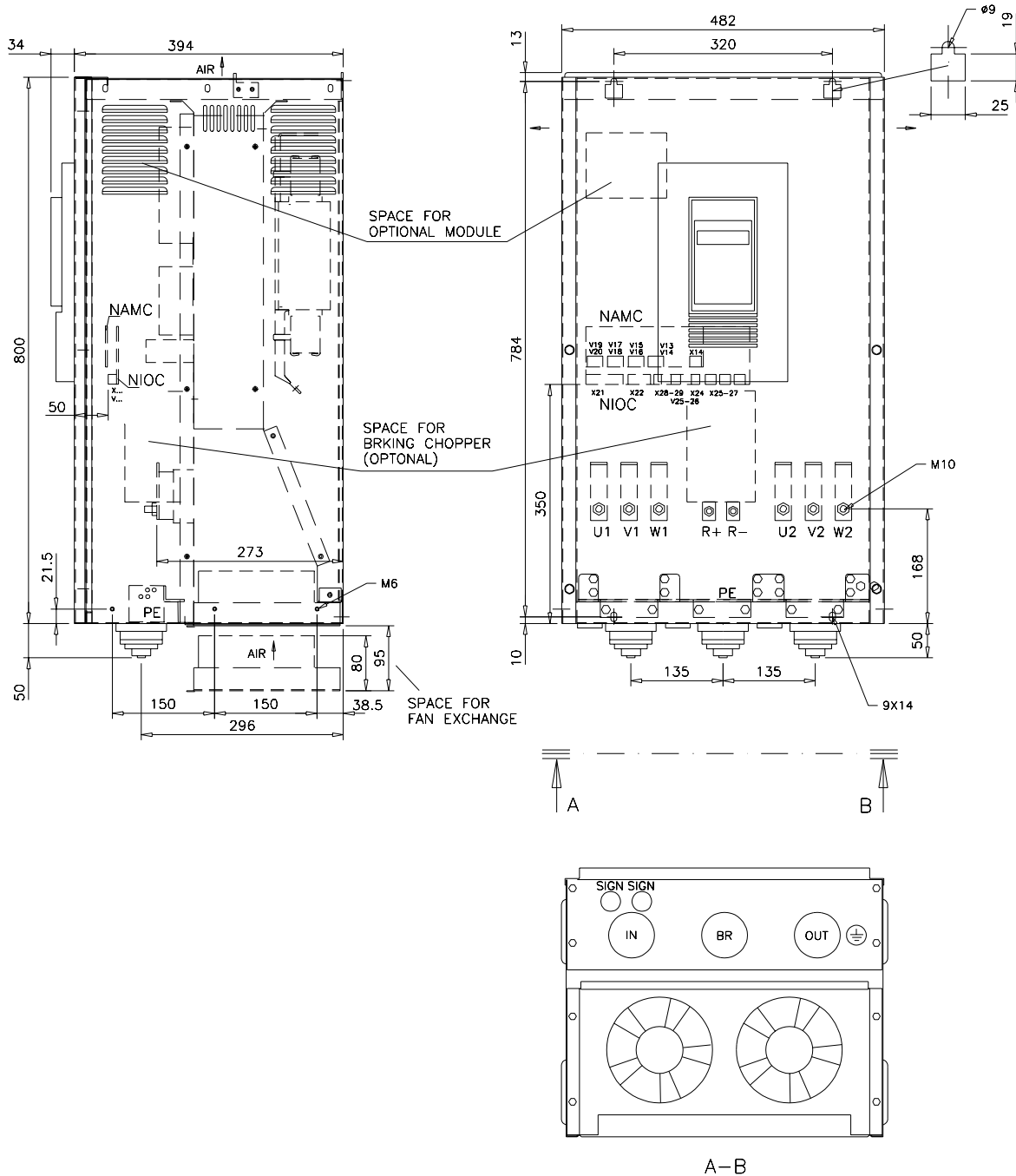


TYPE (ACx = ACS/ACC/ACP)	WEIGHT	L1
ACx 601-0030...0050-3	35 kg	190.5
ACx 601-0040...0060-5	35 kg	190.5
ACx 601-0040-6/-0060-6	35 kg	190.5
ACx 601-0060...0070-3	50 kg	262.5
ACx 601-0070...0100-5	50 kg	262.5
ACx 601-0060-6/-0070-6	50 kg	262.5



**Frame R7**

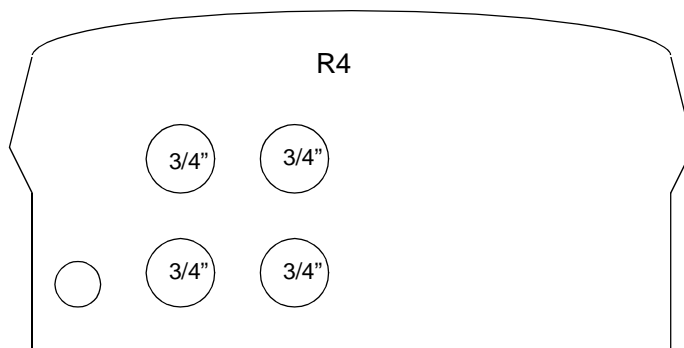
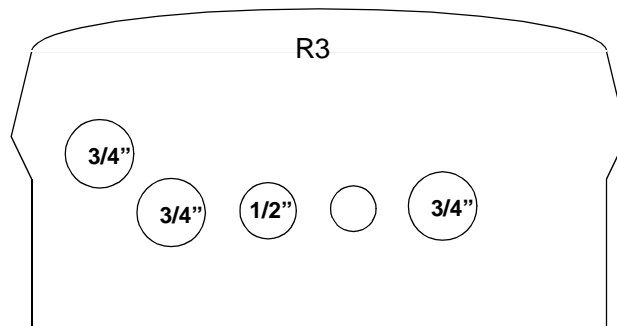
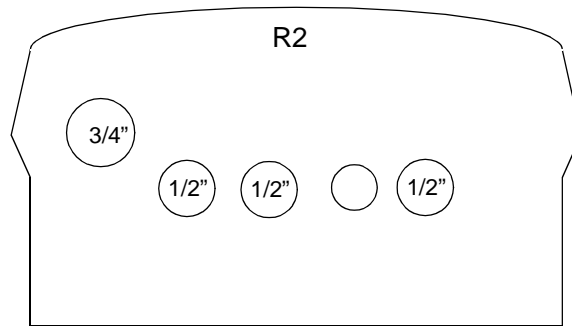
TYPE (ACx = ACS/ACC/ACP)	WEIGHT
ACx 601-0100-3/-6	88 kg
ACx 601-0120-3	88 kg
ACx 601-0120-5/-6	88 kg
ACx 601-0140-5	88 kg



**Conduit Plates  
(USA Version)**

The following figures show the conduit plate (bottom view) of the different size ACS 600 units:

At least three separate rigid metallic conduits must be used; one each for input power, output power, and control wires. Additionally, a separate conduit must be used for dynamic braking device, if used.



*Conduit Entry Plates, R2 - R4 USA Version*

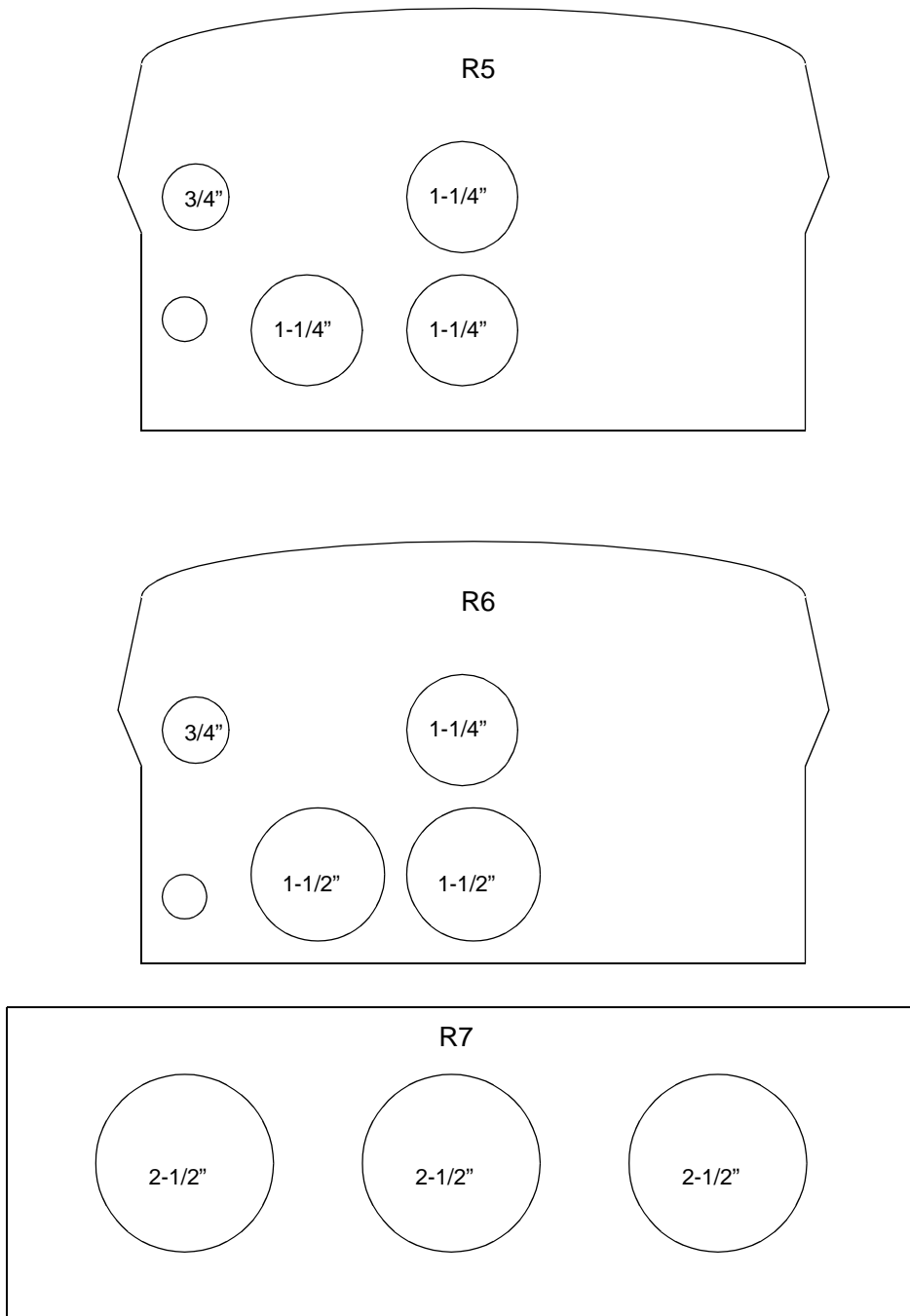


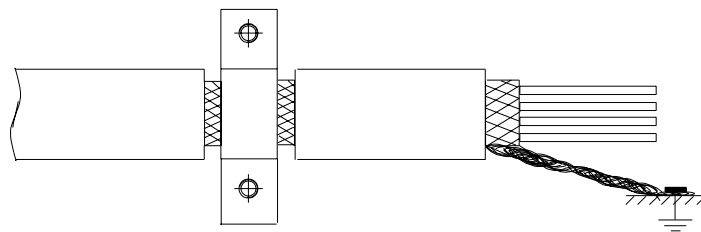
Figure 2-1 Conduit Entry Plates, R5- R7 USA Version

**ACP 601 Control  
Cable Connections**

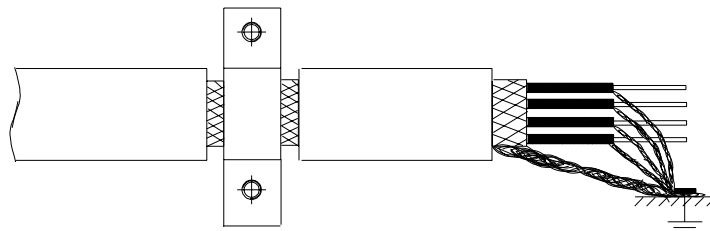


The deliveries include a bag with four clamps, screws and copper tape (frame size R4 also an assembly plate). Clamp the control and encoder cables as explained below. If more than four cables are needed, connect the twisted screen (grounding wires) of the additional cables as short as possible to the grounding rail (⊕) next to the NIOC(P) board. Clamping is very important with the encoder cable but less so with relay and other digital signal cables.

1. Strip the cable according to figure below.
2. Frame size R4 only: fasten the assembly plate with screws to the frame.
3. Connect the conductors to the appropriate terminals on the NIOC/ NIOCP board.
4. Ensure 360 degrees grounding by coiling copper tape onto the stripped part of the cable underneath the clamp.
5. Fasten the clamps to the frame with screws.
6. Twist the screen (grounding wires) of the outer shield and connect it through the shortest possible route (max. 2 cm) to the nearest grounding terminal. With double shielded cables, connect each conductor shield (twisted grounding wires) separately to the nearest grounding terminal. Conductor shields of other than encoder cables can be twisted together.

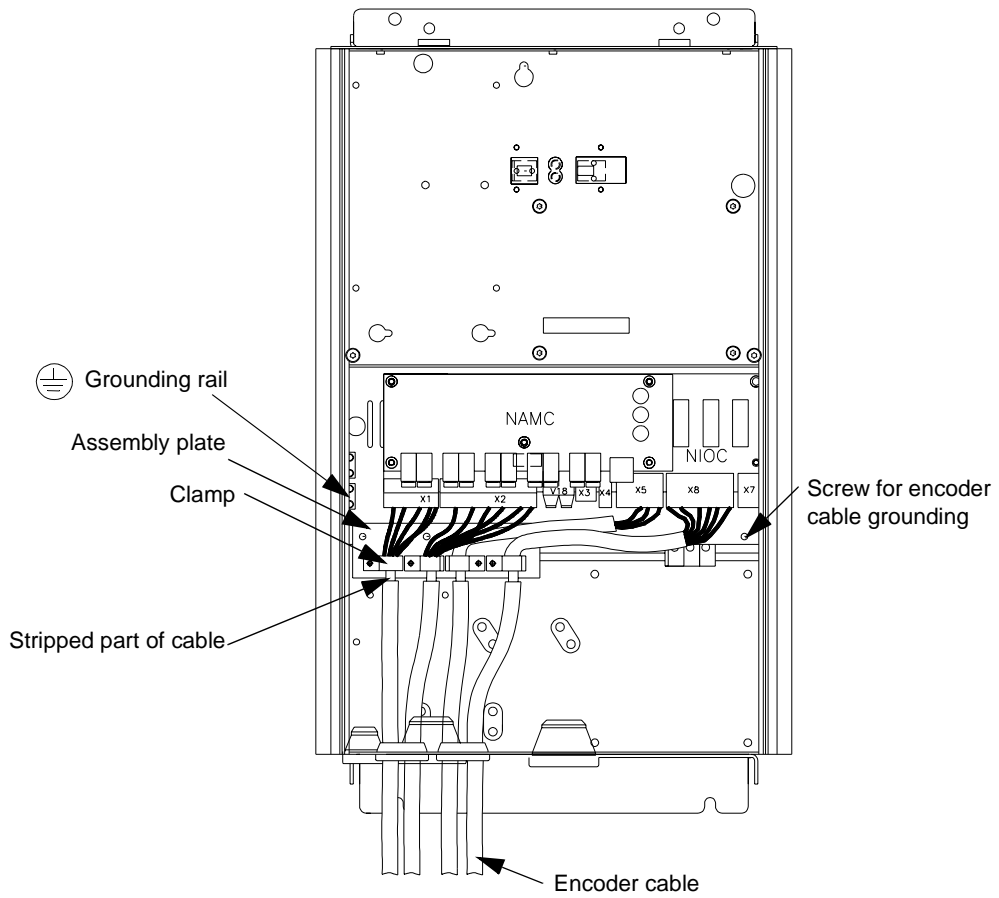


Single shielded cable

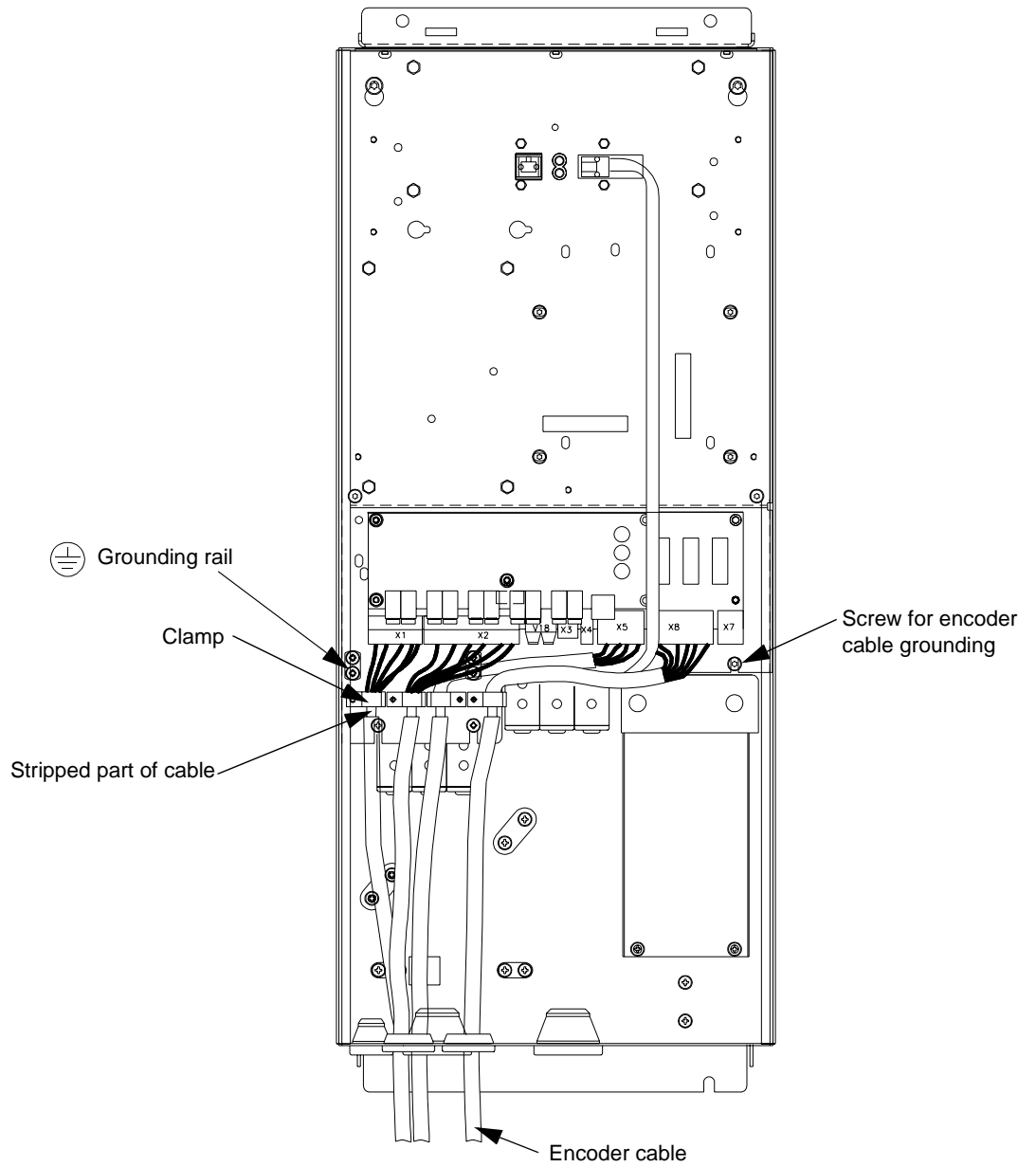


Double shielded cable

**ACP 601 Frame R4**



**ACP 601 Frame R5/R6**







## Appendix C – IEC Installation

### IEC Installations

This appendix is a supplement to *Chapter 3 – Electrical Installation*. It contains additional information to be used in IEC installations. For installations requiring CE compliance, refer also to the section entitled *CE Marking* in Appendix A.

### Power Cables

For ACx 601 frame size R5 and larger or larger 30 kW motors symmetrical shielded motor cable must be used (figure below). A four-conductor system can be used up to frame size R4 with up to 30 kW motors, but shielded symmetrical motor cable is recommended.

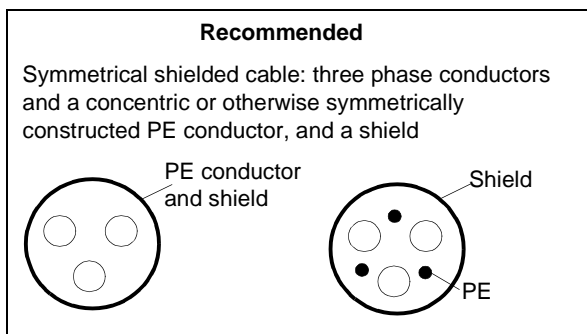
A four-conductor system is allowed for power cabling, but shielded symmetrical cable is recommended. To operate as a protective conductor, the shield conductivity must be at least 50 % of the conductivity of the phase lead.

Compared to a four-conductor system, the use of symmetrical shielded cable reduces electromagnetic emission of the whole drive system as well as motor bearing currents and wear.

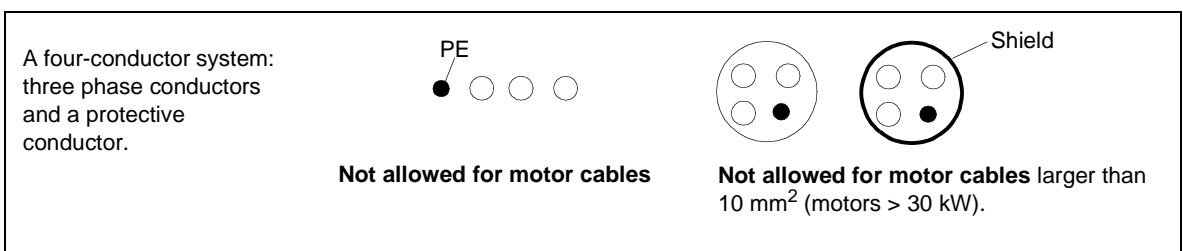
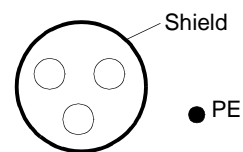
The motor cable and its PE pigtail should be kept as short as possible in order to reduce electromagnetic emission as well as capacitive current.

### Alternative Power Cable Types

Power cable types that can be used with ACx 600 are represented below.

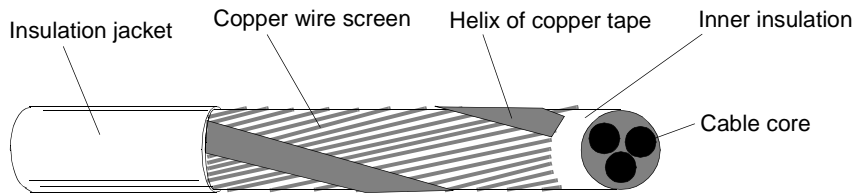


A separate PE conductor is required if the conductivity of the cable shield is < 50 % of the conductivity of the phase conductor.



**Motor Cable Shield**

To effectively suppress radiated and conducted radio-frequency emissions, the shield conductivity must be at least 1/10 of the phase conductor conductivity. One way of evaluating the effectiveness of the shield is the shield inductance, which must be low and only slightly dependent on the frequency. These requirements are easily met with a copper or aluminium shield. The minimum requirement of the motor cable shield of the ACx 600 is shown below. It consists of a concentric layer of copper wires with an open helix of copper tape. The better and tighter the shield is, the lower is the emission level and the bearing currents.



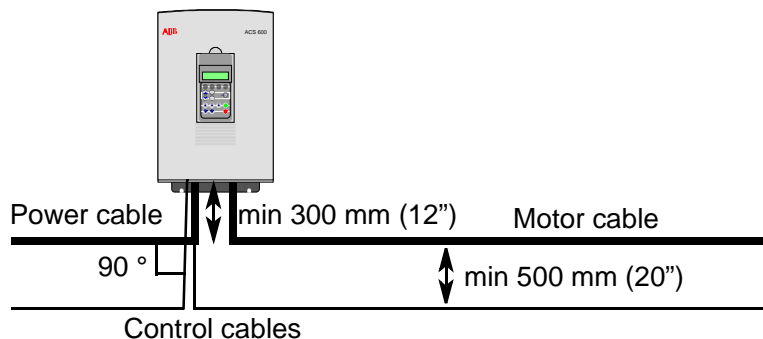
**Cable Routing**

The motor cable should be installed away from other cable routes. Motor cables of several drives can be run in parallel installed next to each other. It is recommended that the motor cable, power cable and control cables be installed on separate trays (minimum distance 500 mm (20")). Long parallel runs of motor cable with other cables should be avoided in order to decrease electromagnetic interference caused by the rapid changes in the frequency converter output voltage.

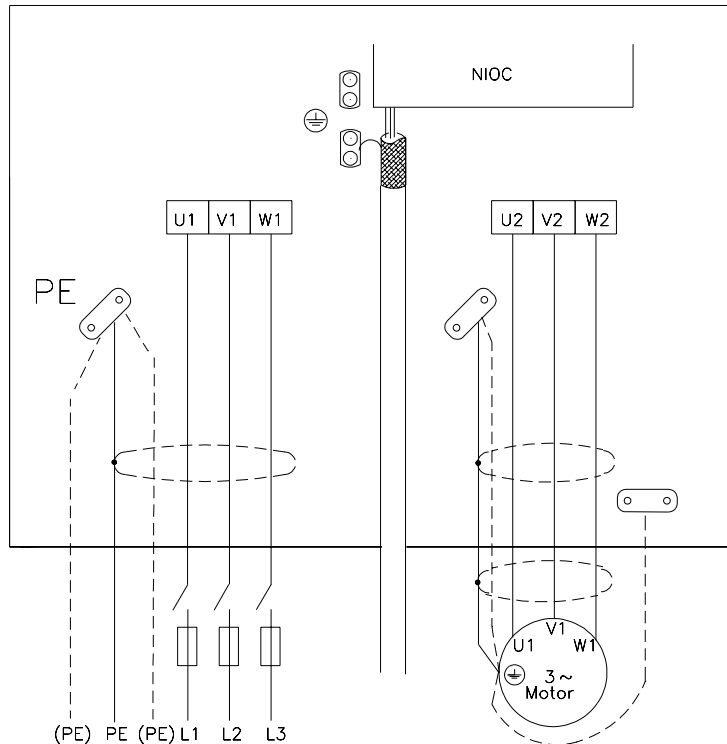
Where control cables must cross power cables make sure they are arranged at an angle as near to 90 degrees as possible. Extra cables should not be run through the ACx 600.

The cable trays have good electrical bonding to each other and to the grounding electrodes. Aluminium tray systems can be used to improve local equalizing of potential.

Below is a diagram of cable routing.



**Cable Connections** Recommended earthing, mains and motor cable connections are presented below. See *Appendix B – Dimensional Drawings* to locate the terminals



- 1) Alternative to earthing of the ACx 601 and the motor through the cable screen.  
**Note:** Connecting the fourth conductor of the motor cable at the motor end increases bearing currents, thus causing extra wear.
- 2) Used if the conductivity of the cable screen is < 50 % of the conductivity of the phase conductor.

Earth the other end of the mains cable at the distribution board.

For minimum radio frequency interference (RFI) at the motor end, earth the cable screen 360 degrees at the lead-through of the motor terminal box or earth the cable by twisting the screen (flattened width  $\geq 1/5 \cdot$  length).


**Earthing, Power, and Motor Cable Connections**

1. Lead the power cable through the INPUT cable entry, and the motor cable through the OUTPUT entry into the unit. Frame R7: Remove the rubber grommets from the INPUT and OUTPUT entries and cut them to adequate diameter for the power and the motor cable. To ensure proper sealing cut along the diameter marking which corresponds to the cable diameter.
2. Connect the phase conductors of the power cable to the U1, V1 and W1 terminals and the phase conductors of the motor cable to the U2, V2 and W2 terminals.
3. Connect the twisted screen of the power cable to the grounding terminal. Perform the same with the motor cable screen.

Connect the additional PE conductors (if present) of the power and motor cables to the grounding terminal. Connect the separate PE conductor (if used) to the grounding terminal.

**Control Cable Connections**

1. Lead the cable inside the unit through the SIGN entry. Connect the conductor in appropriate terminal at the NIOC/NIOCP board (**A2**, refer *Appendix A* and *Firmware Manual*) and tighten screw to secure connection. Connect the twisted screen (grounding wires) to

the grounding rail  next to the NIOC/NIOCP board.

**Components  
Connected to Digital/  
Analog Inputs**



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**WARNING!** IEC 664 requires double or reinforced insulation between live parts and the surface of accessible parts of electrical equipment which are either non-conductive or conductive but not connected to the ground (PE).

To fulfil this requirement, the connection of a thermistor (and other similar components) to the digital inputs of ACx 600 can be implemented in three alternate ways:

1. There is double or reinforced insulation between the thermistor and live parts of the motor.
  2. Circuits connected to all digital and analog inputs of the ACx 600
    - are protected against contact, and
    - insulated with basic insulation (the same voltage level as the converter main circuit) from other low voltage circuits.
  3. An external thermistor relay is used. The insulation of the relay must be rated for the same voltage level as the converter main circuit.
-





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