# Computational Quantum Physics 

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## Chapter 1

## Introduction

### 1.1 General

For physics students the computational quantum physics courses is a recommended prerequisite for any computationally oriented semester thesis, proseminar, master thesis or doctoral thesis.

For computational science and engineering (RW/CSE) students the computational quantum physics courses is part of the specialization in theoretical physics.

### 1.1.1 Exercises

## Programming Languages

Except when a specific programming language or tool is explicitly requested you are free to choose any programming language you like. Solutions will often be given either as C++ programs, Python scripts, or Mathematica Notebooks.

## Computer Access

The exercise rooms offer both Linux workstations, for which accounts can be requested with the computer support group of the physics department in the HPT building, as well as connections for your notebook computers.

### 1.1.2 Prerequisites

As a prerequisite for this course we expect knowledge of the following topics. Please contact us if you have any doubts or questions.

## Computing

- Basic knowledge of UNIX
- At least one procedural programming language such as C, C++, Pascal, Java or FORTRAN. C++ knowledge is preferred.
- Knowledge of a symbolic mathematics program such as Mathematica or Maple.
- Ability to produce graphical plots.


## Numerical Analysis

- Numerical integration and differentiation
- Linear solvers and eigensolvers
- Root solvers and optimization
- Statistical analysis


## Quantum Mechanics

Basic knowledge of quantum mechanics, at the level of the quantum mechanics taught to computational scientists, should be sufficient to follow the course. If you feel lost at any point, please ask the lecturer to explain whatever you do not understand. We want you to be able to follow this course without taking an advanced quantum mechanics class. However, immediately contact the lecturer if you feel that the material of the first week is too advanced.

### 1.1.3 References

1. J.M. Thijssen, Computational Physics, Cambridge University Press (1999) ISBN 0521575885
2. Nicholas J. Giordano, Computational Physics, Pearson Education (1996) ISBN 0133677230.
3. Harvey Gould and Jan Tobochnik, An Introduction to Computer Simulation Methods, 2nd edition, Addison Wesley (1996), ISBN 00201506041
4. Tao Pang, An Introduction to Computational Physics, Cambridge University Press (1997) ISBN 0521485924

### 1.2 Overview

In this class we will learn how to simulate quantum systems, starting from the simple one-dimensional Schrödinger equation to simulations of interacting quantum many body problems in condensed matter physics and in quantum field theories. In particular we will study

- The one-body Schrödinger equation and its numerical solution
- The many-body Schrödinger equation and second quantization
- Approximate solutions to the many body Schrödinger equation
- Path integrals and quantum Monte Carlo simulations
- Numerically exact solutions to (some) many body quantum problems
- Quantum algorithms and emulation of quantum computers
- Some simple quantum field theories


## Chapter 2

## Quantum mechanics in one hour

### 2.1 Introduction

The purpose of this chapter is to refresh your knowledge of quantum mechanics and to establish notation. Depending on your background you might not be familiar with all the material presented here. If that is the case, please ask the lecturers and we will expand the introduction. Those students who are familiar with advanced quantum mechanics are asked to glance over some omissions.

### 2.2 Basis of quantum mechanics

### 2.2.1 Wave functions and Hilbert spaces

Quantum mechanics is nothing but simple linear algebra, albeit in huge Hilbert spaces, which makes the problem hard. The foundations are pretty simple though.

A pure state of a quantum system is described by a "wave function" $|\Psi\rangle$, which is an element of a Hilbert space $\mathcal{H}$ :

$$
\begin{equation*}
|\Psi\rangle \in \mathcal{H} \tag{2.1}
\end{equation*}
$$

Usually the wave functions are normalized:

$$
\begin{equation*}
\||\Psi\rangle \|=\sqrt{\langle\Psi \mid \Psi\rangle}=1 \tag{2.2}
\end{equation*}
$$

Here the "bra-ket" notation

$$
\begin{equation*}
\langle\Phi \mid \Psi\rangle \tag{2.3}
\end{equation*}
$$

denotes the scalar product of the two wave functions $|\Phi\rangle$ and $|\Psi\rangle$.
The simplest example is the spin- $1 / 2$ system, describing e.g. the two spin states of an electron. Classically the spin $\vec{S}$ of the electron (which can be visualized as an internal angular momentum), can point in any direction. In quantum mechanics it is described by a two-dimensional complex Hilbert space $\mathcal{H}=\mathbb{C}^{2}$. A common choice of
basis vectors are the "up" and "down" spin states

$$
\begin{align*}
& |\uparrow\rangle=\binom{1}{0}  \tag{2.4}\\
& |\downarrow\rangle=\binom{0}{1} \tag{2.5}
\end{align*}
$$

This is similar to the classical Ising model, but in contrast to a classical Ising spin that can point only either up or down, the quantum spin can exist in any complex superposition

$$
\begin{equation*}
|\Psi\rangle=\alpha|\uparrow\rangle+\beta|\downarrow\rangle \tag{2.6}
\end{equation*}
$$

of the basis states, where the normalization condition (2.2) requires that $|\alpha|^{2}+|\beta|^{2}=1$.
For example, as we will see below the state

$$
\begin{equation*}
|\rightarrow\rangle=\frac{1}{\sqrt{2}}(|\uparrow\rangle+|\downarrow\rangle) \tag{2.7}
\end{equation*}
$$

is a superposition that describes the spin pointing in the positive $x$-direction.

### 2.2.2 Mixed states and density matrices

Unless specifically prepared in a pure state in an experiment, quantum systems in Nature rarely exist as pure states but instead as probabilistic superpositions. The most general state of a quantum system is then described as a density matrix $\rho$, with unit trace

$$
\begin{equation*}
\operatorname{Tr} \rho=1 \tag{2.8}
\end{equation*}
$$

The density matrix of a pure state is just the projector onto that state

$$
\begin{equation*}
\rho_{\text {pure }}=|\Psi\rangle\langle\Psi| . \tag{2.9}
\end{equation*}
$$

For example, the density matrix of a spin pointing in the positive $x$-direction is

$$
\rho_{\rightarrow}=|\rightarrow\rangle\langle\rightarrow|=\left(\begin{array}{ll}
1 / 2 & 1 / 2  \tag{2.10}\\
1 / 2 & 1 / 2
\end{array}\right) .
$$

Instead of being in a coherent superposition of up and down, the system could also be in a probabilistic mixed state, with a $50 \%$ probability of pointing up and a $50 \%$ probability of pointing down, which would be described by the density matrix

$$
\rho_{\text {mixed }}=\left(\begin{array}{cc}
1 / 2 & 0  \tag{2.11}\\
0 & 1 / 2
\end{array}\right) .
$$

### 2.2.3 Observables

Any physical observable is represented by a self-adjoint linear operator acting on the Hilbert space, which in a final dimensional Hilbert space can be represented by a Hermitian matrix. For our spin- $1 / 2$ system, using the basis introduced above, the components
$S^{x}, S^{y}$ and $S^{z}$ of the spin in the $x$-, $y$-, and $z$-directions are represented by the Pauli matrices

$$
\begin{align*}
S^{x} & =\frac{\hbar}{2} \sigma_{x}=\frac{\hbar}{2}\left(\begin{array}{ll}
0 & 1 \\
1 & 0
\end{array}\right)  \tag{2.12}\\
S^{y} & =\frac{\hbar}{2} \sigma_{y}=\frac{\hbar}{2}\left(\begin{array}{cc}
0 & -i \\
i & 0
\end{array}\right)  \tag{2.13}\\
S^{z} & =\frac{\hbar}{2} \sigma_{z}=\frac{\hbar}{2}\left(\begin{array}{cc}
1 & 0 \\
0 & -1
\end{array}\right) \tag{2.14}
\end{align*}
$$

The spin component along an arbitrary unit vector $\hat{e}$ is the linear superposition of the components, i.e.

$$
\hat{e} \cdot \vec{S}=e^{x} S^{x}+e^{y} S^{y}+e^{z} S^{z}=\frac{\hbar}{2}\left(\begin{array}{cc}
e^{z} & e^{x}-i e^{y}  \tag{2.15}\\
e^{x}+i e^{y} & -e^{z}
\end{array}\right)
$$

The fact that these observables do not commute but instead satisfy the non-trivial commutation relations

$$
\begin{align*}
{\left[S^{x}, S^{y}\right] } & =S^{x} S^{y}-S^{y} S^{x}=i \hbar S^{z}  \tag{2.16}\\
{\left[S^{y}, S^{z}\right] } & =i \hbar S^{x}  \tag{2.17}\\
{\left[S^{z}, S^{x}\right] } & =i \hbar S^{y} \tag{2.18}
\end{align*}
$$

is the root of the differences between classical and quantum mechanics .

### 2.2.4 The measurement process

The outcome of a measurement in a quantum system is usually intrusive and not deterministic. After measuring an observable $A$, the new wave function of the system will be an eigenvector of $A$ and the outcome of the measurement the corresponding eigenvalue. The state of the system is thus changed by the measurement process!

For example, if we start with a spin pointing up with wave function

$$
\begin{equation*}
|\Psi\rangle=|\uparrow\rangle=\binom{1}{0} \tag{2.19}
\end{equation*}
$$

or alternatively density matrix

$$
\rho_{\uparrow}=\left(\begin{array}{ll}
1 & 0  \tag{2.20}\\
0 & 0
\end{array}\right)
$$

and we measure the $x$-component of the spin $S^{x}$, the resulting measurement will be either $+\hbar / 2$ or $-\hbar / 2$, depending on whether the spin after the measurement points in the + or $-x$-direction, and the wave function after the measurement will be either of

$$
\begin{align*}
& |\rightarrow\rangle=\frac{1}{\sqrt{2}}(|\uparrow\rangle+|\downarrow\rangle)=\binom{1 / \sqrt{2}}{1 / \sqrt{2}}  \tag{2.21}\\
& |\leftarrow\rangle=\frac{1}{\sqrt{2}}(|\uparrow\rangle-|\downarrow\rangle)=\binom{1 / \sqrt{2}}{-1 / \sqrt{2}} \tag{2.22}
\end{align*}
$$

Either of these states will be picked with a probability given by the overlap of the initial wave function by the individual eigenstates:

$$
\begin{align*}
& p_{\rightarrow}=\|\langle\rightarrow \mid \Psi\rangle\|^{2}=1 / 2  \tag{2.23}\\
& p_{\leftarrow}=\|\langle\leftarrow \mid \Psi\rangle\|^{2}=1 / 2 \tag{2.24}
\end{align*}
$$

The final state is a probabilistic superposition of these two outcomes, described by the density matrix

$$
\rho=p_{\rightarrow}|\rightarrow\rangle\langle\rightarrow|+p_{\leftarrow}|\leftarrow\rangle\langle\leftarrow|=\left(\begin{array}{cc}
1 / 2 & 0  \tag{2.25}\\
0 & 1 / 2
\end{array}\right) .
$$

which differs from the initial density matrix $\rho_{\uparrow}$.
If we are not interested in the result of a particular outcome, but just in the average, the expectation value of the measurement can easily be calculated from a wave function $|\Psi\rangle$ as

$$
\begin{equation*}
\langle A\rangle=\langle\Psi| A|\Psi\rangle \tag{2.26}
\end{equation*}
$$

or from a density matrix $\rho$ as

$$
\begin{equation*}
\langle A\rangle=\operatorname{Tr}(\rho A) \tag{2.27}
\end{equation*}
$$

For pure states with density matrix $\rho_{\Psi}=|\Psi\rangle\langle\Psi|$ the two formulations are identical:

$$
\begin{equation*}
\operatorname{Tr}\left(\rho_{0} A\right)=\operatorname{Tr}(|\Psi\rangle\langle\Psi| A)=\langle\Psi| A|\Psi\rangle . \tag{2.28}
\end{equation*}
$$

### 2.2.5 The uncertainty relation

If two observables $A$ and $B$ do not commute $[A, B] \neq 0$, they cannot be measured simultaneously. If $A$ is measured first, the wave function is changed to an eigenstate of $A$, which changes the result of a subsequent measurement of $B$. As a consequence the values of $A$ and $B$ in a state $\Psi$ cannot be simultaneously known, which is quantified by the famous Heisenberg uncertainty relation which states that if two observables $A$ and $B$ do not commute but satisfy

$$
\begin{equation*}
[A, B]=i \hbar \tag{2.29}
\end{equation*}
$$

then the product of the root-mean-square deviations $\Delta A$ and $\Delta B$ of simultaneous measurements of $A$ and $B$ has to be larger than

$$
\begin{equation*}
\Delta A \Delta B \geq \hbar / 2 \tag{2.30}
\end{equation*}
$$

For more details about the uncertainty relation, the measurement process or the interpretation of quantum mechanics we refer interested students to an advanced quantum mechanics class or text book.

### 2.2.6 The Schrödinger equation

## The time-dependent Schrödinger equation

After so much introduction the Schrödinger equation is very easy to present. The wave function $|\Psi\rangle$ of a quantum system evolves according to

$$
\begin{equation*}
i \hbar \frac{\partial}{\partial t}|\Psi(t)\rangle=H|\Psi(t)\rangle \tag{2.31}
\end{equation*}
$$

where $H$ is the Hamilton operator. This is just a first order linear differential equation.

## The time-independent Schrödinger equation

For a stationary time-independent problem the Schrödinger equation can be simplified. Using the ansatz

$$
\begin{equation*}
|\Psi(t)\rangle=\exp (-i E t / \hbar)|\Psi\rangle \tag{2.32}
\end{equation*}
$$

where $E$ is the energy of the system, the Schrödinger equation simplifies to a linear eigenvalue problem

$$
\begin{equation*}
H|\Psi\rangle=E|\Psi\rangle \tag{2.33}
\end{equation*}
$$

The rest of the semester will be spent solving just this simple eigenvalue problem!

## The Schrödinger equation for the density matrix

The time evolution of a density matrix $\rho(t)$ can be derived from the time evolution of pure states, and can be written as

$$
\begin{equation*}
i \hbar \frac{\partial}{\partial t} \rho(t)=[H, \rho(t)] \tag{2.34}
\end{equation*}
$$

The proof is left as a simple exercise.

### 2.2.7 The thermal density matrix

Finally we want to describe a physical system not in the ground state but in thermal equilibrium at a given inverse temperature $\beta=1 / k_{B} T$. In a classical system each microstate $i$ of energy $E_{i}$ is occupied with a probability given by the Boltzman distribution

$$
\begin{equation*}
p_{i}=\frac{1}{Z} \exp \left(-\beta E_{i}\right), \tag{2.35}
\end{equation*}
$$

where the partition function

$$
\begin{equation*}
Z=\sum_{i} \exp \left(-\beta E_{i}\right) \tag{2.36}
\end{equation*}
$$

normalizes the probabilities.
In a quantum system, if we use a basis of eigenstates $|i\rangle$ with energy $E_{i}$, the density matrix can be written analogously as

$$
\begin{equation*}
\rho_{\beta}=\frac{1}{Z} \sum_{i} \exp \left(-\beta E_{i}\right)|i\rangle\langle i| \tag{2.37}
\end{equation*}
$$

For a general basis, which is not necessarily an eigenbasis of the Hamiltonian $H$, the density matrix can be obtained by diagonalizing the Hamiltonian, using above equation, and transforming back to the original basis. The resulting density matrix is

$$
\begin{equation*}
\rho_{\beta}=\frac{1}{Z} \exp (-\beta H) \tag{2.38}
\end{equation*}
$$

where the partition function now is

$$
\begin{equation*}
Z=\operatorname{Tr} \exp (-\beta H) \tag{2.39}
\end{equation*}
$$

Calculating the thermal average of an observable $A$ in a quantum system is hence formally very easy:

$$
\begin{equation*}
\langle A\rangle=\operatorname{Tr}\left(A \rho_{\beta}\right)=\frac{\operatorname{Tr} A \exp (-\beta H)}{\operatorname{Tr} \exp (-\beta H)} \tag{2.40}
\end{equation*}
$$

but actually evaluating this expression is a hard problem.

### 2.3 The spin- $S$ problem

Before discussing solutions of the Schrödinger equation we will review two very simple systems: a localized particle with general spin $S$ and a free quantum particle.

In section 2.2.1 we have already seen the Hilbert space and the spin operators for the most common case of a spin- $1 / 2$ particle. The algebra of the spin operators given by the commutation relations (2.12)-(2.12) allows not only the two-dimensional representation shown there, but a series of $2 S+1$-dimensional representations in the Hilbert space $\mathbb{C}^{2 S+1}$ for all integer and half-integer values $S=0, \frac{1}{2}, 1, \frac{3}{2}, 2, \ldots$. The basis states $\{|s\rangle\}$ are usually chosen as eigenstates of the $S^{z}$ operator

$$
\begin{equation*}
S^{z}|s\rangle=\hbar s|s\rangle \tag{2.41}
\end{equation*}
$$

where $s$ can take any value in the range $-S,-S+1,-S+2, \ldots, S-1, S$. In this basis the $S_{z}$ operator is diagonal, and the $S^{x}$ and $S^{y}$ operators can be constructed from the "ladder operators"

$$
\begin{align*}
S^{+}|s\rangle & =\sqrt{S(S+1)-s(s+1)}|s+1\rangle  \tag{2.42}\\
S^{-}|s\rangle & =\sqrt{S(S+1)-s(s-1)}|s-1\rangle \tag{2.43}
\end{align*}
$$

which increment or decrement the $S^{z}$ value by 1 through

$$
\begin{align*}
S^{x} & =\frac{1}{2}\left(S^{+}+S^{-}\right)  \tag{2.44}\\
S^{y} & =\frac{1}{2 i}\left(S^{+}-S^{-}\right) \tag{2.45}
\end{align*}
$$

The Hamiltonian of the spin coupled to a magnetic field $\vec{h}$ is

$$
\begin{equation*}
H=-g \mu_{B} \vec{h} \cdot \vec{S} \tag{2.46}
\end{equation*}
$$

which introduces nontrivial dynamics since the components of $\vec{S}$ do not commute. As a consequence the spin precesses around the magnetic field direction.

Exercise: Derive the differential equation governing the rotation of a spin starting along the $+x$-direction rotating under a field in the $+z$-direction

### 2.4 A quantum particle in free space

Our second example is a single quantum particle in an $n$-dimensional free space. Its Hilbert space is given by all twice-continuously differentiable complex functions over
the real space $\mathbb{R}^{n}$. The wave functions $|\Psi\rangle$ are complex-valued functions $\Psi(\vec{x})$ in $n$ dimensional space. In this representation the operator $\hat{x}$, measuring the position of the particle is simple and diagonal

$$
\begin{equation*}
\hat{x}=\vec{x}, \tag{2.47}
\end{equation*}
$$

while the momentum operator $\hat{p}$ becomes a differential operator

$$
\begin{equation*}
\hat{p}=-i \hbar \nabla \tag{2.48}
\end{equation*}
$$

These two operators do not commute but their commutator is

$$
\begin{equation*}
[\hat{x}, \hat{p}]=i \hbar \tag{2.49}
\end{equation*}
$$

The Schrödinger equation of a quantum particle in an external potential $V(\vec{x})$ can be obtained from the classical Hamilton function by replacing the momentum and position variables by the operators above. Instead of the classical Hamilton function

$$
\begin{equation*}
H(\vec{x}, \vec{p})=\frac{\vec{p}^{2}}{2 m}+V(\vec{x}) \tag{2.50}
\end{equation*}
$$

we use the quantum mechanical Hamiltonian operator

$$
\begin{equation*}
H=\frac{\hat{p}^{2}}{2 m}+V(\hat{x})=-\frac{\hbar^{2}}{2 m} \nabla^{2}+V(\vec{x}), \tag{2.51}
\end{equation*}
$$

which gives the famous form

$$
\begin{equation*}
i \hbar \frac{\partial \psi}{\partial t}=-\frac{\hbar^{2}}{2 m} \nabla^{2} \psi+V(\vec{x}) \psi \tag{2.52}
\end{equation*}
$$

of the one-body Schrödinger equation.

### 2.4.1 The harmonic oscillator

As a special exactly solvable case let us consider the one-dimensional quantum harmonic oscillator with mass $m$ and potential $\frac{K}{2} x^{2}$. Defining momentum $\hat{p}$ and position operators $\hat{q}$ in units where $m=\hbar=K=1$, the time-independent Schrödinger equation is given by

$$
\begin{equation*}
H|n\rangle=\frac{1}{2}\left(\hat{p}^{2}+\hat{q}^{2}\right)|n\rangle=E_{n}|n\rangle \tag{2.53}
\end{equation*}
$$

Inserting the definition of $\hat{p}$ we obtain an eigenvalue problem of an ordinary differential equation

$$
\begin{equation*}
-\frac{1}{2} \phi_{n}^{\prime \prime}(q)+\frac{1}{2} q^{2} \phi_{n}(q)=E_{n} \phi_{n}(q) \tag{2.54}
\end{equation*}
$$

whose eigenvalues $E_{n}=(n+1 / 2)$ and eigenfunctions

$$
\begin{equation*}
\phi_{n}(q)=\frac{1}{\sqrt{2^{n} n!\sqrt{\pi}}} \exp \left(-\frac{1}{2} q^{2}\right) H_{n}(q) \tag{2.55}
\end{equation*}
$$

are known analytically. Here the $H_{n}$ are the Hermite polynomials and $n=0,1, \ldots$.

Using these eigenstates as a basis sets we need to find the representation of $\hat{q}$ and $\hat{p}$. Performing the integrals

$$
\begin{equation*}
\langle m| \hat{q}|n\rangle \quad \text { and } \quad\langle m| \hat{p}|n\rangle \tag{2.56}
\end{equation*}
$$

it turns out that they are nonzero only for $m=n \pm 1$ and they can be written in terms of "ladder operators" $a$ and $a^{\dagger}$ :

$$
\begin{align*}
\hat{q} & =\frac{1}{\sqrt{2}}\left(a^{\dagger}+a\right)  \tag{2.57}\\
\hat{p} & =\frac{1}{i \sqrt{2}}\left(a^{\dagger}-a\right) \tag{2.58}
\end{align*}
$$

where the raising and lowering operators $a^{\dagger}$ and $a$ only have the following nonzero matrix elements:

$$
\begin{equation*}
\langle n+1| a^{\dagger}|n\rangle=\langle n| a|n+1\rangle=\sqrt{n+1} . \tag{2.60}
\end{equation*}
$$

and commutation relations

$$
\begin{gather*}
{[a, a]=\left[a^{\dagger}, a^{\dagger}\right]=0}  \tag{2.61}\\
{\left[a, a^{\dagger}\right]=1 .} \tag{2.62}
\end{gather*}
$$

It will also be useful to introduce the number operator $\hat{n}=a^{\dagger} a$ which is diagonal with eigenvalue $n$ : elements

$$
\begin{equation*}
\left.\hat{n}|n\rangle=a^{\dagger} a|n\rangle=\sqrt{n} a^{\dagger}|n-1\rangle=n \| n\right\rangle . \tag{2.63}
\end{equation*}
$$

To check this representation let us plug the definitions back into the Hamiltonian to obtain

$$
\begin{align*}
H & =\frac{1}{2}\left(\hat{p}^{2}+\hat{q}^{2}\right) \\
& =\frac{1}{4}\left[-\left(a^{\dagger}-a\right)^{2}+\left(a^{\dagger}+a\right)^{2}\right] \\
& =\frac{1}{2}\left(a^{\dagger} a+a a^{\dagger}\right) \\
& =\frac{1}{2}\left(2 a^{\dagger} a+1\right)=\hat{n}+\frac{1}{2}, \tag{2.64}
\end{align*}
$$

which has the correct spectrum. In deriving the last lines we have used the commutation relation (2.62).

## Chapter 3

## The quantum one-body problem

### 3.1 The time-independent 1D Schrödinger equation

We start the numerical solution of quantum problems with the time-indepent onedimensional Schrödinger equation for a particle with mass $m$ in a Potential $V(x)$. In one dimension the Schrödinger equation is just an ordinary differential equation

$$
\begin{equation*}
-\frac{\hbar^{2}}{2 m} \frac{\partial^{2} \psi(x)}{\partial x^{2}}+V(x) \psi(x)=E \psi(x) . \tag{3.1}
\end{equation*}
$$

We start with simple finite-difference schemes and discretize space into intervals of length $\Delta x$ and denote the space points by

$$
\begin{equation*}
x_{n}=n \Delta x \tag{3.2}
\end{equation*}
$$

and the wave function at these points by

$$
\begin{equation*}
\psi_{n}=\psi\left(x_{n}\right) \tag{3.3}
\end{equation*}
$$

### 3.1.1 The Numerov algorithm

After rewriting the second order differential equation to a coupled system of two first order differential equations, any ODE solver such as the Runge-Kutta method could be applied, but there exist better methods. For the special form

$$
\begin{equation*}
\psi^{\prime \prime}(x)+k(x) \psi(x)=0, \tag{3.4}
\end{equation*}
$$

of the Schrödinger equation, with $k(x)=2 m(E-V(x)) / \hbar^{2}$ we can derive the Numerov algorithm by starting from the Taylor expansion of $\psi_{n}$ :

$$
\begin{equation*}
\psi_{n \pm 1}=\psi_{n} \pm \Delta x \psi_{n}^{\prime}+\frac{\Delta x^{2}}{2} \psi_{n}^{\prime \prime} \pm \frac{\Delta x^{3}}{6} \psi_{n}^{(3)}+\frac{\Delta x^{4}}{24} \psi_{n}^{(4)} \pm \frac{\Delta x^{5}}{120} \psi_{n}^{(5)}+\mathrm{O}\left(\Delta x^{6}\right) \tag{3.5}
\end{equation*}
$$

Adding $\psi_{n+1}$ and $\psi_{n-1}$ we obtain

$$
\begin{equation*}
\psi_{n+1}+\psi_{n-1}=2 \psi_{n}+(\Delta x)^{2} \psi_{n}^{\prime \prime}+\frac{(\Delta x)^{4}}{12} \psi_{n}^{(4)} . \tag{3.6}
\end{equation*}
$$

Replacing the fourth derivatives by a finite difference second derivative of the second derivatives

$$
\begin{equation*}
\psi_{n}^{(4)}=\frac{\psi_{n+1}^{\prime \prime}+\psi_{n-1}^{\prime \prime}-2 \psi_{n}^{\prime \prime}}{\Delta x^{2}} \tag{3.7}
\end{equation*}
$$

and substituting $-k(x) \psi(x)$ for $\psi^{\prime \prime}(x)$ we obtain the Numerov algorithm

$$
\begin{align*}
\left(1+\frac{(\Delta x)^{2}}{12} k_{n+1}\right) \psi_{n+1}= & 2\left(1-\frac{5(\Delta x)^{2}}{12} k_{n}\right) \psi_{n} \\
& -\left(1+\frac{(\Delta x)^{2}}{12} k_{n-1}\right) \psi_{n-1}+\mathrm{O}\left(\Delta x^{6}\right) \tag{3.8}
\end{align*}
$$

which is locally of sixth order!

## Initial values

To start the Numerov algorithm we need the wave function not just at one but at two initial values and will now present several ways to obtain these.

For potentials $V(x)$ with reflection symmetry $V(x)=V(-x)$ the wave functions need to be either even $\psi(x)=\psi(-x)$ or odd $\psi(x)=-\psi(-x)$ under reflection, which can be used to find initial values:

- For the even solution we use a half-integer mesh with mesh points $x_{n+1 / 2}=$ $(n+1 / 2) \Delta x$ and pick initial values $\psi\left(x_{-1 / 2}\right)=\psi\left(x_{1 / 2}\right)=1$.
- For the odd solution we know that $\psi(0)=-\psi(0)$ and hence $\psi(0)=0$, specifying the first starting value. Using an integer mesh with mesh points $x_{n}=n \Delta x$ we pick $\psi\left(x_{1}\right)=1$ as the second starting value.

In general potentials we need to use other approaches. If the potentials vanishes for large distances: $V(x)=0$ for $|x| \geq a$ we can use the exact solution of the Schrödinger equation at large distances to define starting points, e.g.

$$
\begin{align*}
\psi(-a) & =1  \tag{3.9}\\
\psi(-a-\Delta x) & =\exp (-\Delta x \sqrt{2 m E} / \hbar) . \tag{3.10}
\end{align*}
$$

Finally, if the potential never vanishes we need to begin with a single starting value $\psi\left(x_{0}\right)$ and obtain the second starting value $\psi\left(x_{1}\right)$ by performing an integration over the first space step $\Delta x$ with an Euler or Runge-Kutta algorithm.

### 3.1.2 The one-dimensional scattering problem

The scattering problem is the numerically easiest quantum problem since solutions exist for all energies $E>0$, if the potential vanishes at large distances $(V(x) \rightarrow 0$ for $|x| \rightarrow \infty)$. The solution becomes particularly simple if the potential is nonzero only on a finite interval $[0, a]$. For a particle approaching the potential barrier from the left $(x<0)$ we can make the following ansatz for the free propagation when $x<0$ :

$$
\begin{equation*}
\psi_{L}(x)=A \exp (i q x)+B \exp (-i q x) \tag{3.11}
\end{equation*}
$$

where $A$ is the amplitude of the incoming wave and $B$ the amplitude of the reflected wave. On the right hand side, once the particle has left the region of finite potential $(x>a)$, we can again make a free propagation ansatz,

$$
\begin{equation*}
\psi_{R}(x)=C \exp (i q x) \tag{3.12}
\end{equation*}
$$

The coefficients $A, B$ and $C$ have to be determined self-consistently by matching to a numerical solution of the Schrödinger equation in the interval $[0, a]$. This is best done in the following way:

- Set $C=1$ and use the two points $a$ and $a+\Delta x$ as starting points for a Numerov integration.
- Integrate the Schrödinger equation numerically - backwards in space, from $a$ to 0 - using the Numerov algorithm.
- Match the numerical solution of the Schrödinger equation for $x<0$ to the free propagation ansatz (3.11) to determine $A$ and $B$.

Once $A$ and $B$ have been determined the reflection and transmission probabilities $R$ and $T$ are given by

$$
\begin{align*}
R & =|B|^{2} /|A|^{2}  \tag{3.13}\\
T & =1 /|A|^{2} \tag{3.14}
\end{align*}
$$

### 3.1.3 Bound states and solution of the eigenvalue problem

While there exist scattering states for all energies $E>0$, bound states solutions of the Schrödinger equation with $E<0$ exist only for discrete energy eigenvalues. Integrating the Schrödinger equation from $-\infty$ to $+\infty$ the solution will diverge to $\pm \infty$ as $x \rightarrow \infty$ for almost all values. These functions cannot be normalized and thus do not constitute solutions to the Schrödinger equation. Only for some special eigenvalues $E$, will the solution go to zero as $x \rightarrow \infty$.

A simple eigensolver can be implemented using the following shooting method, where we again will assume that the potential is zero outside an interval $[0, a]$ :

- Start with an initial guess $E$
- Integrate the Schrödinger equation for $\psi_{E}(x)$ from $x=0$ to $x_{f} \gg a$ and determine the value $\psi_{E}\left(x_{f}\right)$
- use a root solver, such as a bisection method (see appendix A.1), to look for an energy $E$ with $\psi_{E}\left(x_{f}\right) \approx 0$

This algorithm is not ideal since the divergence of the wave function for $x \pm \infty$ will cause roundoff error to proliferate.

A better solution is to integrate the Schrödinger equation from both sides towards the center:

- We pick a starting point $b$ and choose as energy $E=V(b)$
- Starting from $x=0$ we integrate the left hand side solution $\psi_{L}(x)$ to a chosen point $b$ and obtain $\psi_{L}(b)$ and a numerical estimate for $\psi_{L}^{\prime}(b)=\left(\psi_{L}(b)-\psi_{L}(b-\Delta x)\right) / \Delta x$.
- Starting from $x=a$ we integrate the right hand solution $\psi_{R}(x)$ down to the same point $b$ and obtain $\psi_{R}(b)$ and a numerical estimate for $\psi_{R}^{\prime}(b)=\left(\psi_{R}(b+\Delta x)-\right.$ $\left.\psi_{R}(b)\right) / \Delta x$.
- At the point $b$ the wave functions and their first two derivatives have to match, since solutions to the Schrödinger equation have to be twice continuously differentiable. Keeping in mind that we can multiply the wave functions by an arbitrary factor we obtain the conditions

$$
\begin{align*}
\psi_{L}(b) & =\alpha \psi_{R}(b)  \tag{3.15}\\
\psi_{L}^{\prime}(b) & =\alpha \psi_{R}^{\prime}(b)  \tag{3.16}\\
\psi_{L}^{\prime \prime}(b) & =\alpha \psi_{R}^{\prime \prime}(b) \tag{3.17}
\end{align*}
$$

The last condition is automatically fulfilled since by the choice $V(b)=E$ the Schrödinger equation at $b$ reduces to $\psi^{\prime \prime}(b)=0$. The first two conditions can be combined to the condition that the logarithmic derivatives vanish:

$$
\begin{equation*}
\left.\frac{d \log \psi_{L}}{d x}\right|_{x=b}=\frac{\psi_{L}^{\prime}(b)}{\psi_{L}(b)}=\frac{\psi_{R}^{\prime}(b)}{\psi_{R}(b)}=\left.\frac{d \log \psi_{R}}{d x}\right|_{x=b} \tag{3.18}
\end{equation*}
$$

- This last equation has to be solved for in a shooting method, e.g. using a bisection algorithm

Finally, at the end of the calculation, normalize the wave function.

### 3.2 The time-independent Schrödinger equation in higher dimensions

The time independent Schrödinger equation in more than one dimension is a partial differential equation and cannot, in general, be solved by a simple ODE solver such as the Numerov algorithm. Before employing a PDE solver we should thus always first try to reduce the problem to a one-dimensional problem. This can be done if the problem factorizes.

### 3.2.1 Factorization along coordinate axis

A first example is a three-dimensional Schrödinger equation in a cubic box with potential $V(\vec{r})=V(x) V(y) V(z)$ with $\vec{r}=(x, y, z)$. Using the product ansatz

$$
\begin{equation*}
\psi(\vec{r})=\psi_{x}(x) \psi_{y}(y) \psi_{z}(z) \tag{3.19}
\end{equation*}
$$

the PDE factorizes into three ODEs which can be solved as above.

### 3.2.2 Potential with spherical symmetry

Another famous trick is possible for spherically symmetric potentials with $V(\vec{r})=V(|\vec{r}|)$ where an ansatz using spherical harmonics

$$
\begin{equation*}
\psi_{l, m}(\vec{r})=\psi_{l, m}(r, \theta, \phi)=\frac{u(r)}{r} Y_{l m}(\theta, \phi) \tag{3.20}
\end{equation*}
$$

can be used to reduce the three-dimensional Schrödinger equation to a one-dimensional one for the radial wave function $u(r)$ :

$$
\begin{equation*}
\left[-\frac{\hbar^{2}}{2 m} \frac{d^{2}}{d r^{2}}+\frac{\hbar^{2} l(l+1)}{2 m r^{2}}+V(r)\right] u(r)=E u(r) \tag{3.21}
\end{equation*}
$$

in the interval $[0, \infty[$. Given the singular character of the potential for $r \rightarrow 0$, a numerical integration should start at large distances $r$ and integrate towards $r=0$, so that the largest errors are accumulated only at the last steps of the integration.

In the exercises we will solve a three-dimensional scattering problem and calculate the scattering length for two atoms.

### 3.2.3 Finite difference methods

The simplest solvers for partial differential equations, the finite difference solvers can also be used for the Schrödinger equation. Replacing differentials by differences we convert the Schrödinger equation to a system of coupled linear equations. Starting from the three-dimensional Schrödinger equation (we set $\hbar=1$ from now on)

$$
\begin{equation*}
\nabla^{2} \psi(\vec{x})+2 m(E-V(\vec{x})) \psi(\vec{x})=0 \tag{3.22}
\end{equation*}
$$

we discretize space and obtain the system of linear equations

$$
\begin{align*}
& \frac{1}{\Delta x^{2}} {\left[\psi\left(x_{n+1}, y_{n}, z_{n}\right)+\psi\left(x_{n-1}, y_{n}, z_{n}\right)\right.} \\
&+\psi\left(x_{n}, y_{n+1}, z_{n}\right)+\psi\left(x_{n}, y_{n-1}, z_{n}\right)  \tag{3.23}\\
&\left.+\psi\left(x_{n}, y_{n}, z_{n+1}\right)+\psi\left(x_{n}, y_{n}, z_{n-1}\right)\right] \\
&+ {\left[2 m(E-V(\vec{x}))-\frac{6}{\Delta x^{2}}\right] \psi\left(x_{n}, y_{n}, z_{n}\right)=0 . }
\end{align*}
$$

For the scattering problem a linear equation solver can now be used to solve the system of equations. For small linear problems Mathematica can be used, or the dsysv function of the LAPACK library. For larger problems it is essential to realize that the matrices produced by the discretization of the Schrödinger equation are usually very sparse, meaning that only $\mathrm{O}(N)$ of the $N^{2}$ matrix elements are nonzero. For these sparse systems of equations, optimized iterative numerical algorithms exist ${ }^{1}$ and are implemented in numerical libraries such as in the ITL library. ${ }^{2}$

[^0]To calculate bound states, an eigenvalue problem has to be solved. For small problems, where the full matrix can be stored in memory, Mathematica or the dsyev eigensolver in the LAPACK library can be used. For bigger systems, sparse solvers such as the Lanczos algorithm (see appendix A.2) are best. Again there exist efficient implementations ${ }^{3}$ of iterative algorithms for sparse matrices. ${ }^{4}$

### 3.2.4 Variational solutions using a finite basis set

In the case of general potentials, or for more than two particles, it will not be possible to reduce the Schrödinger equation to a one-dimensional problem and we need to employ a PDE solver. One approach will again be to discretize the Schrödinger equation on a discrete mesh using a finite difference approximation. A better solution is to expand the wave functions in terms of a finite set of basis functions

$$
\begin{equation*}
|\phi\rangle=\sum_{i=1}^{N} a_{i}\left|u_{i}\right\rangle . \tag{3.24}
\end{equation*}
$$

To estimate the ground state energy we want to minimize the energy of the variational wave function

$$
\begin{equation*}
E^{*}=\frac{\langle\phi| H|\phi\rangle}{\langle\phi \mid \phi\rangle} . \tag{3.25}
\end{equation*}
$$

Keep in mind that, since we only chose a finite basis set $\left\{\left|u_{i}\right\rangle\right\}$ the variational estimate $E^{*}$ will always be larger than the true ground state energy $E_{0}$, but will converge towards $E_{0}$ as the size of the basis set is increased, e.g. by reducing the mesh size in a finite element basis.

To perform the minimization we denote by

$$
\begin{equation*}
H_{i j}=\left\langle u_{i}\right| H\left|u_{j}\right\rangle=\int d \vec{r} u_{i}(\vec{r})^{*}\left(-\frac{\hbar^{2}}{2 m} \nabla^{2}+V\right) u_{j}(\vec{r}) \tag{3.26}
\end{equation*}
$$

the matrix elements of the Hamilton operator $H$ and by

$$
\begin{equation*}
S_{i j}=\left\langle u_{i} \mid u_{j}\right\rangle=\int d \vec{r} u_{i}(\vec{r})^{*} u_{j}(\vec{r}) \tag{3.27}
\end{equation*}
$$

the overlap matrix. Note that for an orthogonal basis set, $S_{i j}$ is the identity matrix $\delta_{i j}$. Minimizing equation (3.25) we obtain a generalized eigenvalue problem

$$
\begin{equation*}
\sum_{j} H_{i j} a_{j}=E \sum_{k} S_{i k} a_{k} . \tag{3.28}
\end{equation*}
$$

or in a compact notation with $\vec{a}=\left(a_{1}, \ldots, a_{N}\right)$

$$
\begin{equation*}
H \vec{a}=E S \vec{a} . \tag{3.29}
\end{equation*}
$$

[^1]If the basis set is orthogonal this reduces to an ordinary eigenvalue problem and we can use the Lanczos algorithm.

In the general case we have to find orthogonal matrices $U$ such that $U^{T} S U$ is the identity matrix. Introducing a new vector $\vec{b}=U^{-1} \vec{a}$. we can then rearrange the problem into

$$
\begin{align*}
H \vec{a} & =E S \vec{a} \\
H U \vec{b} & =E S U \vec{b} \\
U^{T} H U \vec{b} & =E U^{T} S U \vec{b}=E \vec{b} \tag{3.30}
\end{align*}
$$

and we end up with a standard eigenvalue problem for $U^{T} H U$. Mathematica and LAPACK both contain eigensolvers for such generalized eigenvalue problems.

## Example: the anharmonic oscillator

The final issue is the choice of basis functions. It is advantageous to make use of known solutions to a similar problem as we will illustrate in the case of an anharmonic oscillator with Hamilton operator

$$
\begin{align*}
H & =H_{0}+\lambda q^{4} \\
H_{0} & =\frac{1}{2}\left(p^{2}+q^{2}\right), \tag{3.31}
\end{align*}
$$

where the harmonic oscillator $H_{0}$ was already discussed in section 2.4.1. It makes sense to use the $N$ lowest harmonic oscillator eigenvectors $|n\rangle$ as basis states of a finite basis and write the Hamiltonian as

$$
\begin{equation*}
H=\frac{1}{2}+\hat{n}+\lambda \hat{q}^{4}=\frac{1}{2}+\hat{n}+\frac{\lambda}{4}\left(a^{\dagger}+a\right)^{4} \tag{3.32}
\end{equation*}
$$

Since the operators $a$ and $a^{\dagger}$ are nonzero only in the first sub or superdiagonal, the resulting matrix is a banded matrix of bandwidth 9 . A sparse eigensolver such as the Lanczos algorithm can again be used to calculate the spectrum. Note that since we use the orthonormal eigenstates of $H_{0}$ as basis elements, the overlap matrix $S$ here is the identity matrix and we have to deal only with a standard eigenvalue problem.

## The finite element method

In cases where we have irregular geometries or want higher precision than the lowest order finite difference method, and do not know a suitable set of basis function, the finite element method (FEM) should be chosen over the finite difference method. Since explaining the FEM can take a full semester in itself, we refer interested students to classes on solving partial differential equations.

### 3.3 The time-dependent Schrödinger equation

Finally we will reintroduce the time dependence to study dynamics in non-stationary quantum systems.

### 3.3.1 Spectral methods

By introducing a basis and solving for the complete spectrum of energy eigenstates we can directly solve the time-dependent problem in the case of a stationary Hamiltonian. This is a consequence of the linearity of the Schrödinger equation.

To calculate the time evolution of a state $\left|\psi\left(t_{0}\right)\right\rangle$ from time $t_{0}$ to $t$ we first solve the stationary eigenvalue problem $H|\phi\rangle=E|\phi\rangle$ and calculate the eigenvectors $\left|\phi_{n}\right\rangle$ and eigenvalues $\epsilon_{n}$. Next we represent the initial wave function $|\psi\rangle$ by a spectral decomposition

$$
\begin{equation*}
\left|\psi\left(t_{0}\right)\right\rangle=\sum_{n} c_{n}\left|\phi_{n}\right\rangle . \tag{3.33}
\end{equation*}
$$

Since each of the $\left|\phi_{n}\right\rangle$ is an eigenvector of $H$, the time evolution $e^{-i H\left(t-t_{0}\right) / \hbar}$ is trivial and we obtain at time $t$ :

$$
\begin{equation*}
|\psi(t)\rangle=\sum_{n} c_{n} e^{-i \epsilon_{n}\left(t-t_{0}\right) / \hbar}\left|\phi_{n}\right\rangle . \tag{3.34}
\end{equation*}
$$

This approach is, however, only useful for very small problems since the effort of diagonalizing the matrix is huge. A better method is direct numerical integration, discussed in the next two subsections.

### 3.3.2 Direct numerical integration

If the number of basis states is too large to perform a complete diagonalization of the Hamiltonian, or if the Hamiltonian changes over time we need to perform a direct integration of the Schrödinger equation. Like other initial value problems of partial differential equations the Schrödinger equation can be solved by the method of lines. After choosing a set of basis functions or discretizing the spatial derivatives we obtain a set of coupled ordinary differential equations which can be evolved for each point along the time line (hence the name) by standard ODE solvers.

In the remainder of this chapter we use the symbol $H$ to refer the representation of the Hamiltonian in the chosen finite basis set. A forward Euler scheme

$$
\begin{equation*}
\left|\psi\left(t_{n+1}\right)\right\rangle=\left|\psi\left(t_{n}\right)\right\rangle-\frac{i \Delta_{t}}{\hbar} H\left|\psi\left(t_{n}\right)\right\rangle \tag{3.35}
\end{equation*}
$$

is not only numerically unstable. It also violates the conservation of the norm of the wave function $\langle\psi \mid \psi\rangle=1$. Since the exact quantum evolution

$$
\begin{equation*}
\psi\left(x, t+\Delta_{t}\right)=e^{-i H \Delta_{t} / \hbar} \psi(x, t) . \tag{3.36}
\end{equation*}
$$

is unitary and thus conserves the norm, we want to look for a unitary approximant as integrator. Instead of using the forward Euler method (3.35) which is just a first order Taylor expansion of the exact time evolution

$$
\begin{equation*}
e^{-i H \Delta_{t} / \hbar}=1-\frac{i \Delta_{t}}{\hbar} H+\mathrm{O}\left(\Delta_{t}^{2}\right) \tag{3.37}
\end{equation*}
$$

we reformulate the time evolution operator as

$$
\begin{equation*}
e^{-i H \Delta_{t} / \hbar}=\left(e^{i H \Delta_{t} / 2 \hbar}\right)^{-1} e^{-i H \Delta_{t} / 2 \hbar}=\left(1+\frac{i \Delta_{t}}{2 \hbar} H\right)^{-1}\left(1-\frac{i \Delta_{t}}{2 \hbar} H\right)+\mathrm{O}\left(\Delta_{t}^{3}\right), \tag{3.38}
\end{equation*}
$$

which is unitary!
This gives the simplest stable and unitary integrator algorithm

$$
\begin{equation*}
\psi\left(x, t+\Delta_{t}\right)=\left(1+\frac{i \Delta_{t}}{2 \hbar} H\right)^{-1}\left(1-\frac{i \Delta_{t}}{2 \hbar} H\right) \psi(x, t) \tag{3.39}
\end{equation*}
$$

or equivalently

$$
\begin{equation*}
\left(1+\frac{i \Delta_{t}}{2 \hbar} H\right) \psi\left(x, t+\Delta_{t}\right)=\left(1-\frac{i \Delta_{t}}{2 \hbar}\right) \psi(x, t) . \tag{3.40}
\end{equation*}
$$

Unfortunately this is an implicit integrator. At each time step, after evaluating the right hand side a linear system of equations needs to be solved. For one-dimensional problems the matrix representation of $H$ is often tridiagonal and a tridiagonal solver can be used. In higher dimensions the matrix $H$ will no longer be simply tridiagonal but still very sparse and we can use iterative algorithms, similar to the Lanczos algorithm for the eigenvalue problem. For details about these algorithms we refer to the nice summary at http://mathworld.wolfram.com/topics/Templates.html and especially the biconjugate gradient ( BiCG ) algorithm. Implementations of this algorithm are available, e.g. in the Iterative Template Library (ITL).

### 3.3.3 The split operator method

A simpler and explicit method is possible for a quantum particle in the real space picture with the "standard" Schrödinger equation (2.52). Writing the Hamilton operator as

$$
\begin{equation*}
H=\hat{T}+\hat{V} \tag{3.41}
\end{equation*}
$$

with

$$
\begin{align*}
\hat{T} & =\frac{1}{2 m} \hat{p}^{2}  \tag{3.42}\\
\hat{V} & =V(\vec{x}) \tag{3.43}
\end{align*}
$$

it is easy to see that $\hat{V}$ is diagonal in position space while $\hat{T}$ is diagonal in momentum space. If we split the time evolution as

$$
\begin{equation*}
e^{-i \Delta_{t} H / \hbar}=e^{-i \Delta_{t} \hat{V} / 2 \hbar} e^{-i \Delta_{t} \hat{T} / \hbar} e^{-i \Delta_{t} \hat{V} / 2 \hbar}+\mathrm{O}\left(\Delta_{t}^{3}\right) \tag{3.44}
\end{equation*}
$$

we can perform the individual time evolutions $e^{-i \Delta_{t} \hat{V} / 2 \hbar}$ and $e^{-i \Delta_{t} \hat{T} / \hbar}$ exactly:

$$
\begin{align*}
{\left[e^{-i \Delta_{t} \hat{V} / 2 \hbar}|\psi\rangle\right](\vec{x}) } & =e^{-i \Delta_{t} V(\vec{x}) / 2 \hbar} \psi(\vec{x})  \tag{3.45}\\
{\left[e^{-i \Delta_{t} \hat{T} / \hbar}|\psi\rangle\right](\vec{k}) } & =e^{-i \Delta_{t} \hbar \mid \vec{k} \|^{2} / 2 m} \psi(\vec{k}) \tag{3.46}
\end{align*}
$$

in real space for the first term and momentum space for the second term. This requires a basis change from real to momentum space, which is efficiently performed using a Fast Fourier Transform (FFT) algorithm. Propagating for a time $t=N \Delta_{t}$, two consecutive
applications of $e^{-i \Delta_{t} \hat{V} / 2 \hbar}$ can easily be combined into a propagation by a full time step $e^{-i \Delta_{t} \hat{V} / \hbar}$, resulting in the propagation:

$$
\begin{align*}
e^{-i H t / \hbar} & =\left(e^{-i \Delta_{t} \hat{V} / 2 \hbar} e^{-i \Delta_{t} \hat{T} / \hbar} e^{-i \Delta_{t} \hat{V} / 2 \hbar}\right)^{N}+\mathrm{O}\left(\Delta_{t}^{2}\right) \\
& =e^{-i \Delta_{t} \hat{V} / 2 \hbar}\left[e^{-i \Delta_{t} \hat{T} / \hbar} e^{-i \Delta_{t} \hat{V} / \hbar}\right]^{N-1} e^{-i \Delta_{t} \hat{T} / \hbar} e^{-i \Delta_{t} \hat{V} / 2 \hbar} \tag{3.47}
\end{align*}
$$

and the discretized algorithm starts as

$$
\begin{align*}
\psi_{1}(\vec{x}) & =e^{-i \Delta_{t} V(\vec{x}) / 2 \hbar} \psi_{0}(\vec{x})  \tag{3.48}\\
\psi_{1}(\vec{k}) & =\mathcal{F} \psi_{1}(\vec{x}) \tag{3.49}
\end{align*}
$$

where $\mathcal{F}$ denotes the Fourier transform and $\mathcal{F}^{-1}$ will denote the inverse Fourier transform. Next we propagate in time using full time steps:

$$
\begin{align*}
\psi_{2 n}(\vec{k}) & =e^{-i \Delta_{t} \hbar| | \vec{k} \|^{2} / 2 m} \psi_{2 n-1}(\vec{k})  \tag{3.50}\\
\psi_{2 n}(\vec{x}) & =\mathcal{F}^{-1} \psi_{2 n}(\vec{k})  \tag{3.51}\\
\psi_{2 n+1}(\vec{x}) & =e^{-i \Delta_{t} V(\vec{x}) / \hbar} \psi_{2 n}(\vec{x})  \tag{3.52}\\
\psi_{2 n+1}(\vec{k}) & =\mathcal{F} \psi_{2 n+1}(\vec{x}) \tag{3.53}
\end{align*}
$$

except that in the last step we finish with another half time step in real space:

$$
\begin{equation*}
\psi_{2 N+1}(\vec{x})=e^{-i \Delta_{t} V(\vec{x}) / 2 \hbar} \psi_{2 N}(\vec{x}) \tag{3.54}
\end{equation*}
$$

This is a fast and unitary integrator for the Schrödinger equation in real space. It could be improved by replacing the locally third order splitting (3.44) by a fifth-order version involving five instead of three terms.

## Chapter 4

## Exact diagonalization of quantum spin models

### 4.1 Quantum spin models

After learning how to solve the 1-body Schrödinger equation, let us next generalize to more particles. If a single body quantum problem is described by a Hilbert space $\mathcal{H}$ of dimension $\operatorname{dim} \mathcal{H}=d$ then $N$ distinguishable quantum particles are described by the tensor product of $N$ Hilbert spaces

$$
\begin{equation*}
\mathcal{H}^{(N)} \equiv \mathcal{H}^{\otimes N} \equiv \bigotimes_{i=1}^{N} \mathcal{H} \tag{4.1}
\end{equation*}
$$

with dimension $d^{N}$.
As a first example we will in this chapter learn about quantum spin- $1 / 2$ particles. A single spin- $1 / 2$ has a Hilbert space $\mathcal{H}=\mathbb{C}^{2}$ of dimension 2 , but $N$ spin- $1 / 2$ have a Hilbert space $\mathcal{H}^{(N)}=\mathbb{C}^{2^{N}}$ of dimension $2^{N}$. This exponential scaling of the Hilbert space dimension with the number of particles is a big challenge. The basis for $N=30$ spins is already of size $2^{30} \approx 10^{9}$. A single complex vector needs 16 GByte of memory and may just barely fit into the memory of your personal computer.

For small and moderately sized systems of up to about 30 spin- $1 / 2$ we can calculate the ground state, low-lying spectrum, and time evolution by direct calculations. To go to larger systems we will later learn about quantum Monte Carlo methods for bosonic and unfrustrated magnetic systems that allow millions of particles to be studied in some cases, and approximate methods for fermions that reduce the many-particle problem to a single-particle problem

### 4.1.1 The transverse field Ising model

The simplest quantum spin model is the quantum transverse field Ising model (TFIM), which adds a magnetic field in the $x$ direction to a lattice of spin- $1 / 2$ particles coupled by an Ising interaction:

$$
\begin{equation*}
H=\sum_{\langle i, j\rangle} J_{i j} \sigma_{i}^{z} \sigma_{j}^{z}-\Gamma \sum_{i} \sigma_{i}^{x} . \tag{4.2}
\end{equation*}
$$

Here the symbol $\langle i, j\rangle$ denotes a sum over all bonds in the lattice. In the absence of the second term, the first term is nothing but a classical Ising model and can be solved by your favorite method of simulating the Ising model. The second term does not exist in classical Ising models, where the spins point only in the $z$ direction. Considering that the Pauli $\sigma^{x}$ matrix is

$$
\sigma^{x}=\left(\begin{array}{ll}
0 & 1  \tag{4.3}\\
1 & 0
\end{array}\right)
$$

we see that this term flips an $\uparrow$ spin to a $\downarrow$ spin, and thus introduces quantum dynamics to the Ising model.

### 4.1.2 The quantum Heisenberg model

The quantum Heisenberg model may be viewed as the generalization of the classical Heisenberg model to quantum spins:

$$
\begin{align*}
H & =\sum_{\langle i, j\rangle} J_{i j} \vec{S}_{i} \vec{S}_{j}=\sum_{\langle i, j\rangle} J_{i j}\left[S_{i}^{x} S_{j}^{x}+S_{i}^{y} S_{j}^{y}+S_{i}^{z} S_{j}^{z}\right] \\
& =\sum_{\langle i, j\rangle} J_{i j}\left[\frac{1}{2}\left(S_{i}^{+} S_{j}^{-}+S_{i}^{-} S_{j}^{+}\right)+S_{i}^{z} S_{j}^{z}\right] \tag{4.4}
\end{align*}
$$

Looking at the three terms in the second line we see that none of them changes to total $z$ component of the magnetization $M^{z}=\sum_{i} S_{i}^{z}$. The first two terms flip one spin up, but at the same time flip another spin down thus keeping the total magnetization unchanged. The third (Ising) term just couples to the $z$-component of the spins without changing them. We will be able to use this magnetization conservation to reduce the dimension of the Hilbert space and solve larger spin systems.

Using a basis $\{|\uparrow \uparrow\rangle,|\uparrow \downarrow\rangle,|\downarrow \uparrow\rangle,|\downarrow \downarrow\rangle\}$ for two spins the matrix representation of one 2 -spin term is

$$
\left(\begin{array}{cccc}
J_{i j} / 4 & 0 & 0 & 0  \tag{4.5}\\
0 & -J_{i j} / 4 & J_{i j} / 2 & 0 \\
0 & J_{i j} / 2 & -J_{i j} / 4 & 0 \\
0 & 0 & 0 & J_{i j} / 4
\end{array}\right)
$$

The blockdiagonal form reflects the conservation of the total magnetization.
Actually, the quantum Heisenberg model is more fundamental than the classical one, which is just a classical approximation to the quantum model. We will later derive the Heisenberg model from an underlying fermionic model.

### 4.1.3 The quantum $X X Z$ model

Magnetic materials might not have the same coupling strength in all spin directions but often have a weaker or stronger coupling along one direction. This is captured by the
$X X Z$ model

$$
\begin{align*}
H & =\sum_{\langle i, j\rangle} J_{i j}^{x}\left(S_{i}^{x} S_{j}^{x}+S_{i}^{y} S_{j}^{y}\right)+J_{i j}^{z} S_{i}^{z} S_{j}^{z} \\
& =\sum_{\langle i, j\rangle} \frac{J_{i j}^{x}}{2}\left(S_{i}^{+} S_{j}^{-}+S_{i}^{-} S_{j}^{+}\right)+J_{i j}^{z} S_{i}^{z} S_{j}^{z} . \tag{4.6}
\end{align*}
$$

When $J_{i j}^{x}=0$ we recover the Ising model and for $J_{i j}^{z}=0$ the quantum-XY model.
In the same basis as in above subsection the matrix for a single 2 -spin term is

$$
\left(\begin{array}{cccc}
J_{i j}^{z} / 4 & 0 & 0 & 0  \tag{4.7}\\
0 & -J_{i j}^{z} / 4 & J_{i j}^{x} / 2 & 0 \\
0 & J_{i j}^{x} / 2 & -J_{i j}^{z} / 4 & 0 \\
0 & 0 & 0 & J_{i j}^{z} / 4
\end{array}\right)
$$

and once more the model conserves the total magnetization

### 4.2 Exact diagonalization

Exact diagonalization refers to solving a quantum model by using an iterative matrix eigensolver, such as the Lanczos algorithm discussed in Appendix A.2, to calculate the ground state and low lying excited states. After defining a suitable basis we have to compute the matrix representation of the model Hamiltonian.

Although the matrix it typically sparse, since we have at most $\mathcal{O}\left(N^{2}\right)$ terms in the Hamiltonian and thus only $\mathcal{O}\left(N^{2}\right)$ non-zero matrix elements per row and column, the memory requirements to store the sparse matrix are still a huge $\mathcal{O}\left(N^{2} 2^{N}\right)$. To maximize the system sizes that can be attained we thus want to minimize memory usage by not storing the matrix in memory at all, but just the three vectors required for the Lanczos recurrence relations. This is possible, since the Lanczos algorithm only requires the computation of matrix-vector products but not to store the full matrix. We will learn how to write code that performs an on-the-fly calculation of the matrix in the multiplication routine instead of storing it.

### 4.2.1 Exact diagonalization for the transverse field Ising model

The $2^{N}$ basis states of a quantum spin- $1 / 2$ transverse field Ising model can simply be represented as $N$-bit strings. Enumerating the $2^{N}$ configurations by the integers $0 \ldots 2^{N}-1$ the value of the $i$-th bit of an integer corresponds to the orientation of the $i$-th spin in that configuration: a value of 0 denoting an $\uparrow$ spin and value of $1 \mathrm{a} \downarrow$ spin. Spins can then be checked and manipulated by simple and fast bit operations.

In the exercise classes we will provide you with an exact diagonalization code for the transverse field Ising model. The core of such a code is a matrix-vector multiplication function that computes $|\phi\rangle=H|\psi\rangle$. A simplified version of the more general code handed out in the exercises is

```
template <class Vector>
void TFIM_multiply(const Vector& psi, Vector& phi,
                                    double J, double Gamma, int N)
{
    // compute dimension of Hilbert space
    typedef std::size_t state_t;
    state_t dimension = 1<<N;
    // check dimensions
    assert( psi.size() == dimension );
    assert( phi.size() == dimension );
    // Ising term:
    for( state_t s = 0; s < dimension; ++s ) {
        double jtotal = 0.;
        for( int r = 0; r < N - 1; ++r )
            // check if spins are parallel at site r and r+1
            jtotal += ((s >> r)^(s >> (r+1))) & 1 ? -J: +J;
        phi[s] = jtotal * psi[s];
    }
    // transverse field term:
    for( state_t s = 0; s < dimension; ++s ) {
        for( int r = 0; r < N; ++r ) {
            state_t sflip = s ^ (1<<r); // flip spin at site r.
            phi[sflip] -= Gamma*psi[s];
        }
    }
}
```

Using bit operations this is a very short piece of code.

### 4.2.2 Exact diagonalization for the quantum $X X Z$ and Heisenberg models

In the $X X Z$ and Heisenberg model conservation of the total magnetization allows us to restrict the diagonalization to a subspace of fixed magnetization. These states have a fixed number of $N / 2+M^{z}$ spin- $\uparrow$ and $N / 2-M^{z}$ spin- $\downarrow$. These states can hence be characterized by all $N$-bit bit strings that have $N / 2-M^{z}$ bits set to 1 . Our code now cannot just use the integers $0 \ldots 2^{N}-1$ to enumerate the states, but we can write a small class to map an index to the bit string of a state and back.

In the code fragment below we use the following variables:

- states_ is a vector storing the integers whose bit pattern correspond to the basis states. It can be accessed using the following functions:
- dimension() returns the number of basis states.
- state(i) returns the $i$-th basis state, where i runs from 0 to dimension()-1.
- index_ is a much larger vector of size $2^{N}$. It is used to obtain the number of a state in the basis, given the integer representation of the state. It can be accessed using the function
- index(s) which returns the index $i$ of the state in the basis, or the largest integer to denote an invalid state, if the bit pattern of the integer does not correspond to a basis state.

Since this vector is very large, it will limit the size of systems that can be studied. To save space, the index_ array could be omitted and the index(s) function implemented by a binary search on the states_ array.

Here is the $\mathrm{C}++$ code for this class:

```
class FixedMagnetizationBasis {
public:
    typedef unsigned int state_type;
    typedef unsigned int index_type;
    FixedMagnetizationBasis (int N, int Ndown);
    state_type state(index_type i) const {return states_[i];}
    index_type index(state_type s) const {return index_[s];}
    index_type dimension() const { return states_.size();}
private:
    std::vector<state_type> states_;
    std::vector<index_type> index_;
};
```

In the constructor we build the basis states. The constructor uses the alps : :popent function of the ALPS library.

```
    FixedMagnetizationBasis::FixedMagnetizationBasis (int N, int Ndown)
    : index_(1<<N); // 2^N entries
{
    for (state_type s=0;s<index_.size();++s)
    if(alps::popcnt(s)==Ndown) { // correct number of down-spins
            states_.push_back(s);
            index_[s]=states_.size()-1;
    }
    else
        // invalid state
        index_[s]=std::numeric_limits<index_type>::max();
}
```

In the exercises we will use this class to implement exact diagonalization for a Heisenberg model.

In production codes one uses as many symmetries as easily possible to reduce the dimension of the Hilbert space as much as possible. This may include translational symmetries and other point group symmetries. The implementation then gets much harder than in our exercise example.

In order to make the implementation of exact diagonalization much easier one can generalize the expression templates technique developed by Todd Veldhuizen for array expression expressions to including quantum operators. Using this expression template library we can write a multiplication

$$
\begin{equation*}
|\psi\rangle=H|\phi\rangle=\left(\frac{J}{2} \sum_{i=1}^{L-1}\left(S_{i}^{+} S_{i+1}^{-}+S_{i}^{-} S_{i+1}^{+}\right)+J \sum_{i}^{L-1} S_{i}^{z} S_{i+1}^{z}\right)|\phi\rangle \tag{4.8}
\end{equation*}
$$

simply as:
Range $i(1, L-1)$;
psi $=\operatorname{sum}(i,(0.5 * J *(S p l u s(i) * S m i n u s(i+1)+S m i n u s(i) * S p l u s(i+1))$ $+\mathrm{J} * \mathrm{Sz}(\mathrm{i}) * \mathrm{Sz}(\mathrm{i}+1)) * \mathrm{phi})$;

If one is not as demanding and wants to simulate a slightly smaller system, where the (sparse) matrix can be stored in memory, then a less efficient but more flexible function can be used to create the matrix and store it in memory. Such a program is available through the ALPS project at http://alps.comp-phys.org/. It allows to perform the above calculation just by describing the lattice and model in an XML input file.

### 4.3 Time evolution of quantum spin systems

### 4.3.1 The Trotter-Suzuki decomposition

To implement time evolution we have to calculate once more the matrix exponential $\exp (-i H t)$, and will use an idea similar to the split operator method. To do this we split the Hamiltonian into a sum of $K$ terms $H=\sum_{k=1}^{K} h_{k}$, which can easily be exponentiated and will once more use a Trotter-Suzuki decomposition. ${ }^{1}$

The time evolution operator $\exp \left(-i H \Delta_{t}\right)$ for a small time step $\Delta_{t}$ is decomposed into multiple products of the non-commuting terms in the Hamiltonian. To first order the Trotter-Suzuki decomposition for a small time step $\Delta_{t}$ is

$$
\begin{equation*}
\exp \left(-i H \Delta_{t}\right)=\prod_{k=1}^{K} e^{-i h_{k} \Delta_{t}}+\mathcal{O}\left(\Delta_{t}^{2}\right) \tag{4.9}
\end{equation*}
$$

[^2]The second order version reads

$$
\begin{equation*}
\exp \left(-i H \Delta_{t}\right)=S\left(\frac{\Delta_{t}}{2}\right)+\mathcal{O}\left(\Delta_{t}^{3}\right) \tag{4.10}
\end{equation*}
$$

where $S\left(\Delta_{t}\right)$ is defined as

$$
\begin{equation*}
S\left(\Delta_{t}\right) \equiv\left(\prod_{k=1}^{K} e^{-i h_{k} \Delta_{t}}\right)\left(\prod_{k=K}^{1} e^{-i h_{k} \Delta_{t}}\right) \tag{4.11}
\end{equation*}
$$

For $K=2$ terms this simplifies to

$$
\begin{equation*}
\exp \left(-i H \Delta_{t}\right)=e^{-i h_{1} \Delta_{t} / 2} e^{-i h_{2} \Delta_{t}} e^{-i h_{1} \Delta_{t} / 2} \tag{4.12}
\end{equation*}
$$

by combining the two terms $e^{-i h_{2} \Delta_{t} / 2} e^{-i h_{2} \Delta_{t} / 2}$ into $e^{-i h_{2} \Delta_{t}}$. Just like in the split operator method, by similarly combining the terms $e^{-i h_{1} \Delta_{t} / 2} e^{-i h_{1} \Delta_{t} / 2}$ arising from two adjacent time steps into $e^{-i h_{1} \Delta_{t}}$ one ultimately needs only a single additional term for the full time evolution.

Even smaller errors are obtained in a fourth order Trotter scheme:

$$
\begin{equation*}
\exp \left(-i H \Delta_{t}\right)=\prod_{j=1}^{5} S\left(p_{j} \frac{\Delta_{t}}{2}\right)+\mathcal{O}\left(\Delta_{t}^{5}\right) \tag{4.13}
\end{equation*}
$$

with $p_{1}=p_{2}=p_{4}=p_{5}=p=\frac{1}{4-4^{1 / 3}}$ and $p_{3}=1-4 p$. Once more combining terms this requires about five times more operations than the second order scheme, but allows much larger time steps to be used.

### 4.3.2 Time evolution for the transverse field Ising model

To implement time evolution in the transverse field Ising model we split the Hamiltonian into the Ising term

$$
\begin{equation*}
H^{z}=\sum_{\langle i, j\rangle} J_{i j} \sigma_{i}^{z} \sigma_{j}^{z} \tag{4.14}
\end{equation*}
$$

and the transverse field term

$$
\begin{equation*}
-\Gamma \sum_{i} \sigma_{i}^{x} \tag{4.15}
\end{equation*}
$$

Each of these terms can be easily exponentiated. Since the Ising term is diagonal the exponentiation is particularly simple and gives a diagonal matrix

$$
\begin{equation*}
e^{-i H^{z} \Delta_{t}}=e^{-i \Delta_{t} \sum_{\langle i, j\rangle} J_{i j} \sigma_{i}^{z} \sigma_{j}^{z}}=\prod_{\langle i, j\rangle} e^{-i \Delta_{t} J_{i j} \sigma_{i}^{z} \sigma_{j}^{z}}, \tag{4.16}
\end{equation*}
$$

which can easily be evaluated for each basis state.
The transverse field term splits into $N$ commuting terms for each of the spins:

$$
\begin{equation*}
e^{-i H^{x} \Delta_{t}}=e^{i \Delta_{t} \Gamma \sum_{i} \sigma_{i}^{x}}=\prod_{i} e^{i \Delta_{t} \Gamma \sigma_{i}^{x}} \tag{4.17}
\end{equation*}
$$

For a single spin the exponentiated matrix is just

$$
\sigma^{x}=\left(\begin{array}{cc}
\cos \left(\Delta_{t} \Gamma\right) & i \sin \left(\Delta_{t} \Gamma\right)  \tag{4.18}\\
i \sin \left(\Delta_{t} \Gamma\right) & \cos \left(\Delta_{t} \Gamma\right)
\end{array}\right) .
$$

Both terms can easily be applied on-the-fly to a wave function in a similar way as we did for the multiplication with the Hamiltonian $H$. We will implement time evolution for the TFIM in the exercises.

### 4.3.3 Time evolution for the $X X Z$ and Heisenberg models

A different strategy is needed for the $X X Z$ and Heisenberg models, which do not split as easily into commuting terms. Here one splits the bonds $\langle i, j\rangle$ into $K$ sets of disjoint bonds. In the case of a one-dimensional chain these are even and odd bonds:

$$
\begin{equation*}
H=H^{\text {even }}+H^{\text {odd }} \tag{4.19}
\end{equation*}
$$

where

$$
\begin{align*}
H^{\mathrm{even}} & =\sum_{i} \frac{J_{2 i, 2 i+1}^{x}}{2}\left(S_{2 i}^{+} S_{2 i+1}^{-}+S_{2 i}^{-} S_{2 i+1}^{+}\right)+J_{2 i, 2 i+1}^{z} S_{2 i}^{z} S_{2 i+1}^{z}  \tag{4.20}\\
H^{\mathrm{odd}} & =\sum_{i} \frac{J_{2 i-1,2 i}^{x}}{2}\left(S_{2 i-1}^{+} S_{2 i}^{-}+S_{2 i-1}^{-} S_{2 i}^{+}\right)+J_{2 i-1,2 i}^{z} S_{2 i-1}^{z} S_{2 i}^{z} . \tag{4.21}
\end{align*}
$$

Each of these terms now consists of a sum of commuting terms that can be exponentiated separately:

$$
\begin{equation*}
\exp \left(-i \Delta_{t} H^{\mathrm{even}}\right)=\prod_{i} \exp \left[-i \Delta_{t}\left(\frac{J_{2 i, 2 i+1}^{x}}{2}\left(S_{2 i}^{+} S_{2 i+1}^{-}+S_{2 i}^{-} S_{2 i+1}^{+}\right)+J_{2 i, 2 i+1}^{z} S_{2 i}^{z} S_{2 i+1}^{z}\right)\right] \tag{4.22}
\end{equation*}
$$

and similarly for $\exp \left(-i \Delta_{t} H^{\text {odd }}\right)$. The $4 \times 4$ matrices for the individual two-spin terms can easily be exponentiated and give

$$
e^{i \Delta_{t} J_{i j}^{z} / 4}\left(\begin{array}{cccc}
e^{-i \Delta_{t} J_{i j}^{z} / 2} & 0 & 0 & 0  \tag{4.23}\\
0 & \cos \left(\Delta_{t} J_{i j}^{x} / 2\right) & -i \sin \left(\Delta_{t} J_{i j}^{x} / 2\right) & 0 \\
0 & -i \sin \left(\Delta_{t} J_{i j}^{x} / 2\right) & \cos \left(\Delta_{t} J_{i j}^{x} / 2\right) & 0 \\
0 & 0 & 0 & e^{-i \Delta_{t} J_{i j}^{z} / 2}
\end{array}\right)
$$

Once more a code written for exact diagonalization can easily be changed into a time evolution code since similar terms have to be applied, just in a different order and with different matrix elements.

### 4.4 Higher spin

A generalization of the quantum spin- $1 / 2$ models discussed above to higher spins is conceptually straightforward, but leads to slightly more complicated codes. A quantum spin- $S$ has $2 S+1$ states, with $S^{z}$ components $-S,-S+1, \ldots, S-1, S$. Instead of
one bit for a spin- $1 / 2$ we will need $\left\lceil\log _{2}(2 S+1)\right\rceil$ bits, i.e. two bits for spin- 1 and spin-3/2, and three bits to store the state of a spin- 2 , spin- $5 / 2$, spin- 3 , or spin $7 / 2$. The spin operators $S^{x}, S^{y}, S^{z}$ are represented by $(2 S+1) \times(2 S+1)$ matrices which are higher-dimensional generalizations of the Pauli-matrices.

In the limit $S \rightarrow \infty$ we recover classical spins. Since already the properties of many spin-1 models (with the special exception of one-dimensional models) are very close to those of the classical models, quantum spin- $1 / 2$ models and materials are the most interesting ones and fortunately the easiest to simulate.

## Chapter 5

## Quantum computing

### 5.1 Quantum bits and quantum gates

In 1982 Feynman suggested that the problem of exponential complexity of simulating a quantum system can be solved by using quantum mechanics itself for computing, thus laying the foundation for the field of quantum computing. ${ }^{1}$ Just as there are many ways to build a classical computer and lots of different conventions, also quantum computers could be designed in many different ways. Since we don't have any large scale quantum computer yet we are free to choose a design that is simple from a theoretical point of view.

### 5.1.1 Quantum bits

The basic memory element is typically chosen as the quantum bit, or qubit for short a two-level system like a spin- $1 / 2$, where we associate the up spin state with the 0 bit and the down spin state with the 1 bit:

$$
\begin{align*}
& |0\rangle=|\uparrow\rangle=\binom{1}{0}  \tag{5.1}\\
& |1\rangle=|\downarrow\rangle=\binom{0}{1} \tag{5.2}
\end{align*}
$$

Just like for quantum spin-1/2s the quantum bit can exist in an arbitrary superposition of these two states:

$$
\begin{equation*}
|\Psi\rangle=\alpha|0\rangle+\beta|1\rangle, \tag{5.3}
\end{equation*}
$$

where the normalization condition (2.2) once more requires that $|\alpha|^{2}+|\beta|^{2}=1$. While such a state needs an infinite number of classical bits to describe accurately (think of the binary representation of $\alpha$ and $\beta$ ), a measurement will only give a single bit of information, either 0 or 1 . A register of $N$ qubits can store the wave function of $N$ spin- $1 / 2 \mathrm{~s}$, or $N$ spin-orbitals for fermions, which would require exponential memory on classical computers. This gives an exponential advantage in memory use. However,

[^3]since we can only do one measurement on each qubit only $N$ bits of information can ever be read out. One thus has to be smart in using these quantum bits.

### 5.1.2 Quantum gates

Since quantum mechanical time evolution is unitary (apart from measurements that collapse the wave function), we can only perform unitary operations on quantum bits and measurements. This is the second big restriction.

Just as for classical computers it is convenient to build a quantum circuit from a set of quantum gates that act on a limited set of qubits. Classical circuits are typically built from a set of gates that include OR, AND, NOT, XOR and more. However, in principle only the NAND (not-AND) gate is necessary since all other gates can be built from it. The NAND gate is thus called universal: any classical computation can be done purely with NAND gates. It still makes sense to consider more types of gates when building circuits, to make the design of circuits easier.

For quantum circuits one similarly often uses a larger set of gates than is strictly necessary. In the following I will discuss a set of typically used one and two qubit gates and will then discuss which ones are strictly necessary.

## Single qubit gates

| Pauli-X (NOT) | $-X$ | $\left(\begin{array}{cc}0 & 1 \\ 1 & 0\end{array}\right)$ |
| :--- | :--- | :--- |
| Pauli-Y | $-Y$ | $\left(\begin{array}{cc}0 & -i \\ i & 0\end{array}\right)$ |
| Pauli-Z | $\left(\begin{array}{cc}1 & 0 \\ 0 & -1\end{array}\right)$ |  |
| Hadamard gate | $-H$ | $\frac{1}{\sqrt{2}}\left(\begin{array}{ll}1 & 1 \\ 1 & -1\end{array}\right)$ |
| Phase gate | $\left(\begin{array}{ll}1 & 0 \\ 0 & i\end{array}\right)$ |  |
| T gate or $\pi / 8$ gate | $-T$ | $\left(\begin{array}{cc}1 & 0 \\ 0 & e^{i \pi / 4}\end{array}\right)$ |
| $\operatorname{Rz}(\theta)$ gate | $-R z(\theta)$ | $\left(\begin{array}{cc}e^{-i \theta / 2} & 0 \\ 0 & e^{i \theta / 2}\end{array}\right)$ |

A few remarks may be useful. The $X$ gate is the quantum analog of a classical NOT gate. The Hadamard gate $(H)$ squares to the identity and is essentially a ninety degree rotation around the $y$ axis, rotating a state aligned with $z$ to $x$. The $T$ gate is also called $\pi / 8$ gate since it can - up to an irrelevant global phase - be written as

$$
T=e^{i \pi / 8}\left(\begin{array}{cc}
e^{-i \pi / 8} & 0  \tag{5.4}\\
0 & e^{i \pi / 8}
\end{array}\right) .
$$

The $R z$ gate performs a rotation around the $z$ axis in spin space. Similar rotations around the $x$ and $y$ axis are performed by the $R x$ and $R y$ gates. For example, a rotation around the $x$ axis can be performed by swapping $z$ and $x$ by a Hadamard gate,
performing a rotation around the $z$ axis, and then rotating back:

$$
\begin{equation*}
-R x(\theta)-N=R z(\theta) \quad H \tag{5.5}
\end{equation*}
$$

## Two-qubit gates

A set of common two-qubit gates are controlled gates, consisting of a control qubit and a target qubit. The controlled version $C U$ of a single qubit gate $U$ (any of the list above) performs the single qubit operation $U$ on the target qubit only if the control qubit is set to 1 .

The quantum circuit for such a gate is:


Denoting the matrix representation of the gate $U$ as $\mathcal{U}$, the matrix representation of $C U$ in a basis $\{|00\rangle,|01\rangle,|10\rangle,|11\rangle\}$ is

$$
\left(\begin{array}{ll|ll}
1 & 0 & 0 & 0  \tag{5.6}\\
0 & 1 & 0 & 0 \\
\hline 0 & 0 & \mathcal{U} \\
0 & 0 &
\end{array}\right)
$$

The most important two-qubit gate is the controlled-NOT-gate (CNOT), which is the same as a controlled-X gate. It is typically drawn as


Its matrix representation is

$$
\left(\begin{array}{llll}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 0 & 1 \\
0 & 0 & 1 & 0
\end{array}\right) .
$$

Other two-qubit gates can be built from single qubit gates and the CNOT gate. For example, the swap gate which swaps the states of two qubits can be built from three CNOT gates as


## Universal gate sets

Of the above gates just the Hadamard, $\pi / 8$ and CNOT gates are sufficient to implement any quantum circuit. All the other gatescan be built from these gates, similar to the NAND gate being universal for classical computing.

The tricky part is how to represent arbitrary rotations using a discrete gate set. The Solovay-Kitaev algorithm allows to approximate arbitrary rotations to within any desired accuracy $\epsilon$, with just poly $\left(\log (1 / \epsilon)\right.$ gates. ${ }^{2}$ Better algorithms for approximation of rotations have recently been invented and this is still an interesting field of research.

### 5.2 Quantum algorithms

### 5.2.1 Quantum teleportation

As a first quantum algorithm that outperforms a classical algorithm we will consider quantum teleportation. We want to transfer the information in an arbitrary unknown quantum state $\alpha|0\rangle+\beta|1\rangle$ across a long distance. If we knew the values of $\alpha$ and $\beta$, we could transfer those values, which will in principle need infinitely many classical bits. However, in general we might not even know $\alpha$ and $\beta$, and measuring the state would destroy it. Quantum teleportation lets us transmit a quantum state by sending just two classical bits. A requirement for this is that the sender and receive share a Bell pair. ${ }^{3}$

## Bell states

Bell states, also called EPR pairs after the Einstein-Podolsky-Rosen paper are produced by the following circuit:


Starting from an initial state $\left|\psi_{0}\right\rangle=|x\rangle|y\rangle$, where $x$ and $y$ are either 0 or 1 and not in superposition, the circuit produces a final state

$$
\begin{equation*}
\left|\beta_{x y}\right\rangle \equiv \frac{|0, y\rangle+(-1)^{x}|1, \bar{y}\rangle}{\sqrt{2}} \tag{5.7}
\end{equation*}
$$

For pure initial states $|00\rangle,|01\rangle,|10\rangle$ and $|11\rangle$ we obtain the four Bell states called $\left|\beta_{00}\right\rangle,\left|\beta_{01}\right\rangle,\left|\beta_{10}\right\rangle$ and $\left|\beta_{11}\right\rangle$.

[^4]
## Quantum teleportation

To prepare for a future quantum teleportation the sender and receiver need to share a Bell state. While the two parties are still together they create a Bell state $\left|\beta_{00}\right\rangle$ and each one gets one of the qubits. To later teleport an unknown qubit state $|\psi\rangle$, the sender entangles her qubit of the Bell pair with the qubit $|\psi\rangle$, applies a Hadamard gate to the qubit to be sent and measures both qubits:


After sending the two classical bits of the measurement outcome (the double lines indicate classical bits and classical control) the receiver optionally applies an $X$ and/or $Z$ gate to his qubit, and then has the unknown state $|\psi\rangle$ in his qubit - teleportation has worked! Note that teleportation preserves the entanglements and correlations of the teleported qubit with any other qubit. All entanglement is swapped over to the target qubit.

The implementation of a teleport circuit and the proof of its working is left as a homework exercise.

### 5.2.2 The Deutsch and Deutsch-Jozsa algorithms

The Deutsch algorithm and its generalization, the Deutsch-Jozsa algorithm are the simplest quantum algorithms that show an advantage over classical algorithms, even though the problem they solve is somehow artificial. You are given a binary function $f$ (function values are either 0 or 1 ) and know that either the function is constant, or it is balanced, i.e. it is 0 for exactly half the inputs and 1 for the other half. The Deutsch and Deutsch-Jozsa algorithm can decide between the two cases with exactly one function call. ${ }^{4}$

## The Deutsch algorithm

The Deutsch algorithm asks the above question for a function of a single qubit. Is a function of one input variable $f:\{0,1\} \rightarrow\{0,1\}$ constant or not? Classically one has to obviously make two function calls and determine $f(0)$ and $f(1)$ to decide since we need to check whether $f(0)=f(1)$. Equivalently we can calculate $f(0) \oplus f(1)$, where $\oplus$ denotes binary addition modulo 2. If this value is zero, then $f$ is constant.

For the quantum algorithm we assume the function $f$ is given as a quantum algorithm $U_{f}$ that takes an input state $|x\rangle|y\rangle$ to a state $|x\rangle|f(x) \oplus y\rangle$. We can determine whether the function is constant in a single function call with the following algorithm:

[^5]

We start in a state $|0\rangle|1\rangle$ and apply a Hadamard gate to each qubit, giving the state $\frac{1}{2}(|0\rangle+|1\rangle)(|0\rangle-|1\rangle)$. Applying the function $f$ we obtain

$$
\begin{equation*}
(-1)^{f(0)} \frac{1}{2}\left(|0\rangle+(-1)^{f(0) \oplus f(1)}|1\rangle\right)(|0\rangle-|1\rangle) . \tag{5.8}
\end{equation*}
$$

Since the state of the second qubit is constant and the global phase irrelevant we drop them both and focus on just the first qubit's state $\frac{1}{\sqrt{2}}\left(|0\rangle+(-1)^{f(0) \oplus f(1)}|1\rangle\right)$. The desired information $f(0) \oplus f(1)$ is now encoded in the phase of the $|1\rangle$ state, which we cannot access. However, we note that depending on the value of $f(0) \oplus f(1)$ the qubit represents a quantum spin pointing either in the $+x$ or $-x$ direction. We thus apply another Hadamard gate to swap that information to the $z$ direction and can then directly measure the value:

$$
\begin{equation*}
\frac{1}{2}\left(\left(1+(-1)^{f(0) \oplus f(1)}\right)|0\rangle+\left(1-(-1)^{f(0) \oplus f(1)}\right)|1\rangle\right) \tag{5.9}
\end{equation*}
$$

We see that in a final measurement we get the state $|0\rangle$ with certainty if $f(0)=f(1)$ and the state $|1\rangle$ otherwise. A single function call and single measurement can thus tell if the function is constant or not.

## The Deutsch-Jozsa algorithm

The Deutsch-Jozsa algorithm generalizes the Deutsch algorithm to functions defined not just over two values but $2^{N}$ values, encoded in $N$ bits. The question is once more In a deterministic classical algorithm it requires at least $2^{N-1}+1$ function calls to determine whether the function $f:\{0,1\}^{N} \rightarrow\{0,1\}$ is balanced or constant. The Deutsch-Jozsa quantum algorithm once more manages to decide the question with a single function call. It is similar to the Deutsch algorithm, but acts on $N$ input qubits instead of a single one:


The first line in this algorithm now represents an $N$-qubit quantum register, $x$, with each qubit initalized to 0 . The second line is a single qubit $y$ in the state $|1\rangle$. Applying a Hadmard gate to each qubit gives a superposition of all possible input states:

$$
\begin{equation*}
\frac{1}{\sqrt{2^{n+1}}} \sum_{x=0}^{2^{n}-1}|x\rangle(|0\rangle-|1\rangle) \tag{5.10}
\end{equation*}
$$

We now call the function $f$ with this input and obtain a superposition of all function values:

$$
\begin{equation*}
\frac{1}{\sqrt{2^{n+1}}} \sum_{x=0}^{2^{n}-1}|x\rangle(|f(x)\rangle-|1 \oplus f(x)\rangle)=\frac{1}{\sqrt{2^{n+1}}} \sum_{x=0}^{2^{n}-1}(-1)^{f(x)}|x\rangle(|0\rangle-|1\rangle) . \tag{5.11}
\end{equation*}
$$

Once more we can ignore the quantum register $y$ which is now in a definite state $(|0\rangle-|1\rangle) / \sqrt{2}$ and might think that we have succeeded in solving the problem. However, the information we need is stored in a quantum register and we need to measure it to get the result. Just measuring the register $x$ does not help us. We would just get the result $f(x)$ for some random $x$ and could instead just have classically computed the value $f(x)$ for a random argument. While the quantum algorithm can evaluate the function $f(x)$ for all inputs at once, we can't easily read out all those values since we can only obtain $N$ bits through measurements.

The solution is to smartly manipulate the quantum register $x$ to obtain the answer to our desired question before measuring. Here that can be done by once more applying a Hadamard gate to each of the qubits comprising $x$ and get

$$
\begin{equation*}
\frac{1}{2^{n}} \sum_{x=0}^{2^{n}-1}\left[(-1)^{f(x)} \sum_{y=0}^{2^{n}-1}(-1)^{x \cdot y}\right]|y\rangle=\frac{1}{2^{n}} \sum_{y=0}^{2^{n}-1}\left[\sum_{x=0}^{2^{n}-1}(-1)^{f(x)}(-1)^{x \cdot y}\right]|y\rangle, \tag{5.12}
\end{equation*}
$$

where • refers to a bit-wise dot product. The probability of measuring all 0 s is

$$
\begin{equation*}
\left|\frac{1}{2^{n}} \sum_{x=0}^{2^{n}-1}(-1)^{f(x)}\right|^{2} \tag{5.13}
\end{equation*}
$$

This is one if the function is constant and 0 if the function is balanced. A single function application and measurement is hence sufficient to distinguish between the two possibilities.

### 5.3 Simulating quantum systems

### 5.3.1 Time evolution of a quantum spin model

Exponential speedup can be obtained for the simulation of quantum systems, which we will consider here for the case of a transverse field Ising model - the same model that we used in the exercises for simulation of adiabatic quantum optimization. We once more consider the TFIM Hamiltonian (4.2). In order to simulate the time evolution on a quantum computer we have to use a Trotter decomposition just like in the classical case, and again have the choice between simpler low-order approximations or more accurate high-order ones that are more complex but also more accurate.

So far all is the same as in our classical algorithm that we wrote last week. The big advantage of quantum computers shows in the implementation of the individual terms of the Trotterized time evolution, which is s now much easier. First, we need just $N$ qubits instead of $2^{N}$ complex numbers in a classical code and requires only $\mathcal{O}(N)$ instead of $\mathcal{O}\left(2^{N}\right)$ operations.

The time evolution under the transverse field term $e^{i \Delta_{t} \Gamma \sigma_{i}^{x}}$ is trivial to implement, since it is just a rotation around the $x$ axis, implemented by an $R_{x}$ gate:

$$
-R_{x}\left(-2 \Delta_{t} \Gamma\right)
$$

If we don't want to assume an $R_{x}$ gate but just want to use an $R_{z}$ gate then a basis transformation will be needed:


The Ising term is a 2 -spin coupling and thus requires a 2 -qubit gate. To implement $e^{-i \Delta_{t} J_{i j} \sigma_{i}^{z} \sigma_{j}^{z}}$ one needs to rotate by an angle $-\Delta_{t} J_{i j}$ if the two spin values are the same and $+\Delta_{t} J_{i j}$ if they differ. The following simple circuit can realize this operation:


Similar circuits can be designed for other quantum models, as we will do in the exercises for a quantum Heisenberg model.

Before discussing fermionic quantum many body problems we will need to learn how to solve them classically. After that we will discuss quantum algorithms for fermion models.

### 5.3.2 Adiabatic state preparation

## Ground state preparation through adiabatic state preparation

We have seen that it is much easier to implement the time evolution under the unitary operation $\exp (-i H t)$ on a quantum computer than on a classical computer. However, quantum computers can only perform unitary operations. On a classical computer the effort of preparing the ground state of a quantum system by the power method or Lanczos algorithm is similar to that of time evolution. However, the quantum computer cannot do the second even though it is exponentially faster than the first.

Since a quantum computer is very fast when implementing time evolution we want to use time evolution to prepare the ground state of a quantum system. This can be done using adiabatic state preparation, which is based on the quantum adiabatic theorem. We assume that at $t=0$ we start in the ground state $\left|\psi_{0} t\right\rangle$ of a timedependent Hamiltonian $H(t)$. If we change the Hamiltonian $H(t)$ adiabatically slowly we will remain in the ground state $\left|\psi_{0} t\right\rangle$ of the instantaneous Hamiltonian $H(t)$. This opens a way to prepare the ground state of a quantum system. Let us start at time $t=0$ in a Hamiltonian $H_{0}$ of which we can easily compute the ground state. For a TFIM this may just be the transverse field term and we start with all spins pointing along the field. For a Heisenberg or $X X Z$ model we may simply switch off the $x$ and $y$ components of the couplings and start with an Ising model which we can solve by classical means. In order to find the ground state of an unknown Hamiltonian $H_{f}$ we adiabatically interpolate between $H_{0}$ and $H_{f}$ to arrive at the desired Hamiltonian at time $t_{f}$ :

$$
\begin{equation*}
H(t)=\left(1-\frac{t}{t_{f}}\right) H_{0}+\frac{t}{t_{f}} H_{f} \tag{5.14}
\end{equation*}
$$

Instead of this linear interpolation any other function can be chosen as long as $H(0)=$ $H_{0}$ and $H\left(t_{f}\right)=H_{f}$. If we choose $t_{f}$ long enough we are guaranteed to end up in the ground state with only exponentially small errors.

What is meant by "long enough"? The quantum adiabatic theorem states that this time should be much longer than a scale set by the minimum gap:

$$
\begin{equation*}
t_{f} \gg \mathcal{O}\left(\min _{t} \Delta(t)^{-2}\right), \tag{5.15}
\end{equation*}
$$

where the gap

$$
\begin{equation*}
\Delta(t)=E_{1}(t)-E_{0}(t) \tag{5.16}
\end{equation*}
$$

is the difference between the ground state energy $E_{0}(t)$ and the energy of the first excited state $E_{1}(t)$. Since in practice we know neither the minimum gap of the unknown quantum system, nor the constants that go into this inequality, we will have to perform numerical experiments on our (quantum) computer to determine when the results start to converge as a function of $t_{f}$.

## The Landau-Zener problem

As is often the case, we can make more quantitative statements in simple problems. Here this simple problem is the Landau-Zener problem, defined by the following time dependent Hamiltonian:

$$
\begin{equation*}
H(t)=t v \sigma_{z}-\epsilon \sigma_{x} . \tag{5.17}
\end{equation*}
$$

At time $t \leftarrow-\infty$ the ground state is $|\uparrow\rangle$ and at $t \rightarrow+\infty$ the ground state is $|\downarrow\rangle$. If we move too fast $(v \rightarrow \infty)$ the spin has no chance to flip and will be stuck in the initial state $|\uparrow\rangle$, and if we move slowly enough $(v \rightarrow 0)$ we should adiabatically find the final ground state $|\downarrow\rangle$.

The eigenvalues of this model are easily calculated to be $\pm \sqrt{\epsilon^{2}+v^{2} t^{2}}$ and are shown below for $\epsilon=v=1$ :


It is easy to see that the minimum gap is at time $t=0$ with a value of $\Delta(0)=2 \epsilon$.
Landau and Zener independently solved this problem ${ }^{5}$ and obtained what is now known as the Landau-Zener formula. The probability for a diabatic transition, that is for not ending up in the ground state is given by

$$
\begin{equation*}
P=e^{-2 \pi \Gamma} \tag{5.18}
\end{equation*}
$$

[^6]with
\[

$$
\begin{equation*}
\Gamma=\frac{\epsilon^{2}}{2 \hbar v} \tag{5.19}
\end{equation*}
$$

\]

In order to have an exponentially small error probability $P$ we need to choose $\Gamma \gg 1$ and thus the velocity $v \ll \epsilon^{2} / 2=\Delta^{2} / 8$.

### 5.3.3 Quantum phase estimation and energy measurements

## Measuring energies from phases

The most straightforward way of measuring the energy of a quantum state $|\psi\rangle$ may seem to be to measure all the terms that make up the Hamiltonian $H$ and thus evaluate $\langle\psi| H|\psi\rangle$. However, this approach has several disadvantages. The wave function $|\psi\rangle$ gets destroyed with every measurement and we get only $N$ bits of information. As this approach is similar to Monte Carlo sampling, we need $\mathcal{O}\left(\epsilon^{-2}\right)$ measurements and thus $\mathcal{O}\left(\epsilon^{-2}\right)$ preparations of the wave function $|\psi\rangle$ to measure the energy to an accuracy $\epsilon$.

An alternative is to measure the phase which a state $|\psi\rangle$ picks up under time evolution with $H$. Let us first assume that $|\psi\rangle=\left|\phi_{n}\right\rangle$ be an eigenstate $\left|\phi_{n}\right\rangle$ of $H$ with eigenvalue $E_{n}$. Under time evolution $e^{-i H t}|\psi\rangle=e^{-i E_{n} t}\left|\phi_{i}\right\rangle$ the state picks up a phase $E_{n} t$. Measuring this phase would thus allow to measure the energy.

Let us now drop the assumption that $|\psi\rangle$ is an eigenstate, but assume a superposition of eigenstates $|\psi\rangle=\sum_{n} c_{n}\left|\phi_{n}\right\rangle$. Each of the eigenstates $\left|\phi_{n}\right\rangle$ picks up the corresponding phase $\phi_{n}=E_{n} t$. If we measure the phase under time evolution, we will get one of these phases $\phi_{n}$, randomly with probability $\left|c_{n}\right|^{2}$. The wave function then collapses into the corresponding eigenstate $\left|\phi_{n}\right\rangle .^{6}$

This provides a way of getting pure eigenstates and their corresponding energy eigenvalues by first preparing a state with large overlap with the desired state $\left|\phi_{k}\right\rangle$, for example by adiabatic state preparation, and then measuring the phase.

## Quantum phase estimation

But, how do we measure the phase under time evolution? At first sight the phase is not an observable quantity. However, we can set up an "interference experiment" to determine the phase. We add an ancilla qubit and perform the evolution under $U=e^{-i H t}$ only if the ancilla is on:


We start from $|0\rangle|\psi\rangle$ and apply a Hadamard gate to the ancilla, giving

$$
\begin{equation*}
\frac{1}{\sqrt{2}}(|0\rangle|\psi\rangle+|1\rangle|\psi\rangle) \tag{5.20}
\end{equation*}
$$

[^7]We then apply the evolution controlled by the ancilla,:

$$
\begin{equation*}
\frac{1}{\sqrt{2}}(|0\rangle|\psi\rangle+|1\rangle U|\psi\rangle) \tag{5.21}
\end{equation*}
$$

If $|\psi\rangle$ is an eigenstate $\left|\phi_{n}\right\rangle$ we pick up the corresponding phase $\phi=E_{n} t$

$$
\begin{equation*}
\frac{1}{\sqrt{2}}\left(|0\rangle|\psi\rangle+e^{-i \phi}|1\rangle|\psi\rangle\right) . \tag{5.22}
\end{equation*}
$$

Measuring now would not give us any information since phase cannot be determined. But we can interfere the two cases by another Hadamard transform on the ancilla, obtaining

$$
\begin{equation*}
\frac{1}{2}\left[\left(1+e^{-i \phi}\right)|0\rangle|\psi\rangle+\left(1-e^{-i \phi}\right)|1\rangle|\psi\rangle\right] . \tag{5.23}
\end{equation*}
$$

Now we measure the ancilla. The probability of measuring 0 is $(1+\cos \phi) / 2$. If $\phi$ should be a multiple of $\pi$ we can determine whether it is an odd or even multiple with a single measurement. If the phase is not a multiple of $\pi$ we repeat the quantum phase estimation and then estimate $\phi$ from the observed ratio of measuring 0 and 1 . As the measurement becomes more precise the wave function will gradually collapse towards a superposition of those eigenstates compatible with the measurement and ultimately to a single eigenstate.

However, this procedure is inefficient. A more efficient algorithm is due to Kitaev. It performs phase estimations with times $2^{k} t(k=1, \ldots, n)$, for that are powers of 2 , and thus measures all bits in a binary representation of the phase at once:


We end up with a register containing the Fourier transform of the phase:

$$
\begin{equation*}
\frac{1}{\sqrt{2^{n}}} \sum_{x} e^{i x \theta}|x\rangle|\psi\rangle \tag{5.24}
\end{equation*}
$$

Employing an inverse quantum Fourier transform $F^{-1}$ we measure a binary representation $\pi x / 2^{n}$ of the phase $\phi$.

## Classical and quantum complexity of ground state preparation

In order to prepare the ground state of an $N$-qubit classical system using the power method or the Lanczos algorithm we need to repeatedly perform matrix-vector multiplications. Assuming $d$ terms in the Hamiltonian and $N$ quantum spin- $1 / 2$ s each of
these matrix-vector multiplications requires $\mathcal{O}\left(d 2^{N}\right)$ operations. The number of multiplications $M$ that is required can be determined from the error in the power method or Lanczos algorithm. The error decreases as $\epsilon \sim\left|E_{1} / E_{0}\right|^{M}=\left(1-\Delta /\left|E_{0}\right|\right)^{M}$. To achieve a desired accuracy $\epsilon$ we need $M=\log \epsilon / \log \left(1-\Delta /\left|E_{0}\right|\right) \sim 1 / \Delta$ iterations, giving a total complexity of $\mathcal{O}\left(2^{N} d / \Delta\right)$.

On a quantum computer we need only $\mathcal{O}(d)$ operations, but need to evolve slow compared to the time scale given by $\Delta^{-2}$, thus resulting in a total complexity of $\mathcal{O}\left(d / \Delta^{2}\right)$. The worse scaling in $\Delta$ in the quantum case is unfortunate but usually more than compensated by the exponential term $2^{N}$ in the classical case.

### 5.4 Further quantum algorithms

If there is still time towards the end of the lecture I will discuss further quantum algorithms, such as the quantum Fourier transforms and Shor's algorithm for factoring.

## Chapter 6

## Indistinguishable particles: fermions and bosons

### 6.1 Introduction

In quantum mechanics we assume that elementary particles, such as the electron or photon, are indistinguishable: there is no serial number painted on the electrons that would allow us to distinguish two electrons. Hence, if we exchange two particles the system is still the same as before. For a two-body wave function $\psi\left(\vec{q}_{1}, \vec{q}_{2}\right)$ this means that

$$
\begin{equation*}
\psi\left(\vec{q}_{2}, \vec{q}_{1}\right)=e^{i \phi} \psi\left(\vec{q}_{1}, \vec{q}_{2}\right), \tag{6.1}
\end{equation*}
$$

since upon exchanging the two particles the wave function needs to be identical, up to a phase factor $e^{i \phi}$. In three dimensions the first homotopy group is trivial and after doing two exchanges we need to be back at the original wave function ${ }^{1}$

$$
\begin{equation*}
\psi\left(\vec{q}_{1}, \vec{q}_{2}\right)=e^{i \phi} \psi\left(\vec{q}_{2}, \vec{q}_{1}\right)=e^{2 i \phi} \psi\left(\vec{q}_{1}, \vec{q}_{2}\right), \tag{6.2}
\end{equation*}
$$

and hence $e^{i \phi}= \pm 1$ :

$$
\begin{equation*}
\psi\left(\vec{q}_{2}, \vec{q}_{1}\right)= \pm \psi\left(\vec{q}_{1}, \vec{q}_{2}\right) \tag{6.3}
\end{equation*}
$$

The many-body Hilbert space can thus be split into orthogonal subspaces, one in which particles pick up a - sign and are called fermions, and the other where particles pick up a + sign and are called bosons.

### 6.1.1 Bosons

For bosons the general many-body wave function thus needs to be symmetric under permutations. Instead of an arbitrary wave function $\psi\left(\vec{q}_{1}, \ldots, \vec{q}_{N}\right)$ of $N$ particles we use the symmetrized wave function

$$
\begin{equation*}
\Psi^{(S)}=\mathcal{S}_{+} \psi\left(\vec{q}_{1}, \ldots, \vec{q}_{N}\right) \equiv \mathcal{N}_{S} \sum_{p} \psi\left(\vec{q}_{p(1)}, \ldots, \vec{q}_{p(N)}\right), \tag{6.4}
\end{equation*}
$$

[^8]where the sum goes over all permutations $p$ of $N$ particles, and $\mathcal{N}_{S}$ is a normalization factor.

### 6.1.2 Fermions

For fermions the wave function has to be antisymmetric under exchange of any two fermions, and we use the anti-symmetrized wave function

$$
\begin{equation*}
\Psi^{(A)} \mathcal{S}_{-} \psi\left(\vec{q}_{1}, \ldots, \vec{q}_{N}\right) \equiv \mathcal{N}_{A} \sum_{p} \operatorname{sgn}(p) \psi\left(\vec{q}_{p(1)}, \ldots, \vec{q}_{p(N)}\right), \tag{6.5}
\end{equation*}
$$

where $\operatorname{sgn}(p)= \pm 1$ is the sign of the permutation and $\mathcal{N}_{A}$ again a normalization factor.
A consequence of the antisymmetrization is that no two fermions can be in the same state as a wave function

$$
\begin{equation*}
\psi\left(\vec{q}_{1}, \vec{q}_{2}\right)=\phi\left(\vec{q}_{1}\right) \phi\left(\vec{q}_{2}\right) \tag{6.6}
\end{equation*}
$$

since this vanishes under antisymmetrization:

$$
\begin{equation*}
\Psi\left(\vec{q}_{1}, \vec{q}_{2}\right)=\psi\left(\vec{q}_{1}, \vec{q}_{2}\right)-\psi\left(\vec{q}_{2}, \vec{q}_{1}\right)=\phi\left(\vec{q}_{1}\right) \phi\left(\vec{q}_{2}\right)-\phi\left(\vec{q}_{2}\right) \phi\left(\vec{q}_{1}\right)=0 \tag{6.7}
\end{equation*}
$$

### 6.1.3 Spinful fermions

Fermions, such as electrons, usually have a spin- $1 / 2$ degree of freedom in addition to their orbital wave function. The full wave function as a function of a generalized coordinate $\vec{x}=(\vec{q}, \sigma)$ including both position $\vec{q}$ and spin $\sigma$.

### 6.2 The Fock space

The Hilbert space describing a quantum many-body system with $N=0,1, \ldots, \infty$ particles is called the Fock space. It is the direct sum of the appropriately symmetrized $N$-particel Hilbert spaces (made up from single-particle Hilbert spaces) $\mathcal{H}$ :

$$
\begin{equation*}
\bigoplus_{N=0}^{\infty} S_{ \pm} \mathcal{H}^{\otimes N} \tag{6.8}
\end{equation*}
$$

where $S_{+}$is the symmetrization operator used for bosons and $S_{-}$is the anti-symmetrization operator used for fermions.

### 6.2.1 The occupation number basis

Given a basis $\left\{\left|\phi_{1}\right\rangle, \ldots,\left|\phi_{L}\right\rangle\right\}$ of the single-particle Hilbert space $\mathcal{H}$, a basis for the Fock space is constructed by specifying the number of particles $n_{i}$ occupying the singleparticle wave function $\left|f_{1}\right\rangle$. The wave function of the state $\left|n_{1}, \ldots, n_{L}\right\rangle$ is given by the appropriately symmetrized and normalized product of the single particle wave functions. For example, the basis state $|1,1\rangle$ has wave function

$$
\begin{equation*}
\frac{1}{\sqrt{2}}\left[\phi_{1}\left(\vec{x}_{1}\right) \phi_{2}\left(\vec{x}_{2}\right) \pm \phi_{1}\left(\vec{x}_{2}\right) \phi_{2}\left(\vec{x}_{1}\right)\right] \tag{6.9}
\end{equation*}
$$

where the + sign is for bosons and the - sign for fermions.
For bosons the occupation numbers $n_{i}$ can go from 0 to $\infty$, but for fermions they are restricted to $n_{i}=0$ or 1 since no two fermions can occupy the same state.

### 6.2.2 The Slater determinant

The antisymmetrized and normalized product of $N$ single-particle wave functions $\phi_{i}$ can be written as a determinant, called the Slater determinant

$$
\mathcal{S}_{-} \prod_{i_{1}}^{N} \phi_{i}\left(\vec{x}_{i}\right)=\frac{1}{\sqrt{N}}\left|\begin{array}{ccc}
\phi_{1}\left(\vec{x}_{1}\right) & \cdots & \phi_{N}\left(\vec{x}_{1}\right)  \tag{6.10}\\
\vdots & & \vdots \\
\phi_{1}\left(\vec{x}_{N}\right) & \cdots & \phi_{N}\left(\vec{x}_{N}\right)
\end{array}\right|
$$

Note that while the set of Slater determinants of single particle basis functions forms a basis of the fermionic Fock space, the general fermionic many body wave function is a linear superposition of many Slater determinants and cannot be written as a single Slater determinant. The Hartee Fock method, discussed below, will simplify the quantum many body problem to a one body problem by making the approximation that the ground state wave function can be described by a single Slater determinant.

### 6.3 Creation and annihilation operators

Since it is very cumbersome to work with appropriately symmetrized many body wave functions, we will mainly use the formalism of second quantization and work with creation and annihilation operators.

The annihilation operator $a_{i, \sigma}$ associated with a basis function $\left|\phi_{i}\right\rangle$ is defined as the result of the inner product of a many body wave function $|\Psi\rangle$ with this basis function $\left|\phi_{i}\right\rangle$. Given an $N$-particle wave function $\left|\Psi^{(N)}\right\rangle$ the result of applying the annihilation operator is an $N$ - 1-particle wave function $\left|\tilde{\Psi}^{(N)}\right\rangle=a_{i}\left|\Psi^{(N)}\right\rangle$. It is given by the appropriately symmetrized inner product

$$
\begin{equation*}
\tilde{\Psi}\left(\vec{x}_{1}, \ldots, \vec{x}_{N-1}\right)=\mathcal{S}_{ \pm} \int d \vec{x}_{N} f_{i}^{\dagger}\left(\vec{x}_{N}\right) \Psi\left(\vec{x}_{1}, \ldots, \vec{x}_{N}\right) \tag{6.11}
\end{equation*}
$$

Applied to a single-particle basis state $\left|\phi_{j}\right\rangle$ the result is

$$
\begin{equation*}
a_{i}\left|\phi_{j}\right\rangle=\delta_{i j}|0\rangle \tag{6.12}
\end{equation*}
$$

where $|0\rangle$ is the "vacuum" state with no particles.
The creation operator $a_{i}^{\dagger}$ is defined as the adjoint of the annihilation operator $a_{i}$. Applying it to the vacuum "creates" a particle with wave function $\phi_{i}$ :

$$
\begin{equation*}
\left|\phi_{i}\right\rangle=a_{i}^{\dagger}|0\rangle \tag{6.13}
\end{equation*}
$$

For sake of simplicity and concreteness we will now assume that the $L$ basis functions $\left|\phi_{i}\right\rangle$ of the single particle Hilbert space factor into $L /(2 S+1)$ orbital wave functions $f_{i}(\vec{q})$ and $2 S+1$ spin wave functions $|\sigma\rangle$, where $\sigma=-S,-S+1, \ldots, S$. We will write
creation and annihilation operators $a_{i, \sigma}^{\dagger}$ and $a_{i, \sigma}$ where $i$ is the orbital index and $\sigma$ the spin index. The most common cases will be spinless bosons with $S=0$, where the spin index can be dropped and spin- $1 / 2$ fermions, where the spin can be up $(+1 / 2)$ or down $(-1 / 2)$.

### 6.3.1 Commutation relations

The creation and annihilation operators fulfill certain canonical commutation relations, which we will first discuss for an orthogonal set of basis functions. We will later generalize them to non-orthogonal basis sets.

For bosons, the commutation relations are the same as that of the ladder operators discussed for the harmonic oscillator (2.62):

$$
\begin{gather*}
{\left[a_{i}, a_{j}\right]=\left[a_{i}^{\dagger}, a_{j}^{\dagger}\right]=0}  \tag{6.14}\\
{\left[a_{i}, a_{j}^{\dagger}\right]=\delta_{i j} .} \tag{6.15}
\end{gather*}
$$

For fermions, on the other hand, the operators anticommute

$$
\begin{align*}
& \left\{a_{j \sigma^{\prime}}^{\dagger}, a_{i \sigma}\right\}=\left\{a_{i \sigma}^{\dagger}, a_{j \sigma^{\prime}}\right\}=\delta_{\sigma \sigma^{\prime}} \delta_{i j} \\
& \left\{a_{i \sigma}, a_{j \sigma^{\prime}}\right\}=\left\{a_{i \sigma}^{\dagger}, a_{j \sigma^{\prime}}^{\dagger}\right\}=0 . \tag{6.16}
\end{align*}
$$

The anti-commutation implies that

$$
\begin{equation*}
\left(a_{i}^{\dagger}\right)^{2}=a_{i}^{\dagger} a_{i}^{\dagger}=-a_{i}^{\dagger} a_{i}^{\dagger} \tag{6.17}
\end{equation*}
$$

and that thus

$$
\begin{equation*}
\left(a_{i}^{\dagger}\right)^{2}=0, \tag{6.18}
\end{equation*}
$$

as expected since no two fermions can exist in the same state.

### 6.3.2 Fock basis in second quantization and normal ordering

The basis state $\left|n_{1}, \ldots, n_{L}\right\rangle$ in the occupation number basis can easily be expressed in terms of creation operators:

$$
\begin{equation*}
\left|n_{1}, \ldots, n_{L}\right\rangle=\prod_{i=1}^{L}\left(a_{i}^{\dagger}\right)^{n_{i}}|0\rangle=\left(a_{1}^{\dagger}\right)^{n_{1}}\left(a_{2}^{\dagger}\right)^{n_{2}} \cdots\left(a_{L}^{\dagger}\right)^{n_{L}}|0\rangle \tag{6.19}
\end{equation*}
$$

For bosons the ordering of the creation operators does not matter, since the operators commute. For fermions, however, the ordering matters since the fermionic creation operators anticommute: and $a_{1}^{\dagger} a_{2}^{\dagger}|0\rangle=-a_{1}^{\dagger} a_{2}^{\dagger}|0\rangle$. We thus need to agree on a specific ordering of the creation operators to define what we mean by the state $\left|n_{1}, \ldots, n_{L}\right\rangle$. The choice of ordering does not matter but we have to stay consistent and use e.g. the convention in equation (6.19).

Once the normal ordering is defined, we can derive the expressions for the matrix elements of the creation and annihilation operators in that basis. Using above normal ordering the matrix elements are

$$
\begin{align*}
a_{i}\left|n_{1}, \ldots, n_{i}, \ldots, n_{L}\right\rangle & =\delta_{n_{i}, 1}(-1)^{\sum_{j=1}^{i-1} n_{i}}\left|n_{1}, \ldots, n_{i}-1, \ldots, n_{L}\right\rangle  \tag{6.20}\\
a_{i}^{\dagger}\left|n_{1}, \ldots, n_{i}, \ldots, n_{L}\right\rangle & =\delta_{n_{i}, 0}(-1)^{\sum_{j=1}^{i-1} n_{i}}\left|n_{1}, \ldots, n_{i}+1, \ldots, n_{L}\right\rangle \tag{6.21}
\end{align*}
$$

where the minus signs come from commuting the annihilation and creation operator to the correct position in the normal ordered product.

### 6.3.3 Nonorthogonal basis sets

In simulating the electronic properties of atoms and molecules below we will see that the natural choice of single particle basis functions centered around atoms will necessarily give a non-orthogonal set of basis functions. This is no problem, as long as the definition of the annihilation and creation operators is carefully generalized. For this generalization it will be useful to introduce the fermion field operators $\psi_{\sigma}^{\dagger}(\vec{r})$ and $\psi_{\sigma}(\vec{r})$, creating and annihilating a fermion localized at a single point $\vec{r}$ in space. Their commutation relations are simply

$$
\begin{align*}
& \left\{\psi_{\sigma^{\prime}}^{\dagger}(\vec{r}), \psi_{\sigma}\left(\overrightarrow{r^{\prime}}\right)\right\}=\left\{\psi_{\sigma}^{\dagger}(\vec{r}), \psi_{\sigma^{\prime}}\left(\overrightarrow{r^{\prime}}\right)\right\}=\delta_{\sigma \sigma^{\prime}} \delta\left(\vec{r}-\overrightarrow{r^{\prime}}\right) \\
& \left\{\psi_{\sigma}(\vec{r}), \psi_{\sigma^{\prime}}\left(\overrightarrow{r^{\prime}}\right)\right\}=\left\{\psi_{\sigma}^{\dagger}(\vec{r}), \psi_{\sigma^{\prime}}^{\dagger}\left(\overrightarrow{r^{\prime}}\right)\right\}=0 \tag{6.22}
\end{align*}
$$

The scalar products of the basis functions define a matrix

$$
\begin{equation*}
S_{i j}=\int d^{3} \vec{r} f_{i}^{*}(\vec{r}) f_{j}(\vec{r}) \tag{6.23}
\end{equation*}
$$

which is in general not the identity matrix. The associated annihilation operators $a_{i \sigma}$ are again defined as scalar products

$$
\begin{equation*}
a_{i \sigma}=\sum_{j}\left(S^{-1}\right)_{i j} \int d^{3} \vec{r} f_{j}^{*}(\vec{r}) \psi_{\sigma}(\vec{r}) \tag{6.24}
\end{equation*}
$$

The non-orthogonality causes the commutation relations of these operators to differ from those of normal fermion creation- and annihilation operators:

$$
\begin{align*}
\left\{a_{i \sigma}^{\dagger}, a_{j \sigma^{\prime}}\right\} & =\delta_{\sigma \sigma^{\prime}}\left(S^{-1}\right)_{i j} \\
\left\{a_{i \sigma}, a_{j \sigma^{\prime}}\right\}=\left\{a_{i \sigma}^{\dagger}, a_{j \sigma^{\prime}}^{\dagger}\right\} & =0 . \tag{6.25}
\end{align*}
$$

Due to the non-orthogonality the adjoint $a_{i \sigma}^{\dagger}$ does not create a state with wave function $f_{i}$. This is done by the operator $\hat{a}_{i \sigma}^{\dagger}$, defined through:

$$
\begin{equation*}
\hat{a}_{i \sigma}^{\dagger}=\sum_{j} S_{j i} a_{j \sigma}^{\dagger} \tag{6.26}
\end{equation*}
$$

which has the following simple commutation relation with $a_{j \sigma}$ :

$$
\begin{equation*}
\left\{\hat{a}_{i \sigma}^{\dagger}, a_{j \sigma}\right\}=\delta_{i j} . \tag{6.27}
\end{equation*}
$$

The commutation relations of the $\hat{a}_{i \sigma}^{\dagger}$ and the $\hat{a}_{j \sigma^{\prime}}$ are:

$$
\begin{align*}
\left\{\hat{a}_{i \sigma}^{\dagger} \hat{a}_{j \sigma^{\prime}}\right\} & =\delta_{\sigma \sigma^{\prime}} S_{i j} \\
\left\{\hat{a}_{i \sigma}, \hat{a}_{j \sigma^{\prime}}\right\}=\left\{\hat{a}_{i \sigma}^{\dagger}, \hat{a}_{j \sigma^{\prime}}^{\dagger}\right\} & =0 . \tag{6.28}
\end{align*}
$$

We will need to keep the distinction between $a$ and $\hat{a}$ in mind when dealing with non-orthogonal basis sets.

## Chapter 7

## Quantum Monte Carlo

This chapter is devoted to the study of quatum many body systems using Monte Carlo techniques. We analyze two of the methods that belong to the large family of the quantum Monte Carlo techniques, namely the Path-Integral Monte Carlo (PIMC) and the Diffusion Monte Carlo (DMC, also named Green's function Monte Carlo). In the first section we start by introducing PIMC.

### 7.1 Path Integrals in Quantum Statistical Mechanics

In this section we introduce the path-integral description of the properties of quantum many-body systems. We show that path integrals permit to calculate the static properties of systems of Bosons at thermal equilibrium by means of Monte Carlo methods.

We consider a many-particle system described by the non-relativistic Hamiltonian

$$
\begin{equation*}
\hat{H}=\hat{T}+\hat{V} \tag{7.1}
\end{equation*}
$$

in coordinate representation the kinetic operator $\hat{T}$ and the potential operator $\hat{V}$ are defined as:

$$
\begin{align*}
& \hat{T}=-\frac{\hbar^{2}}{2 m} \sum_{i=1}^{N} \Delta_{i}, \text { and }  \tag{7.2}\\
& \hat{V}=V(\boldsymbol{R}) \tag{7.3}
\end{align*}
$$

In these equations $\hbar$ is the Plank's constant divided by $2 \pi, m$ the particles mass, $N$ the number of particles and the vector $\boldsymbol{R} \equiv\left(\boldsymbol{r}_{1}, \ldots, \boldsymbol{r}_{N}\right)$ describes their positions. We consider here systems in $d$ dimensions, with fixed number of particles, temperature $T$, contained in a volume $V$.
In most case, the potential $V(\boldsymbol{R})$ is determined by inter-particle interactions, in which case it can be written as the sum of pair contributions $V(\boldsymbol{R})=\sum_{i<j} v\left(\boldsymbol{r}_{i}-\boldsymbol{r}_{j}\right)$, where $v(\boldsymbol{r})$ is the inter-particle potential; it can also be due to an external field, call it $v_{\text {ext }}(\boldsymbol{r})$, in which case it is just the sum of single particle contributions $V(\boldsymbol{R})=\sum_{i} v_{\text {ext }}\left(\boldsymbol{r}_{i}\right)$.

We first assume that particles, although being identical, are distinguishable. Therefore, they obey Boltzmann statistics. In section 7.1.3 we will describe the treatment of identical particles obeying Bose statistics.

All the static properties of a quantum many-body system in thermal equilibrium are obtainable from the thermal density matrix $\exp (-\beta \hat{H})$, where $\beta=1 / k_{B} T$, with $k_{B}$ the Boltzmann's constant. The expectation value of an observable operator $\hat{O}$ is:

$$
\begin{equation*}
\langle\hat{O}\rangle=\operatorname{Tr}(\hat{O} \exp (-\beta \hat{H})) / Z \tag{7.4}
\end{equation*}
$$

where the partition function $Z$ is the trace of the density matrix:

$$
\begin{equation*}
Z=\operatorname{Tr}(\exp (-\beta \hat{H})) \tag{7.5}
\end{equation*}
$$

In the following we will find convenient to use the density matrix in coordinate representation. We denote its matrix elements as:

$$
\begin{equation*}
\rho\left(\boldsymbol{R}, \boldsymbol{R}^{\prime}, \beta\right) \equiv\langle\boldsymbol{R}| \exp (-\beta \hat{H})\left|\boldsymbol{R}^{\prime}\right\rangle \tag{7.6}
\end{equation*}
$$

The partition function is the integral of the diagonal matrix elements over all possible configurations:

$$
\begin{equation*}
Z(N, T, V)=\int \rho(\boldsymbol{R}, \boldsymbol{R}, \beta) \mathrm{d} \boldsymbol{R} \tag{7.7}
\end{equation*}
$$

The product of two density matrices is again a density matrix:

$$
\begin{equation*}
\exp \left(-\left(\beta_{1}+\beta_{2}\right) \hat{H}\right)=\exp \left(-\beta_{1} \hat{H}\right) \exp \left(-\beta_{2} \hat{H}\right) \tag{7.8}
\end{equation*}
$$

This property, often referred to as 'product property', written in coordinate representation gives a convolution integral:

$$
\begin{equation*}
\rho\left(\boldsymbol{R}_{1}, \boldsymbol{R}_{3}, \beta_{1}+\beta_{2}\right)=\int \rho\left(\boldsymbol{R}_{1}, \boldsymbol{R}_{2}, \beta_{1}\right) \rho\left(\boldsymbol{R}_{2}, \boldsymbol{R}_{3}, \beta_{2}\right) \mathrm{d} \boldsymbol{R}_{2} . \tag{7.9}
\end{equation*}
$$

If we apply the product property $M$ times we obtain the density matrix at the inverse temperature $\beta$ as the product of $M$ density matrices at the inverse temperature $\tau=$ $\beta / M$. In operator form:

$$
\begin{equation*}
\exp (-\beta \hat{H})=(\exp (-\tau \hat{H}))^{M} \tag{7.10}
\end{equation*}
$$

We call time step the quantity $\tau$. Eq. (7.10) written in coordinate representation becomes:

$$
\begin{align*}
& \rho\left(\boldsymbol{R}_{1}, \boldsymbol{R}_{M+1}, \beta\right)=\int \cdots \int \mathrm{d} \boldsymbol{R}_{2} \mathrm{~d} \boldsymbol{R}_{3} \cdots \mathrm{~d} \boldsymbol{R}_{M} \\
& \qquad \rho\left(\boldsymbol{R}_{1}, \boldsymbol{R}_{2}, \tau\right) \rho\left(\boldsymbol{R}_{2}, \boldsymbol{R}_{3}, \tau\right) \cdots \rho\left(\boldsymbol{R}_{M}, \boldsymbol{R}_{M+1}, \tau\right) . \tag{7.11}
\end{align*}
$$

Eq. (7.11) is not useful as it is since the density matrices $\rho\left(\boldsymbol{R}_{j}, \boldsymbol{R}_{j+1}, \tau\right)$ are, in general, unknown quantities. We note, however, that if $M$ is a large number, then the time-step $\tau$, which corresponds to the high temperature $M \tau$, is small. If in eq. (7.11) we replace the exact density matrix $\rho\left(\boldsymbol{R}_{j}, \boldsymbol{R}_{j+1}, \tau\right)$ with a 'short time' or 'high temperature' approximation we obtain a multidimensional integral of known functions. Furthermore, in coordinate representation the density matrix is positive definite. It is known that many-variable integrals of positive functions can be calculated efficiently by means of Monte Carlo methods.
The simplest expression for the 'high temperature' density matrix is the so called primitive approximation. It consists in neglecting all terms beyond the one which is linear in $\tau$ in the left-hand side exponent of the following operator identity (Baker-CampbellHausdorff relation):

$$
\begin{equation*}
\exp \left(-\tau(\hat{T}+\hat{V})+\frac{\tau^{2}}{2}[\hat{T}, \hat{V}]+\cdots\right)=\exp (-\tau \hat{T}) \exp (-\tau \hat{V}) \tag{7.12}
\end{equation*}
$$

(In this equation dots indicate terms which contain powers of $\tau$ higher than the second.) One obtains the following approximate expression for the density matrix operator:

$$
\begin{equation*}
\exp (-\tau \hat{H}) \cong \exp (-\tau \hat{T}) \exp (-\tau \hat{V}) \tag{7.13}
\end{equation*}
$$

It is easy to write the matrix elements of the kinetic density matrix $\exp (-\tau \hat{T})$ and the potential density matrix $\exp (-\tau \hat{V})$ in coordinate representation. The latter is diagonal:

$$
\begin{equation*}
\left\langle\boldsymbol{R}_{i}\right| \exp (-\tau \hat{V})\left|\boldsymbol{R}_{i+1}\right\rangle=\exp \left(-\tau V\left(\boldsymbol{R}_{i}\right)\right) \delta\left(\boldsymbol{R}_{i}-\boldsymbol{R}_{i+1}\right), \tag{7.14}
\end{equation*}
$$

given that we consider potentials that are diagonal in coordinate space. The former, in free space, is a gaussian propagator (see section 7.1.2):

$$
\begin{equation*}
\left\langle\boldsymbol{R}_{i}\right| \exp (-\tau \hat{T})\left|\boldsymbol{R}_{i+1}\right\rangle=\left(2 \pi \hbar^{2} \tau / m\right)^{-d N / 2} \exp \left[-\frac{\left(\boldsymbol{R}_{i}-\boldsymbol{R}_{i+1}\right)^{2}}{2 \hbar^{2} \tau / m}\right] \tag{7.15}
\end{equation*}
$$

For later convenience we introduce the following definition:

$$
\begin{equation*}
\rho^{\text {free }}\left(\boldsymbol{R}, \boldsymbol{R}^{\prime}, \tau\right) \equiv\left(2 \pi \hbar^{2} \tau / m\right)^{-d N / 2} \exp \left[-\frac{\left(\boldsymbol{R}-\boldsymbol{R}^{\prime}\right)^{2}}{2 \hbar^{2} \tau / m}\right] \tag{7.16}
\end{equation*}
$$

In the limit of large Trotter number $M$ equation (7.10) remains exact if we use the primitive approximation eq. (7.12) in its right hand side. This is guaranteed by the Trotter formula:

$$
\begin{equation*}
\exp (-\beta(\hat{T}+\hat{V}))=\lim _{M \rightarrow+\infty}[\exp (-\tau \hat{T}) \exp (-\tau \hat{V})]^{M} \tag{7.17}
\end{equation*}
$$

which holds for any pairs of operators bounded from below. The kinetic operator $\hat{T}$ and the potential operators $\hat{V}$ of interest to us satisfy this requirement. To make the
consequence of the Trotter formula explicit in coordinate representation we substitute the matrix elements of the kinetic and the potential density matrices eqs. (7.15) and (7.14) in the path-integral formula (7.11). We arrive at the following $d N(M-1)$ dimensional integral:

$$
\begin{equation*}
\rho\left(\boldsymbol{R}_{1}, \boldsymbol{R}_{M+1}, \beta\right) \cong \int \cdots \int \prod_{j=2}^{M} \mathrm{~d} \boldsymbol{R}_{j} \prod_{j=1}^{M}\left\{\rho^{\text {free }}\left(\boldsymbol{R}_{j}, \boldsymbol{R}_{j+1}, \tau\right) \exp \left[-\tau V\left(\boldsymbol{R}_{j}\right)\right]\right\} \tag{7.18}
\end{equation*}
$$

The Trotter formula guarantees that in the limit $M \rightarrow \infty$ this is an exact equation. If $M$ is a large, but finite, number the integral (7.18) can be computed using the Monte Carlo procedure. One big issue is the determination of the lowest value of $M$ for which the systematic error due to $M$ being finite is smaller than the unavoidable statistical error associated to the Monte Carlo evaluation.

At this point it is useful to introduce some definitions we will employ extensively in the next lectures.

Many-particle path: also called 'system configuration', it is the set of the $d N M$ coordinates $\boldsymbol{R}_{1}, \boldsymbol{R}_{2}, \ldots, \boldsymbol{R}_{M}$.

Time-slice: the $j$-th term of a system configuration, indicated with $\boldsymbol{R}_{j}$, contains the $d N$ coordinates of the $N$ particles at imaginary time $(j-1) \tau$ and will be called 'time-slice'.

World line: the 'world line' $i$ is the set of coordinates describing the path of the particle $i$ in imaginary time: $\left\{\boldsymbol{r}_{1}^{i}, \boldsymbol{r}_{2}^{i}, \ldots, \boldsymbol{r}_{j}^{i}, \ldots, \boldsymbol{r}_{M}^{i}\right\}$.
Bead: we call 'beads' the $M$ components of a world line.
The trace of the density matrix (7.18) gives the partition function:

$$
\begin{align*}
Z(N, V, T)=\int \rho\left(\boldsymbol{R}_{1}, \boldsymbol{R}_{1}, \beta\right) \mathrm{d} \boldsymbol{R}_{1}= & \int \cdots \int \prod_{j=1}^{M} \mathrm{~d} \boldsymbol{R}_{j} \\
& \prod_{j=1}^{M}\left\{\rho^{\mathrm{free}}\left(\boldsymbol{R}_{j}, \boldsymbol{R}_{j+1}, \tau\right) \exp \left[-\tau V\left(\boldsymbol{R}_{j}\right)\right]\right\} \tag{7.19}
\end{align*}
$$

For distinguishable particles $\boldsymbol{R}_{M+1} \equiv \boldsymbol{R}_{1}$. Note that eq. (7.19) represents the partition function of a classical system of polymers. Every polymer is a necklace of beads interacting as if they were connected by ideal springs. This harmonic interaction is due to the kinetic density matrix. In the primitive approximation beads with the same imaginary time index $j$, i.e., belonging to the same time-slice, interact with the inter-particle potential $v(r)$. With higher order approximations one generally introduces effective interparticle interactions. This is the famous mapping of quantum to classical systems introduced by Feynman to describe the properties of superfluid helium. Each quantum particle has been substituted by a classical polymer. The size of polymers is of order $\lambda_{T}=\sqrt{2 \pi \hbar^{2} \beta / m}$, the de Broglie thermal wave-length, and represents the indetermination on the position of the corresponding quantum particle. In the section 7.1.3 we will
see how the indistinguishability of identical particles modifies the 'polymer' description of the quantum many body system.

### 7.1.1 Analogy inverse temperature - imaginary time

In the previous sections we have shown that the partition function of a quantum system can be decomposed using path-integrals. It is interesting to notice that a path-integral can be regarded as a time-evolution in imaginary time. To understand this, let us consider the time-dependent Schrödinger equation:

$$
\begin{equation*}
i \hbar \frac{\partial}{\partial t} \phi(\boldsymbol{R}, t)=\hat{H} \phi(\boldsymbol{R}, t) \tag{7.20}
\end{equation*}
$$

The Green's function of eq. (7.20) is:

$$
\begin{equation*}
G\left(\boldsymbol{R}, \boldsymbol{R}^{\prime}, t\right)=\langle\boldsymbol{R}| \exp (-i t / \hbar \hat{H})\left|\boldsymbol{R}^{\prime}\right\rangle . \tag{7.21}
\end{equation*}
$$

It is the solution of the Schrödinger equation with the initial condition $\phi(\boldsymbol{R}, 0)=$ $\delta\left(\boldsymbol{R}-\boldsymbol{R}^{\prime}\right)$. It governs the time-evolution of the wave function. In fact, using the Green's function one can write the differential equation (7.20) in the integral form:

$$
\begin{equation*}
\phi(\boldsymbol{R}, t)=\int G\left(\boldsymbol{R}, \boldsymbol{R}^{\prime}, t\right) \phi\left(\boldsymbol{R}^{\prime}, 0\right) \mathrm{d} \boldsymbol{R}^{\prime} . \tag{7.22}
\end{equation*}
$$

Now, we can notice that eq. (7.21) is analogous to the thermal density matrix (7.6) once one substitutes $\beta \rightarrow i t / \hbar$ in eq. (7.6).

### 7.1.2 Free-particle density matrix

Let us consider a free particle in 1D. The Hamiltonian describing this system is:

$$
\begin{equation*}
\hat{H}=-\frac{\hbar^{2}}{2 m} \frac{\mathrm{~d}^{2}}{\mathrm{~d} x^{2}} \tag{7.23}
\end{equation*}
$$

It is easy to determine the thermal density matrix corresponding to this Hamiltonian. We start from the definition:

$$
\begin{equation*}
\rho\left(x, x^{\prime}, \beta\right)=\langle x| \exp (-\beta \hat{H})\left|x^{\prime}\right\rangle ; \tag{7.24}
\end{equation*}
$$

We introduce twice the completeness relation $\int|p\rangle\langle p| \mathrm{d} p=\boldsymbol{I}$, where $|p\rangle$ are the eigenstates of the momentum operator:

$$
\begin{align*}
& \rho\left(x, x^{\prime}, \beta\right)=\int \mathrm{d} p \int \mathrm{~d} p^{\prime}\langle x \mid p\rangle\langle p| \exp (-\beta \hat{H})\left|p^{\prime}\right\rangle\left\langle p^{\prime} \mid x^{\prime}\right\rangle= \\
& \frac{1}{2 \pi} \int \mathrm{~d} p / \hbar \exp \left(i\left(x-x^{\prime}\right) p / \hbar\right) \exp \left(-\frac{\beta}{2 m} p^{2}\right) . \tag{7.25}
\end{align*}
$$

Here we have used the expression of the momentum eigenstates is coordinate space $\langle x \mid p\rangle=\frac{1}{\sqrt{2 \pi \hbar}} \exp (i x p / \hbar)$, and their orthogonality $\left\langle p \mid p^{\prime}\right\rangle=\delta\left(p-p^{\prime}\right)$. In the last integral in eq. (7.25) we recognize the inverse-Fourier transform of a Gaussian function. The Fourier transform $F(k)$ of the function $f(x)=\exp \left(-x^{2} /\left(4 a^{2}\right)\right)$ is again a Gaussian function:

$$
\begin{equation*}
F(k)=\sqrt{2 a^{2}} \exp \left(-a^{2} k^{2}\right) . \tag{7.26}
\end{equation*}
$$

Using this result in eq. (7.25) we obtain that the free-particle density matrix is a Gaussian propagator:

$$
\begin{equation*}
\rho\left(x, x^{\prime}, \beta\right)=\sqrt{\frac{m}{2 \pi \beta \hbar^{2}}} \exp \left(-\frac{m}{2 \beta \hbar^{2}}\left(x-x^{\prime}\right)^{2}\right) . \tag{7.27}
\end{equation*}
$$

### 7.1.3 Bose symmetry

The expression (7.19) for the partition function is not symmetrical under particle exchange, so it holds for distinguishable particles only. The correct expression for identical particles obeying Bose (Fermi) statistics should be symmetrical (anti-symmetrical) under particle exchange. A convenient way to symmetrize the density matrix (7.18) is to sum over all possible permutations of the particle labels in one of the two arguments:

$$
\begin{equation*}
\rho_{\text {Bose }}\left(\boldsymbol{R}_{1}, \boldsymbol{R}_{2}, \beta\right)=\frac{1}{N!} \sum_{P} \rho\left(\boldsymbol{R}_{1}, \mathbf{P} \boldsymbol{R}_{2}, \beta\right) \tag{7.28}
\end{equation*}
$$

where $\mathbf{P}$ is one of the $N$ ! permutations of the particle labels; this means that $\mathbf{P R}=$ $\left(\boldsymbol{r}^{p(1)}, \boldsymbol{r}^{p(2)}, \ldots, \boldsymbol{r}^{p(N)}\right)$, where $p(i)$, with $i=1,2, \ldots, N$, is the particle label in permutation with the $i$-th particle. If we trace the symmetrized density matrix eq. (7.28) we obtain the partition function for identical Bose particles:

$$
\begin{align*}
& Z_{\text {Bose }}(N, V, T)=\frac{1}{N!} \sum_{P} \int \cdots \int \prod_{j=1}^{M} \mathrm{~d} \boldsymbol{R}_{j} \\
& \prod_{j=1}^{M}\left\{\rho^{\text {free }}\left(\boldsymbol{R}_{j}, \boldsymbol{R}_{j+1}, \tau\right) \exp \left[-\tau V\left(\boldsymbol{R}_{j}\right)\right]\right\} \tag{7.29}
\end{align*}
$$

with the new boundary condition $\boldsymbol{R}_{M+1}=\mathbf{P} \boldsymbol{R}_{1}$. As a consequence of symmetrization the necklaces constituting the polymers are not closed on themselves. The last bead of the $i$-th world line, $\boldsymbol{r}_{M}^{i}$, is connected to the first bead of the $p(i)$-th world-line, $\boldsymbol{r}_{1}^{p(i)}$. At low temperatures, where the thermal wave-length $\lambda_{T}$ is comparable to the average inter-particle distance, large permutations cycles form. These are responsible for macroscopic quantum phenomena such as superfluidity and Bose-Einstein condensation.
An exact evaluation of the $N$ ! addends summed in eq.(7.29) becomes soon unfeasible by increasing $N$. Fortunately, all terms are positive definite, then we can still arrange a Monte Carlo procedure for the evaluation of eq. (7.29). If we considered Fermi particles, an additional ' + ' or ' - ' sign would appear in front of each term, the former for even permutations, the latter for odd permutations. A Monte Carlo evaluation of the Fermi partition function would lead to an exponentially small signal to noise ratio going to
small $T$ and large $N$. As a consequence of this sign problem the path-integral calculation becomes unfeasible unless one introduces some systematic approximations.

### 7.1.4 Path sampling methods

In this section we describe the Monte Carlo procedure to sample path-integrals.
One has to set a random walk through configuration space. Let $P\left(X, X^{\prime}\right)$ be the probability to jump from configuration $X$ to $X^{\prime}$. One can prove that if the transition matrix $P\left(X, X^{\prime}\right)$ satisfies the detailed balance condition:

$$
\begin{equation*}
\pi(X) P\left(X, X^{\prime}\right)=\pi\left(X^{\prime}\right) P\left(X^{\prime}, X\right) \tag{7.30}
\end{equation*}
$$

then the random walk samples points with probability $\pi(X)$.
One very flexible algorithm that satisfies eq. (7.30) is the famous Metropolis algorithm. This algorithm is divided in two steps. The first is the proposal of a transition from point $X$ to $X^{\prime}$ with an arbitrary probability $T\left(X, X^{\prime}\right)$. The second consists in an acceptance/rejection stage. The proposal is accepted with the probability defined by:

$$
\begin{equation*}
A\left(X, X^{\prime}\right)=\min \left(1, \chi\left(X, X^{\prime}\right)\right) \tag{7.31}
\end{equation*}
$$

where

$$
\begin{equation*}
\chi\left(X, X^{\prime}\right)=\frac{\pi\left(X^{\prime}\right) T\left(X^{\prime}, X\right)}{\pi(X) T\left(X, X^{\prime}\right)} . \tag{7.32}
\end{equation*}
$$

If, for example, we choose to displace one bead, say $\boldsymbol{r}_{j}^{i}$, to another point, call it $\boldsymbol{r}_{j}^{i \prime}$, that we sample uniformly from a sphere with center in the old position, then one has that $T\left(X^{\prime}, X\right)=T\left(X, X^{\prime}\right)$ by symmetry and that the probability to accept the move is determined by

$$
\begin{equation*}
\chi\left(X, X^{\prime}\right)=\frac{\exp \left[-\frac{\left(\boldsymbol{r}_{j-1}^{i}-\boldsymbol{r}_{j}^{i \prime}\right)^{2}+\left(\boldsymbol{r}_{j}^{i \prime}-\boldsymbol{r}_{j+1}^{i}\right)^{2}}{2 \hbar^{2} \tau / m}\right]}{\exp \left[-\frac{\left(\boldsymbol{r}_{j-1}^{i}-\boldsymbol{r}_{j}^{i}\right)^{2}+\left(\boldsymbol{r}_{j}^{i}-\boldsymbol{r}_{j+1}^{i}\right)^{2}}{2 \hbar^{2} \tau / m}\right]} \exp \left[-\tau\left(V\left(\boldsymbol{R}_{j}^{\prime}\right)-V\left(\boldsymbol{R}_{j}\right)\right)\right] . \tag{7.33}
\end{equation*}
$$

This type of 'single bead' move becomes extremely inefficient when the number of time-slices $M$ increases (critical slowing down), so one faces ergodicity problems. To increase efficiency one can implement a direct sampling of the kinetic-energy part of the probability distribution for one bead or for a larger piece of a word-line. There are several algorithms that permit drawing a free-particle path (see references). With this type of move rejections are only determined by inter-particle interactions and/or external potentials.

### 7.1.5 Calculating properties

The expectation value of any operator $\hat{O}$ associated to a physical observable can be written as a path integral in the following form:

$$
\begin{equation*}
\bar{O} \equiv\langle O(X)\rangle \equiv \frac{1}{N!} \sum_{P} \int O(X) \pi(X, \mathbf{P}) \mathrm{d} X \tag{7.34}
\end{equation*}
$$

The energy per particle $E / N$ of a quantum many body system is the expectation value of the Hamiltonian operator $\hat{H}$ divided by the number of particles $N$. According to its thermodynamic definition we can also obtain $E / N$ through a $\beta$-derivative of the partition function $Z$ :

$$
\frac{E(N, V, \beta)}{N}=-\frac{1}{N Z} \frac{\partial Z(N, V, \beta)}{\partial \beta} .
$$

If we apply this derivative to the symmetrized partition function defined in eq. (7.29) we obtain the following estimator for the energy per particle (called thermodynamic estimator):

$$
\begin{equation*}
\frac{E_{\mathrm{th}}}{N}=\left\langle\frac{d}{2 \tau}-\frac{m}{2(\hbar \tau)^{2} M N} \sum_{j=1}^{M}\left(\boldsymbol{R}_{j}-\boldsymbol{R}_{j+1}\right)^{2}+\frac{1}{M N} \sum_{j=1}^{M} V\left(\boldsymbol{R}_{j}\right)\right\rangle . \tag{7.35}
\end{equation*}
$$

### 7.1.6 Useful references

- A statistical approach to Quantum Mechanics, by M. Creutz and B. Freedman, Annals of Physics 132 (1981) 427.
- A Java demonstration of Path integral Monte Carlo by A. Santamaria can be found at http://fisteo12.ific.uv.es/~santamar/qapplet/metro.html. Note that the parameters of the quartic potential can be adjusted interactively.
- D. M. Ceperley, Review of Modern Physics 67, 279 (1995).


### 7.2 Diffusion Monte Carlo

Diffusion Monte Carlo (DMC) is a tool to study the ground-state properties of quantum systems. This means that using DMC one can simulate many-body systems at zero temperature. When applied to bosons, DMC provides the exact result for the ground-state energy and for other diagonal properties. By introducing some approximation, one can also treat fermionic systems. One approximation which has proven to be reliable is the so-called fixed-node approximation. Similarly, one can extend DMC to study excited states.

DMC is based on the solution of the time-dependent Schrödinger equation written in imaginary time:

$$
\begin{equation*}
-\frac{\partial}{\partial \beta} \phi(\boldsymbol{R}, \beta)=\hat{H} \phi(\boldsymbol{R}, \beta), \tag{7.36}
\end{equation*}
$$

where $\beta=i t / \hbar$. The formal solution of eq. (7.36) is:

$$
\begin{equation*}
\phi(\boldsymbol{R}, \beta)=\exp (-\beta \hat{H}) \phi(\boldsymbol{R}, 0) . \tag{7.37}
\end{equation*}
$$

Let us expand $\phi(\boldsymbol{R}, \beta)$ on the basis of the eigenstates $\phi_{n}(\boldsymbol{R}, \beta)$ :

$$
\begin{equation*}
\phi(\boldsymbol{R}, \beta)=\sum_{n=0}^{\infty} c_{n} \phi_{n}(\boldsymbol{R}, \beta)=\sum_{n=0}^{\infty} c_{n} \phi_{n}(\boldsymbol{R}) \exp \left(-E_{n} \beta\right) . \tag{7.38}
\end{equation*}
$$

The states $\phi_{n}$ are the solution of the time independent Schrödinger equation $\hat{H} \phi_{n}=$ $E_{n} \phi_{n}$ with eigenvalues $E_{n}$. We order them in such a way that $E_{n}$ monotonically increases with the quantum number $n$. In the long time limit $\beta \rightarrow \infty$ eq. (7.38) reduces to:

$$
\begin{equation*}
\phi(\boldsymbol{R}, \beta) \approx c_{0} \phi_{0}(\boldsymbol{R}) \exp \left(-E_{0} \beta\right) \tag{7.39}
\end{equation*}
$$

In other words, the contribution of the ground state dominates the sum in eq. (7.38). States with $n \neq 0$ decay exponentially faster. In the following we will see that by introducing an energy shift we can obtain a normalized wave function.
In the case of Bose systems at zero temperature one can assume, without loss of generality, that $\phi_{0}(\boldsymbol{R})$ is real and positive definite ${ }^{1}$. Fermi systems and excited stated of bosons will be addressed in subsection 7.2.2.
Let us introduce the Green's function of eq. (7.36):

$$
\begin{equation*}
\rho\left(\boldsymbol{R}, \boldsymbol{R}^{\prime}, \beta\right)=\langle\boldsymbol{R}| \exp (-\beta \hat{H})\left|\boldsymbol{R}^{\prime}\right\rangle . \tag{7.40}
\end{equation*}
$$

Notice that $\rho\left(\boldsymbol{R}, \boldsymbol{R}^{\prime}, \beta\right)$ is equal to the thermal density matrix (7.6). The Green's function permits to write the eq. (7.36) in the integral form:

$$
\begin{equation*}
\phi(\boldsymbol{R}, \beta)=\int \rho\left(\boldsymbol{R}, \boldsymbol{R}^{\prime}, \beta\right) \phi\left(\boldsymbol{R}^{\prime}, 0\right) \mathrm{d} \boldsymbol{R}^{\prime} . \tag{7.41}
\end{equation*}
$$

This integral equation may be interpreted as a diffusion process guided by $\rho\left(\boldsymbol{R}, \boldsymbol{R}^{\prime}, \beta\right)$ from the initial state $\phi\left(\boldsymbol{R}^{\prime}, 0\right)$ to the final state $\phi(\boldsymbol{R}, \beta)$ at time $\beta$.
The evolution during the long time interval $\beta$ can be generated repeating a large number of short time-steps $\tau$. In the limit $\tau \rightarrow 0$, one can make use of the primitive approximation (see section 7.1):

$$
\begin{equation*}
\rho\left(\boldsymbol{R}_{1}, \boldsymbol{R}_{3}, \tau\right) \approx\left(\frac{m}{2 \pi \hbar^{2} \tau}\right)^{d N / 2} \exp \left[-\frac{\left(\boldsymbol{R}_{1}-\boldsymbol{R}_{2}\right)^{2}}{2 \hbar^{2} \tau / m}\right] \exp \left[-\tau V\left(\boldsymbol{R}_{2}\right)\right] \delta\left(\boldsymbol{R}_{2}-\boldsymbol{R}_{3}\right) \tag{7.42}
\end{equation*}
$$

In a DMC simulation, one treats $\phi(\boldsymbol{R}, \beta)$ as the density distribution of a large ensemble of equivalent copies of the many-body system, usually called walkers. The simulation starts with an arbitrary initial distribution. The population of walkers diffuses according to the Green's function (7.42). The first term corresponds to a free-particle diffusion, which can be implemented by adding to $\boldsymbol{R}_{1}$ a vector whose components are sampled from a gaussian distribution. The second term in eq. (7.42), instead, does not cause displacement of particles. It only determines a change in the probability density. This effect, usually called branching, can be implemented by allowing variations in the number of walkers. We have to assign to each walker a number of descendant $n_{d}$ proportional to the weight $\exp \left[-\tau\left(V\left(\boldsymbol{R}_{2}\right)-E\right)\right]$. Notice that we have included the energy shift $E$, which serves to normalize the density distribution. One could simply set $n_{d}$ to be equal to the integer number which is closest to $w$. However, this discretization of the weight $w$ would result in a considerable loss of information. A much more efficient procedure is obtained by calculating $n_{d}$ according to the following rule:

$$
\begin{equation*}
n_{d}=\operatorname{int}(w+\eta) \tag{7.43}
\end{equation*}
$$

[^9]where $\eta$ is a uniform random variable in the range $[0,1]$, and the function int() takes the integer part of the argument. In this way one makes use of the full information contained in the signal $w$. If $n_{d}>1$, one has to create $n_{d}-1$ identical copies of the walker and include them in the total population. If $n_{d}=0$, one has to erase the current walker from the population. The parameter $E$ acts as a normalization factor. It must be adjusted during the simulation in order to maintain the total number of walkers close to an average value, call it $n_{\text {ave }}$. This is an algorithm parameter which has to be optimized. For small values of $n_{\text {ave }}$ one has systematic deviations from the exact results. On the other hand, large values of $n_{\text {ave }}$ result in computationally demanding simulations.
If we generate a long random walk performing sequentially the two types of update that we have described, the asymptotic distribution $\phi(\boldsymbol{R}, \beta \rightarrow \infty)$ converges to the exact ground state $\phi_{0}(\boldsymbol{R})$.

### 7.2.1 Importance Sampling

The algorithm described in the previous subsection is extremely inefficient for large particle numbers, especially if the inter-particle interaction is not smooth. The efficiency can be enormously enhanced by using the importance sampling technique. To implement this method one has to design a trial wave function, call it $\phi_{\mathrm{T}}$, that approximately describes the exact ground-state $\phi_{0}$. For example, in the case of homogeneous liquid or gases an accurate approximation of the ground-state is given by the Jastrow wave function:

$$
\begin{equation*}
\phi_{\mathrm{J}}(\boldsymbol{R})=\prod_{i<j} f_{2}\left(\left|\boldsymbol{r}_{i}-\boldsymbol{r}_{j}\right|\right) \tag{7.44}
\end{equation*}
$$

where the function $f_{2}(r)$ describes the direct correlation between particles $i$ and $j$. In dilute systems, like ultracold gases, is can be set equal to the solution of the two-body problem for the relative motion of the pair.
One then solves the modified Schrödinger equation (in imaginary time) for the product $f(\boldsymbol{R}, \beta)=\phi_{\mathrm{T}}(\boldsymbol{R}) \phi(\boldsymbol{R}, \beta):$

$$
\begin{equation*}
-\frac{\partial}{\partial \beta} f(\boldsymbol{R}, \beta)=-\frac{\hbar^{2}}{2 m} \Delta f(\boldsymbol{R}, \beta)+\frac{\hbar^{2}}{2 m} \nabla(\boldsymbol{F} f(\boldsymbol{R}, \beta))+\left(E_{\mathrm{loc}}(\boldsymbol{R})-E\right) f(\boldsymbol{R}, \beta) \tag{7.45}
\end{equation*}
$$

where $\boldsymbol{F}=\frac{2 \nabla \phi_{\mathrm{T}}(\boldsymbol{R})}{\phi_{\mathrm{T}}(\boldsymbol{R})}$ is called pseudo force and the local energy $E_{\mathrm{loc}}(\boldsymbol{R})$ is defined by:

$$
\begin{equation*}
E_{\mathrm{loc}}(\boldsymbol{R})=\frac{\hat{H} \phi_{\mathrm{T}}(\boldsymbol{R})}{\phi_{\mathrm{T}}(\boldsymbol{R})} \tag{7.46}
\end{equation*}
$$

The function $f(\boldsymbol{R}, \beta)$ is interpreted as density distribution of the population of walkers. In the long time limit it converges to the product $\phi_{\mathrm{T}}(\boldsymbol{R}) \phi_{0}(\boldsymbol{R})$. It is easy to see that the average of the local energy (7.46) is equal to the ground-state energy. Instead, for observable operators that do not commute with the Hamiltonian, one obtains the mixed estimator $\left\langle\phi_{0}\right| \hat{O}\left|\phi_{\mathrm{T}}\right\rangle /\left\langle\phi_{0} \mid \phi_{\mathrm{T}}\right\rangle .{ }^{2}$

[^10]The diffusion process that solves eq. (7.45) is similar to the one described above. The free-particle diffusion must be implemented in the same way. Between this free-particle diffusion and the branching term, one must introduce an additional update which consists in a drift of particle coordinates guided by the pseudo-force $\boldsymbol{F}$ :

$$
\begin{equation*}
\boldsymbol{R}_{2}=\boldsymbol{R}_{1}+\frac{\hbar^{2} \tau}{2 m} \boldsymbol{F}\left(\boldsymbol{R}_{1}\right) \tag{7.47}
\end{equation*}
$$

This drift guides the walkers in regions with high probability. The branching term has to be implemented similarly to what described before, but substituting the local energy $E_{\text {loc }}(\boldsymbol{R})$ to the bare potential $V(\boldsymbol{R})$. In fact, with an accurate choice of the trial wave function $\phi_{\mathrm{T}}$, the local energy has small fluctuations. This permits to stabilize the populations of walkers, which, if no importance sampling was implemented, would instead oscillate widely rendering the simulation unfeasible.

### 7.2.2 Fixed Node Diffusion Monte Carlo

The conclusion that the DMC algorithm samples, after long times, a density distribution proportional to the exact ground state $\phi_{0}$, is based on the hypothesis that $\phi_{0}$ and $\psi_{\mathrm{T}}$ are not orthogonal. If, instead, they are orthogonal, the asymptotic distribution is proportional to the lowest excited state $\phi_{1}$ not orthogonal to $\psi_{\mathrm{T}}$. This property is often used to simulate excited states of bosons or the ground state of fermions, which can be considered as the first fully antisymmetric eigenstate of the Hamiltonian. Having to deal with non-positive definite wave functions introduces the well known sign problem. Several procedures exist to circumvent this pathology. Here we describe the fixed-node approximation. This approximation consists in forcing the ground state of the Fermi system $\phi_{\mathrm{F}}$ to have the same nodal structure as the trial wave function. It is evident that, if $\phi_{\mathrm{F}}$ and $\psi_{\mathrm{T}}$ change sign together, the probability distribution is always positive. It can be proven that the fixed-node constraint provides an upper bound to the ground-state energy of fermions. In particular, if the nodes of $\psi_{\mathrm{T}}$ were exact, the FNDMC would provide the exact ground-state energy. In a DMC simulation, the nodal constraint on $\phi_{\mathrm{F}}$ corresponds to forcing the walkers not to cross the nodal surface.
Just to show an example, we describe now one type of antisymmetric trial wave function which has proven to capture the essential properties of several Fermi systems in the homogeneous normal phase. This is the so-called Jastrow-Slater wave function. If we consider a spin-polarized system (all fermions have the same spin-projection) in a box of size $L$ with periodic boundary conditions, the Jastrow-Slater wave function $\phi_{\text {JS }}$ is the product of a Jastrow factor (7.44) and a Slater determinant of plane waves:

$$
\begin{equation*}
\phi_{\mathrm{JS}}(\boldsymbol{R})=\phi_{\mathrm{J}}(\boldsymbol{R}) \operatorname{Det}_{\alpha, n}\left[\exp \left(i \boldsymbol{k}_{\alpha} \cdot \boldsymbol{r}_{n}\right)\right], \tag{7.48}
\end{equation*}
$$

where the index $n=1, \ldots, N$ labels particles and $\boldsymbol{k}_{\alpha}$ are the wave vectors compatible with periodic boundary conditions.
Techniques to go beyond the fixed-node approximation exist, but they have not proven to be robust. The sign problem has to be considered still unsolved.

### 7.2.3 Useful references

- J. Boronat, in Microscopic approaches to quantum liquids in confined geometries, chapter 2, ed. by E. Krotscheck and J. Navarro, World Scientific (2002).
- B. L. Hammond, W. A. Lester and Peter James Reynolds, Monte Carlo methods in Ab Initio quantum chemistry, World Scientific (1994).
- I. Kosztin, B. Faber and K. Schulten, Introduction to the Diffusion Monte Carlo Method, arXiv:physics/9702023.
- M. H. Kalos and P. A. Whitlock, Monte Carlo methods, Wiley pub. (1986).


## Chapter 8

## Electronic structure of molecules and atoms

### 8.1 Introduction

In this chapter we will discuss the arguably most important quantum many body problem - the electronic structure problem - relevant for almost all properties of matter relevant in our daily life. With $\mathrm{O}\left(10^{23}\right)$ atoms in a typical piece of matter, the exponential scaling of the Hilbert space dimension with the number of particles is a nightmare. In this chapter we will discuss first the exact solution by exact diagonalization of simplified effective models, and then approximate methods that reduce the problem to a polynomial one, typically scaling like $\mathcal{O}\left(N^{4}\right)$ and even $\mathrm{O}(N)$ in modern codes that aim for a sparse matrix structure. These methods map the problem to a single-particle problem and work only as long as correlations between electrons are weak.

This enormous reduction in complexity is however paid for by a crude approximation of electron correlation effects. This is acceptable for normal metals, band insulators and semi-conductors but fails in materials with strong electron correlations, such as almost all transition metal compounds.

### 8.2 The electronic structure problem

For many atoms (with the notable exception of Hydrogen and Helium which are so light that quantum effects are importanr in daily life), the nuclei of atoms are so much heavier than the electrons that we can view them as classical particles and can consider them as stationary for the purpose of calculating the properties of the electrons. Using this Born-Oppenheimer approximation the Hamiltonian operator for the electrons becomes

$$
\begin{equation*}
H=\sum_{i=1}^{N}\left(-\frac{\hbar^{2}}{2 m} \nabla^{2}+V\left(\vec{r}_{i}\right)\right)+\sum_{i<j} \frac{e^{2}}{\left|\overrightarrow{r_{i}}-\overrightarrow{r_{j}}\right|} \tag{8.1}
\end{equation*}
$$

where the potential of the $M$ atomic nuclei with charges $Z_{i} e$ at the locations $\vec{R}_{i}$ is given by

$$
\begin{equation*}
V(\vec{r})=-e^{2} \sum_{i=1}^{M} \frac{Z_{i}}{\left|\vec{R}_{i}-\vec{r}\right|} . \tag{8.2}
\end{equation*}
$$

The Car-Parinello method for molecular dynamics, which we will discuss later, moves the nuclei classically according to electronic forces that are calculated quantum mechanically.

Using a basis set of $L$ orbital wave functions $\left\{f_{i}\right\}$, the matrix elements of the Hamilton operator (8.1) are

$$
\begin{array}{r}
t_{i j}=\int d^{3} \vec{r} f_{i}^{*}(\vec{r})\left(-\frac{\hbar^{2}}{2 m} \nabla^{2}+V(\vec{r})\right) f_{j}(\vec{r}) \\
V_{i j k l}=e^{2} \int d^{3} \vec{r} \int d^{3} \vec{r}^{\prime} f_{i}^{*}(\vec{r}) f_{j}(\vec{r}) \frac{1}{\left|\vec{r}-\vec{r}^{\prime}\right|} f_{k}^{*}\left(\vec{r}^{\prime}\right) f_{l}\left(\vec{r}^{\prime}\right) \tag{8.4}
\end{array}
$$

and the Hamilton operator can be written in second quantized notation as

$$
\begin{equation*}
H=\sum_{i j \sigma} t_{i j} a_{i \sigma}^{\dagger} a_{j \sigma}+\frac{1}{2} \sum_{i j k l \sigma \sigma^{\prime}} V_{i j k l} a_{i \sigma}^{\dagger} a_{k \sigma^{\prime}}^{\dagger} a_{l \sigma^{\prime}} a_{j \sigma} \tag{8.5}
\end{equation*}
$$

### 8.3 Basis functions

Before attempting to solve the many body problem we will discuss basis sets for single particle wave functions.

### 8.3.1 The electron gas

For the free electron gas with Hamilton operator

$$
\begin{align*}
H & =-\sum_{i=1}^{N} \frac{\hbar^{2}}{2 m} \nabla^{2}+e^{2} \sum_{i<j} v_{e e}\left(\vec{r}_{i}, \vec{r}_{j}\right)  \tag{8.6}\\
v_{e e}\left(\vec{r}, \vec{r}^{\prime}\right) & =\frac{1}{\left|\vec{r}-\vec{r}^{\prime}\right|} \tag{8.7}
\end{align*}
$$

the ideal choice for basis functions are plane waves

$$
\begin{equation*}
\psi_{\vec{k}}(\vec{r})=\exp (-i \vec{k} \vec{r}) \tag{8.8}
\end{equation*}
$$

Such plane wave basis functions are also commonly used for band structure calculations of periodic crystals.

At low temperatures the electron gas forms a Wigner crystal. Then a better choice of basis functions are eigenfunctions of harmonic oscillators centered around the classical equilibrium positions.

### 8.3.2 Atoms and molecules

Which functions should be used as basis functions for atoms and molecules? We can let ourselves be guided by the exact solution of the Hydrogen atom and use the so-called Slater-Type-Orbitals (STO):

$$
\begin{equation*}
f_{i n l m}(r, \theta, \phi) \propto r^{n-1} e^{-\zeta_{i} r} Y_{l m}(\theta, \phi) . \tag{8.9}
\end{equation*}
$$

These wave functions have the correct asymptotic radial dependence and the correct angular dependence. The values $\zeta_{i}$ are optimized so that the eigenstates of isolated atoms are reproduced as accurately as possible.

The main disadvantage of the STOs becomes apparent when trying to evaluate the matrix elements in equation (8.4) for basis functions centered around two different nuclei at position $\vec{R}_{A}$ and $\vec{R}_{B}$. There we have to evaluate integrals containing terms like

$$
\begin{equation*}
\frac{1}{\vec{r}-\overrightarrow{r^{\prime}}} e^{-\zeta_{i}\left|\vec{r}-\vec{R}_{A}\right|} e^{-\zeta_{j}\left|\vec{r}-\vec{R}_{B}\right|} \tag{8.10}
\end{equation*}
$$

which cannot be solved in any closed form.
The Gauss-Type-Orbitals (GTO)

$$
\begin{equation*}
f_{i l m n}(\vec{r}) \propto x^{l} y^{m} z^{n} e^{-\zeta_{i} r^{2}} \tag{8.11}
\end{equation*}
$$

simplify the evaluation of matrix elements, as Gaussian functions can be integrated easily and the product of Gaussian functions centered at two different nuclei is again a single Gaussian function:

$$
\begin{equation*}
e^{-\zeta_{i}\left|\vec{r}-\vec{R}_{A}\right|^{2}} e^{-\zeta_{j}\left|\vec{r}-\vec{R}_{B}\right|^{2}}=K e^{-\zeta|\vec{r}-\vec{R}|^{2}} \tag{8.12}
\end{equation*}
$$

with

$$
\begin{align*}
K & =e^{-\frac{\zeta_{i} \zeta_{j}}{\zeta_{i}+\zeta_{j}}\left|\vec{R}_{A}-\overrightarrow{R_{B}}\right|^{2}}  \tag{8.13}\\
\zeta & =\zeta_{i}+\zeta_{j}  \tag{8.14}\\
\vec{R} & =\frac{\zeta_{i} \vec{R}_{A}+\zeta_{j} \vec{R}_{B}}{\zeta_{i}+\zeta_{j}} \tag{8.15}
\end{align*}
$$

Also the term $\frac{1}{\left|\vec{r}-\vec{r}^{\top}\right|}$ can be rewritten as an integral over a Gaussian function

$$
\begin{equation*}
\frac{1}{\left|\vec{r}-\vec{r}^{\prime}\right|}=\frac{2}{\sqrt{\pi}} \int_{0}^{\infty} d t e^{-t^{2}\left(\vec{r}-\vec{r}^{\prime}\right)^{2}} . \tag{8.16}
\end{equation*}
$$

and thus all the integrals (8.4) reduce to purely Gaussian integrals which can be performed analytically.

Independent of whether one chooses STOs or GTOs, extra care must be taken to account for the non-orthogonality of these basis functions.

### 8.3.3 Electrons in solids

Neither plane waves nor localized functions are ideal for electrons in solids. The core electrons are mostly localized and would best be described by localized basis functions as discussed in Sec. 8.3.2. The valence orbitals, on the other hand, overlap to form delocalized bands and are better described by a plane wave basis as in Sec. 8.3.1. More complicated bases sets, like linear augmented plane waves (LAPW), which smoothly cross over from localized wave function behavior near the nuclei to plane waves in the region between the atoms are used for such simulations. It is easy to imagine that a full featured electronic structure code with such basis functions gets very complicated to code.

### 8.3.4 Other basis sets

There is ongoing development of new basis sets, such as finite element or wavelet based approaches. One key problem for the simulation of large molecules is that since there are $\mathcal{O}\left(L^{4}\right)$ integrals of the type (8.4), quantum chemistry calculations typically scale as $\mathcal{O}\left(N^{4}\right)$. A big goal is thus to find smart basis sets and truncation schemes to reduce the effort to an approximately $\mathcal{O}(N)$ method, since the overlap of basis functions at large distances becomes negligibly small. The group of S. Goedecker in Basel is one of the leading groups in this area, using wavelet basis sets.

### 8.4 Pseudo-potentials

The electrons in inner, fully occupied shells do not contribute in the chemical bindings. To simplify the calculations they can be replaced by pseudo-potentials, modeling the inner shells. Only the outer shells (including the valence shells) are then modeled using basis functions. The pseudo-potentials are chosen such that calculations for isolated atoms are as accurate as possible.

### 8.5 Effective models

To understand the properties of these materials the Hamilton operator of the full quantum chemical problem (8.1) is usually simplified to effective models, which still contain the same important features, but which are easier to investigate. They can be used to understand the physics of these materials, but not directly to quantitatively fit experimental measurements.

### 8.5.1 The tight-binding model

The simplest model is the tight-binding model, which concentrates on the valence bands. All matrix elements $t_{i j}$ in equation (8.3), apart from the ones between nearest neighbor atoms are set to zero. The others are simplified, as in:

$$
\begin{equation*}
H=\sum_{\langle i, j\rangle, \sigma}\left(t_{i j} c_{i, \sigma}^{\dagger} c_{j, \sigma}+\text { H.c. }\right) \tag{8.17}
\end{equation*}
$$

This model is easily solvable by Fourier transforming it, as there are no interactions.

### 8.5.2 The Hubbard model

To include effects of electron correlations, the Hubbard model includes only the often dominant intra-orbital repulsion $V_{i i i i}$ of the $V_{i j k l}$ in equation (8.4):

$$
\begin{equation*}
H=\sum_{\langle i, j\rangle, \sigma}\left(t_{i j} c_{i, \sigma}^{\dagger} c_{j, \sigma}+\text { H.c. }\right)+\sum_{i} U_{i} n_{i, \uparrow} n_{i, \downarrow} . \tag{8.18}
\end{equation*}
$$

The Hubbard model is a long-studied, but except for the 1D case still not completely understood model for correlated electron systems.

In contrast to band insulators, which are insulators because all bands are either completely filled or empty, the Hubbard model at large $U$ is insulating at half filling, when there is one electron per orbital. The reason is the strong Coulomb repulsion $U$ between the electrons, which prohibit any electron movement in the half filled case at low temperatures.

### 8.5.3 The Heisenberg model

In this insulating state the Hubbard model can be simplified to a quantum Heisenberg model, containing exactly one spin per site.

$$
\begin{equation*}
H=\sum_{\langle i, j\rangle} J_{i j} \vec{S}_{i} \vec{S}_{j} \tag{8.19}
\end{equation*}
$$

For large $U / t$ the perturbation expansion gives $J_{i j}=2 t_{i j}^{2}\left(1 / U_{i}+1 / U_{j}\right)$. The Heisenberg model is the relevant effective models at temperatures $T \ll t_{i j}, U$ ( $10^{4} \mathrm{~K}$ in copper oxides). The derivation will be shown in the lecture.

### 8.5.4 The $t$ - $J$ model

The $t$ - $J$ model is the effective model for large $U$ at low temperatures away from halffilling. Its Hamiltonian is

$$
\begin{equation*}
H=\sum_{\langle i, j\rangle, \sigma}\left[\left(1-n_{i,-\sigma}\right) t_{i j} c_{i, \sigma}^{\dagger} c_{j, \sigma}\left(1-n_{j,-\sigma}\right)+\text { H.c. }\right]+\sum_{\langle i, j\rangle} J_{i j}\left(\vec{S}_{i} \vec{S}_{j}-n_{i} n_{j} / 4\right) . \tag{8.20}
\end{equation*}
$$

As double-occupancy is prohibited in the $t-J$ model there are only three instead of four states per orbital, greatly reducing the Hilbert space size.

### 8.6 Exact diagonalization

The most accurate method is exact diagonalization of the Hamiltonian matrix using the Lanczos algorithm, discussed in appendix A.2. The size of the Hilbert space of an $N$-site system ( $4^{N}$ for a Hubbard model , $3^{N}$ for a $t$ - $J$ model and $(2 S+1)^{N}$ for a spin- $S$ model) can be reduced by making use of symmetries. Translational symmetries can be
employed by using Bloch waves with fixed momentum as basis states. Conservation of particle number and spin allows to restrict a calculation to subspaces of fixed particle number and magnetization.

As an example we will sketch how to implement exact diagonalization for a simple one-dimensional spinless fermion model with nearest neighbor hopping $t$ and nearest neighbor repulsion $V$ :

$$
\begin{equation*}
H=-t \sum_{i=1}^{L-1}\left(c_{i}^{\dagger} c_{i+1}+\text { H.c. }\right)+V \sum_{i=1}^{L-1} n_{i} n_{i+1} . \tag{8.21}
\end{equation*}
$$

The first step is to construct a basis set. We describe a basis state using "multi-bit coding". A many-body state of fermions can be represented as an unsigned integer where bit $i$ set to one corresponds to an occupied site $i$. For spinful fermions we take either two integers, one for the up and one for the down spins, or two bits per site.

As the Hamiltonian conserves the total particle number we thus want to construct a basis of all states with $N$ particles on $L$ sites (or $N$ bits set to one in $L$ bits). In the code fragment below we use the following variables:

- states_ is a vector storing the integers whose bit patterns correspond to the basis states. It can be accessed using the following functions:
- dimension() returns the number of basis states.
- state(i) returns the $i$-th basis state, where i runs from 0 to dimension()-1.
- index_ is a much larger vector of size $2^{L}$. It is used to obtain the number of a state in the basis, given the integer representation of the state. It can be accessed using the function
- index(s) which returns the index $i$ of the state in the basis, or the largest integer to denote an invalid state, if the bit pattern of the integer does not correspond to a basis state.

Since this vector is very large, it will limit the size of system that can be studied. To save space, the index_ array could be omitted and the index(s) function implemented by a binary search on the states_ array.

Here is the $\mathrm{C}++$ code for this class:

```
#include <vector>
#include <alps/bitops.h>
#include <limits>
#include <valarray>
#include <cassert>
class FermionBasis {
public:
    typedef unsigned int state_type;
```

```
    typedef unsigned int index_type;
    FermionBasis (int L, int N);
    state_type state(index_type i) const {return states_[i];}
    index_type index(state_type s) const {return index_[s];}
    unsigned int dimension() const { return states_.size();}
private:
    std::vector<state_type> states_;
    std::vector<index_type> index_;
};
```

In the constructor we build the basis states. For $N$ spinless fermions on $L$ sites the valid basis states are all the ways to place $N$ particles on $L$ sites, which is equivalent to all integers between 0 and $2^{L}-1$ that have $N$ bits set. The constructor uses the alps::popent function of the ALPS library.

```
FermionBasis::FermionBasis(int L, int N)
{
    index_.resize(1<<L); // 2^L entries
    for (state_type s=0;s<index_.size();++s)
        if(alps::popcnt(s)==N) {
            // correct number of particles
                    states_.push_back(s);
                index_[s]=states_.size()-1;
    }
        else
            // invalid state
            index_[s]=std::numeric_limits<index_type>: :max();
}
```

Finally we want to implement a matrix-vector multiplication $v=H w$ for our Hamiltonian and derive a Hamiltonian class. We do not want to store the matrix at all, neither in dense nor in sparse form but instead implement a fast function to perform the matrix-vector multiplication on-the-fly.

```
class HamiltonianMatrix : public FermionBasis {
public:
    HamiltonianMatrix(int L, int N, double t, double V)
        : FermionBasis(L,N), t_(t), V_(V), L_(L) {}
    void multiply(std::valarray<double>& v, const std::valarray<double>& w);
private:
    double t_, V_;
    int L_;
};
```

Finally we show the implementation of the matrix-vector multiplication. It might look like magic but we will explain it all in detail during the lecture.
void HamiltonianMatrix::multiply(std::valarray<double>\& v,
const std::valarray<double>\& w)
\{
// check dimensions
assert(v.size()==dimension());
assert(w.size()==dimension());
// do the V-term
for (int i=0;i<dimension();++i) \{
state_type s = state(i);
// count number of neighboring fermion pairs
$\mathrm{v}[\mathrm{i}]=\mathrm{w}[\mathrm{i}] * \mathrm{~V}_{-} * a l \mathrm{ps}:: \operatorname{popcnt}(\mathrm{s} \&(\mathrm{~s} \gg 1))$;
\}
// do the t-term
for (int i=0;i<dimension();++i) \{
state_type s = state(i);
// inside the chain
for (int $r=0 ; r<L_{-}-1 ;++r$ ) \{
state_type shop $=s^{\wedge}(3 \ll r) ; ~ / / ~ e x c h a n g e ~ t w o ~ n e i g h b o r s ~$ index_type idx = index(shop); // get the index if(idx!=std:: numeric_limits<index_type>: :max())
v[idx]+=-t_*w[i];
\}
// across the boundary
state_type shop $=s^{\wedge}(1 \mid(1 \ll(L-1))) ; / /$ exchange the first and last
index_type idx = index(shop); // get the index
if (idx!=std::numeric_limits<index_type>: :max())
// watch out for Fermi sign since we hop over some particles v[idx]+=-t*(alps::popcnt(s\&((1<<(L-1))-2))\%2==0 ? 1 : -1)*w[i];
\}
\}

This class can now be used with the Lanczos algorithm to calculate the energies and wave functions of the low lying states of the Hamiltonian.

In production codes one uses all symmetries to reduce the dimension of the Hilbert space as much as possible. In this example translational symmetry can be used if periodic boundary conditions are applied. The implementation gets much harder then.

In order to make the implementation of exact diagonalization much easier we have generalized the expression templates technique developed by Todd Veldhuizen for array expression to expressions including quantum operators. Using this expression template
library we can write a multiplication

$$
\begin{equation*}
|\psi\rangle=H|\phi\rangle=\left(-t \sum_{i=1}^{L-1}\left(c_{i}^{\dagger} c_{i+1}+\text { H.c. }\right)+V \sum_{i}^{L-1} n_{i} n_{i+1}\right)|\phi\rangle \tag{8.22}
\end{equation*}
$$

simply as:
Range $\mathrm{i}(1, \mathrm{~L}-1)$;
$\mathrm{psi}=\operatorname{sum}(\mathrm{i},(-\mathrm{t} *(\operatorname{cdag}(\mathrm{i}) * \mathrm{c}(\mathrm{i}+1)+$ HermitianConjugate $)+\mathrm{V} * \mathrm{n}(\mathrm{i}) * \mathrm{n}(\mathrm{i}+1)) * \mathrm{phi})$;
The advantage of the above on-the-fly calculation of the matrix in the multiplication routine is that the matrix need not be stored in memory, which is an advantage for the biggest systems where just a few vectors of the Hilbert space will fit into memory.

If one is not as demanding and wants to simulate a slightly smaller system, where the (sparse) matrix can be stored in memory, then a less efficient but more flexible function can be used to create the matrix and store it in memory. Such a program is available through the ALPS project at http://alps.comp-phys.org/. It allows to perform the above calculation just by describing the lattice and model in an XML input file.

### 8.7 The Hartree Fock method

### 8.7.1 The Hartree-Fock approximation

The Hartree-Fock approximation is based on the assumption of independent electrons. It starts from an ansatz for the $N$-particle wave function as a Slater determinant of $N$ single-particle wave functions:

$$
\Phi\left(\vec{r}_{1}, \sigma_{1} ; \ldots ; \vec{r}_{N}, \sigma_{N}\right)=\frac{1}{\sqrt{N}}\left|\begin{array}{ccc}
\phi_{1}\left(\vec{r}_{1}, \sigma_{1}\right) & \cdots & \phi_{N}\left(\vec{r}_{1}, \sigma_{1}\right)  \tag{8.23}\\
\vdots & & \vdots \\
\phi_{1}\left(\vec{r}_{N}, \sigma_{N}\right) & \cdots & \phi_{N}\left(\vec{r}_{N}, \sigma_{N}\right)
\end{array}\right| .
$$

The orthogonal single particle wave functions $\phi_{\mu}$ are chosen so that the energy is minimized.

For numerical calculations a finite basis has to be introduced, as discussed in the previous section. Quantum chemists distinguish between the self-consistent-field (SCF) approximation in a finite basis set and the Hartree-Fock (HF) limit, working in a complete basis. In physics both are known as Hartree-Fock approximation.

### 8.7.2 The Hartree-Fock equations in nonorthogonal basis sets

It will be easiest to perform the derivation of the Hartree-Fock equations in a second quantized notation. To simplify the discussion we assume closed-shell conditions, where each orbital is occupied by both an electron with spin $\uparrow$ and one with spin $\downarrow$. We start by writing the Hartree Fock wave function (8.23) in second quantized form:

$$
\begin{equation*}
|\Phi\rangle=\prod_{\mu, \sigma} c_{\mu \sigma}^{\dagger}|0\rangle, \tag{8.24}
\end{equation*}
$$

where $c_{\mu \sigma}^{\dagger}$ creates an electron in the orbital $\phi_{\mu}(\mathbf{r}, \sigma)$. As these wave functions are orthogonal the $c_{\mu \sigma}^{\dagger}$ satsify the usual fermion anticommutation relations. Greek subscripts refer to the Hartree-Fock single particle orbitals and roman subscripts to the single particle basis functions. Next we expand the $c_{\mu \sigma}^{\dagger}$ in terms of the creation operators $\hat{a}_{n \sigma}^{\dagger}$ of our finite basis set:

$$
\begin{equation*}
c_{\mu \sigma}^{\dagger}=\sum_{n=1}^{L} d_{\mu n} \hat{a}_{n \sigma}^{\dagger} \tag{8.25}
\end{equation*}
$$

and find that

$$
\begin{equation*}
a_{j \sigma}|\Phi\rangle=a_{j \sigma} \prod_{\mu, \sigma^{\prime}} c_{\mu \sigma^{\prime}}^{\dagger}|0\rangle=\sum_{\nu} d_{\nu j} \prod_{\mu \sigma^{\prime} \neq \nu \sigma} c_{\mu \sigma^{\prime}}^{\dagger}|0\rangle . \tag{8.26}
\end{equation*}
$$

In order to evaluate the matrix elements $\langle\Phi| H|\Phi\rangle$ of the Hamiltonian (8.5) we introduce the bond-order matrix

$$
\begin{equation*}
P_{i j}=\sum_{\sigma}\langle\Phi| a_{i \sigma}^{\dagger} a_{j \sigma}|\Phi\rangle=2 \sum_{\nu} d_{\nu i}^{*} d_{\nu j}, \tag{8.27}
\end{equation*}
$$

where we have made use of the closed-shell conditions to sum over the spin degrees of freedom. The kinetic term of $H$ is now simply $\sum_{i j} P_{i j} t_{i j}$. Next we rewrite the interaction part $\langle\Phi| a_{i \sigma}^{\dagger} a_{k \sigma^{\prime}}^{\dagger} a_{l \sigma^{\prime}} a_{j \sigma}|\Phi\rangle$ in terms of the $P_{i j}$. We find that if $\sigma=\sigma^{\prime}$

$$
\begin{equation*}
\langle\Phi| a_{i \sigma}^{\dagger} a_{k \sigma}^{\dagger} a_{l \sigma} a_{j \sigma}|\Phi\rangle=\langle\Phi| a_{i \sigma}^{\dagger} a_{j \sigma}|\Phi\rangle\langle\Phi| a_{k \sigma}^{\dagger} a_{l \sigma}|\Phi\rangle-\langle\Phi| a_{i \sigma}^{\dagger} a_{l \sigma}|\Phi\rangle\langle\Phi| a_{k \sigma}^{\dagger} a_{j \sigma}|\Phi\rangle \tag{8.28}
\end{equation*}
$$

and if $\sigma \neq \sigma^{\prime}$ :

$$
\begin{equation*}
\langle\Phi| a_{i \sigma}^{\dagger} a_{k \sigma^{\prime}}^{\dagger} a_{l \sigma^{\prime}} a_{j \sigma}|\Phi\rangle=\langle\Phi| a_{i \sigma}^{\dagger} a_{j \sigma}|\Phi\rangle\langle\Phi| a_{k \sigma^{\prime}}^{\dagger} a_{l \sigma^{\prime}}|\Phi\rangle \tag{8.29}
\end{equation*}
$$

Then the energy is (again summing over the spin degrees of freedom):

$$
\begin{equation*}
E_{0}=\sum_{i j} t_{i j} P_{i j}+\frac{1}{2} \sum_{i j k l}\left(V_{i j k l}-\frac{1}{2} V_{i l k j}\right) P_{i j} P_{k l} . \tag{8.30}
\end{equation*}
$$

We now need to minimize the energy $E_{0}$ under the condition that the $\left|\phi_{\mu}\right\rangle$ are normalized:

$$
\begin{equation*}
1=\left\langle\phi_{\mu} \mid \phi_{\mu}\right\rangle=\sum_{i, j} d_{\mu i}^{*} d_{\mu j} S_{i j} . \tag{8.31}
\end{equation*}
$$

Using Lagrange multipliers to enforce this constraint we have to minimize

$$
\begin{equation*}
\sum_{i j} t_{i j} P_{i j}+\frac{1}{2} \sum_{i j k l}\left(V_{i j k l}-\frac{1}{2} V_{i l k j}\right) P_{i j} P_{k l}-\sum_{\mu} \epsilon_{\mu} \sum_{i, j} d_{\mu i}^{*} d_{\mu j} S_{i j} \tag{8.32}
\end{equation*}
$$

Setting the derivative with respect to $d_{\mu i}$ to zero we end up with the Hartree-Fock equations for a finite basis set:

$$
\begin{equation*}
\sum_{j=1}^{L}\left(f_{i j}-\epsilon_{\mu} S_{i j}\right) d_{\mu j}=0 \tag{8.33}
\end{equation*}
$$

where

$$
\begin{equation*}
f_{i j}=t_{i j}+\sum_{k l}\left(V_{i j k l}-\frac{1}{2} V_{i l k j}\right) P_{k l} . \tag{8.34}
\end{equation*}
$$

This is again a generalized eigenvalue problem of the form $A x=\lambda B x$ and looks like a one-particle Schrödinger equation. However, since the potential depends on the solution it is a nonlinear and not a linear eigenvalue problem. The equation is solved iteratively, always using the new solution for the potential, until convergence to a fixed point is achieved.

The eigenvalues $\epsilon_{\mu}$ of $f$ do not directly correspond to energies of the orbitals, as the Fock operator counts the $V$-terms twice. Thus we obtain the total ground state energy from the Fock operator eigenvalues by subtracting the double counted part:

$$
\begin{equation*}
E_{0}=\sum_{\mu=1}^{N} \epsilon_{\mu}-\frac{1}{2} \sum_{i j k l}\left(V_{i j k l}-\frac{1}{2} V_{i l k j}\right) P_{i j} P_{k l} \tag{8.35}
\end{equation*}
$$

### 8.7.3 Configuration-Interaction

The approximations used in Hartree-Fock and density functional methods are based on non-interacting electron pictures. They do not treat correlations and interactions between electrons correctly. To improve these methods, and to allow the calculation of excited states, often the "configuration-interaction" (CI) method is used.

Starting from the Hartree-Fock ground state

$$
\begin{equation*}
\left|\psi_{H F}\right\rangle=\prod_{\mu=1}^{N} c_{\mu}^{\dagger}|0\rangle \tag{8.36}
\end{equation*}
$$

one or two of the $c_{\mu}^{\dagger}$ are replaced by other orbitals $c_{i}^{\dagger}$ :

$$
\begin{equation*}
\left|\psi_{0}\right\rangle=\left(1+\sum_{i, \mu} \alpha_{\mu}^{i} c_{i} \dagger c_{\mu}+\sum_{i<j, \mu<\nu} \alpha_{\mu \nu}^{i j} c_{i} \dagger c_{j} \dagger c_{\mu} c_{\nu}\right)\left|\psi_{H F}\right\rangle \tag{8.37}
\end{equation*}
$$

The energies are then minimized using this variational ansatz. In a problem with $N$ occupied and $M$ empty orbitals this leads to a matrix eigenvalue problem with dimension $1+N M+N^{2} M^{2}$. Using the Lanczos algorithm the low lying eigenstates can then be calculated in $\mathrm{O}\left((N+M)^{2}\right)$ steps.

Further improvements are possible by allowing more than only double-substitutions. The optimal method treats the full quantum problem of dimension $(N+M)!/ N!M!$. Quantum chemists call this method "full-CI". Physicists simplify the Hamilton operator slightly to obtain simpler models with fewer matrix elements, and call that method "exact diagonalization". This method will be discussed later in the course.

### 8.8 Density functional theory

Another commonly used method, for which the Nobel prize in chemistry was awarded to Walter Kohn, is the density functional theory. In density functional theory the many-body wave function living in $\mathbb{R}^{3 N}$ is replaced by the electron density, which lives just in $\mathbb{R}^{3}$. Density functional theory again reduces the many body problem to a onedimensional problem. In contrast to Hartree-Fock theory it has the advantage that it
could - in principle - be exact if there were not the small problem of the unknown exchange-correlation functional.

It is based on two fundamental theorems by Hohenberg and Kohn. The first theorem states that the ground state energy $E_{0}$ of an electronic system in an external potential $V$ is a functional of the electron density $\rho(\vec{r})$ :

$$
\begin{equation*}
E_{0}=E[\rho]=\int d^{3} \vec{r} V(\vec{r}) \rho(\vec{r})+F[\rho], \tag{8.38}
\end{equation*}
$$

with a universal functional $F$. The second theorem states that the density of the ground state wave function minimizes this functional. The proof of both theorems will be shown in the lecture.

These theorems make our life very easy: we only have to minimize the energy functional and we obtain both the ground state energy and the electron density in the ground state - and everything is exact!

The problem is that, while the functional $F$ is universal, it is also unknown! Thus we need to find good approximations for the functional. One usually starts from the ansatz:

$$
\begin{equation*}
F[\rho]=E_{h}[\rho]+E_{k}[\rho]+E_{x c}[\rho] . \tag{8.39}
\end{equation*}
$$

The Hartree-term $E_{h}$ given by the Coulomb repulsion between two electrons:

$$
\begin{equation*}
E_{h}[\rho]=\frac{e^{2}}{2} \int d^{3} \vec{r} d^{3} \vec{r} \vec{r}^{\prime} \frac{\rho(\vec{r}) \rho\left(\vec{r}^{\prime}\right)}{\left|\vec{r}-\vec{r}^{\prime}\right|} . \tag{8.40}
\end{equation*}
$$

The kinetic energy $E_{k}[\rho]$ is that of a non-interacting electron gas with the same density. The exchange- and correlation term $E_{x c}[\rho]$ contains the remaining unknown contribution, which we will discuss a bit later.

To calculate the ground state density we have to minimize this energy, solving the variational problem

$$
\begin{equation*}
0=\delta E[\rho]=\int d^{3} \vec{r} \delta \rho(\vec{r})\left(V(\vec{r})+e^{2} \int d^{3} \vec{r}^{\prime} \frac{\rho\left(\vec{r}^{\prime}\right)}{\left|\vec{r}-\vec{r}^{\prime}\right|}+\frac{\delta E_{k}[\rho]}{\delta \rho(\vec{r})}+\frac{\delta E_{x c}[\rho]}{\delta \rho(\vec{r})}\right) \tag{8.41}
\end{equation*}
$$

subject to the constraint that the total electron number to be conserved

$$
\begin{equation*}
\int d^{3} \vec{r} \delta \rho(\vec{r})=0 . \tag{8.42}
\end{equation*}
$$

Comparing this variational equation to the one for noninteracting system

$$
\begin{equation*}
\left(-\frac{1}{2 m} \nabla^{2}+V_{e f f}(\vec{r})\right) \phi_{\mu}(\vec{r})=\epsilon_{\mu} \phi_{\mu}(\vec{r}), \tag{8.43}
\end{equation*}
$$

we realize that they are the same if we define the potential of the non-interacting system as

$$
\begin{equation*}
V_{e f f}(\vec{r})=V(\vec{r})+e^{2} \int d^{3} \vec{r}^{\prime} \frac{\rho\left(\vec{r}^{\prime}\right)}{\left|\vec{r}-\vec{r}^{\prime}\right|}+v_{x c}(\vec{r}), \tag{8.44}
\end{equation*}
$$

where the exchange-correlation potential is defined by

$$
\begin{equation*}
v_{x c}(\vec{r})=\frac{\delta E_{x c}[\rho]}{\delta \rho(\vec{r})} . \tag{8.45}
\end{equation*}
$$

The form (8.43) arises because we have separated the kinetic energy of the non-interacting electron system from the functional. The variation of this kinetic energy just gives the kinetic term of this Schrödinger-like equation.

The non-linear equation is again solved iteratively, making an ansatz using $N / 2$ normalized single-electron wave functions, which we occupy with spin $\uparrow$ and $\operatorname{spin} \downarrow$ electrons to get the electron density.

$$
\begin{equation*}
\rho(\vec{r})=2 \sum_{\mu=1}^{N / 2}\left|\phi_{\mu}(\vec{r})\right|^{2}, \tag{8.46}
\end{equation*}
$$

### 8.8.1 Local Density Approximation

Apart from the restricted basis set everything was exact up to this point. As the functional $E_{x c}[\rho]$ and thus the potential $v_{x c}(\vec{r})$ is not known, we need to introduce approximations.

The simplest approximation is the "local density approximation" (LDA), which replaces $v_{x c}$ by that of a uniform electron gas with the same density. Instead of taking a functional $E[\rho](\vec{r})$ which could be a function of $\rho(\vec{r}), \nabla \rho(\vec{r}), \nabla \nabla \rho(\vec{r}), \ldots$ we ignore all the gradients and just take the local density

$$
\begin{equation*}
E_{x c}[\rho](r)=E_{\mathrm{LDA}}(\rho(r)) ; \tag{8.47}
\end{equation*}
$$

Defining

$$
\begin{equation*}
r_{s}^{-1}=a_{B}\left(\frac{4 \pi}{3} \rho\right)^{1 / 3} \tag{8.48}
\end{equation*}
$$

the exchange correlation potential is

$$
\begin{equation*}
v_{x c}=-\frac{e^{2}}{a_{B}}\left(\frac{3}{2 \pi}\right)^{2 / 3} \frac{1}{r_{s}}\left[1+0.0545 r_{s} \ln \left(1+11.4 / r_{s}\right)\right] \tag{8.49}
\end{equation*}
$$

where the first part corresponds to uncorrelated electrons and the last factor is a correlation correction determined by fitting to quantum Monte Carlo (QMC) simulations of an electron gas.

### 8.8.2 Improved approximations

Improvements over the LDA have been an intense field of research in quantum chemistry. I will just mention two improvements. The "local spin density approximation" (LSDA) uses separate densities for electrons with spin $\uparrow$ and $\downarrow$. The "generalized gradient approximation" (GGA) and its variants use functionals depending not only on the density, but also on its derivatives.

### 8.9 Car-Parinello molecular dynamics

In the lecture on "Computational Statistical Physics" you have learned about the molecular dynamics method, in which atoms move on classical trajectories under forces, such
as those from the Lennard-Jones potential, which have been previously calculated in quantum mechanical simulations. It would be nicer, and more accurate, to use a full quantum mechanical force calculation at every time step instead of using such static forces that have been extracted from previous simulations.

Roberto Car (currently in Princeton) and Michele Parinello (currently at ETH) have combined density functional theory with molecular dynamics to do just that. Their method, Car-Parinello molecular dynamics (CPMD) allows much better simulations of molecular vibration spectra and of chemical reactions.

The atomic nuclei are propagated using classical molecular dynamics, but the electronic forces which move them are estimated using density functional theory:

$$
\begin{equation*}
M_{n} \frac{d^{2} \vec{R}_{n}}{d t^{2}}=-\frac{\partial E\left[\rho(\vec{r}, t), \vec{R}_{n}\right]}{\partial \vec{R}_{n}} \tag{8.50}
\end{equation*}
$$

Here $M_{n}$ and $\vec{R}_{n}$ are the masses and locations of the atomic nuclei.
As the solution of the full electronic problem at every time step is a very time consuming task we do not want to perform it all the time from scratch. Instead CPMD uses the previous values of the noninteracting electron wave functions $\left\{\phi_{\mu}\right\}$ of the DFT calculation (8.43) [don't confuse it with the Hartee-Fock orbitals!] and evolves them to the ground state for the current positions of the nuclei by an artificial molecular dynamics evolution. Hence both the nuclei $\left\{\vec{R}_{n}\right\}$ and the wave functions $\left\{\phi_{\mu}\right\}$ evolve in the same molecular dynamics scheme. The electronic degrees of freedoms are updated using an artificial dynamics:

$$
\begin{equation*}
m \frac{d^{2} \phi_{\mu}(\vec{r}, t)}{d t^{2}}=-\frac{1}{2} \frac{\delta E\left[\rho(\vec{r}, t), \vec{R}_{n}\right]}{\delta \phi_{\mu}^{\dagger}(\vec{r}, t)}+\sum_{\nu} \Lambda_{\mu \nu} \phi_{\nu}(\vec{r}, t), \tag{8.51}
\end{equation*}
$$

where $m$ is an artificial mass that needs to be chosen much lighter than the nuclear masses so that the electronic structure adapts quickly to the move of the nuclei. The Lagrange multipliers $\Lambda_{\mu \nu}$ need to be chosen to ensure proper orthonormalization of the wave functions.

Since the exact form of the artifical dynamics of the electronic structure does not matter, we can evolve the expansion coefficients $d_{\mu n}$ of an expansion in terms of the basis functions as in equation (8.25) instead of evolving the wave functions. This gives the equations of motion

$$
\begin{equation*}
m \frac{d^{2} d_{\mu n}}{d t^{2}}=-\frac{\partial E}{\partial d_{\mu n}}+\sum_{\nu} \Lambda_{\mu \nu} \sum_{l} S_{n l} d_{\nu l} \tag{8.52}
\end{equation*}
$$

There are various algorithms to determine the $\Lambda_{\mu \nu}$ so that the wave functions stay orthonormal. We refer to text books and special lectures on CPMD for details.

### 8.10 Program packages

As the model Hamiltonian and the types of basis sets are essentially the same for all quantum chemistry applications flexible program packages have been written. There is thus usually no need to write your own programs - unless you want to implement a new algorithm.

## Chapter 9

## Quantum Monte Carlo algorithms for lattice models

### 9.1 World line representations for quantum lattice models

The basic problem for Monte Carlo simulations of quantum systems is that the partition function is not a simple sum over classical configurations but an operator expression

$$
\begin{equation*}
Z=\operatorname{Tr} \exp (-\beta \mathcal{H}) \tag{9.1}
\end{equation*}
$$

where $\mathcal{H}$ is the Hamilton operator and the trace $\operatorname{Tr}$ goes over all states in the Hilbert space. Similarly the expression for an observable like the magnetization $m$ is an operator expression:

$$
\begin{equation*}
\langle m\rangle=\frac{1}{Z} \operatorname{Tr}[m \exp (-\beta \mathcal{H})], \tag{9.2}
\end{equation*}
$$

and the Monte Carlo method cannot directly be applied except in the classical case where the Hamilton operator $\mathcal{H}$ is diagonal. The first step of any QMC algorithm is thus the mapping of the quantum system to an equivalent "classical" system

$$
\begin{align*}
Z & =\operatorname{Tr} \exp (-\beta \mathcal{H})=\sum_{c} w(c)  \tag{9.3}\\
\langle m\rangle & =\frac{1}{Z} \operatorname{Tr}[m \exp (-\beta \mathcal{H})]=\frac{1}{Z} \sum_{c} m(c) w(c)=\sum_{c} m(c) P(c), \tag{9.4}
\end{align*}
$$

where $P(c)=w(c) / Z$ and the sum goes over configurations $c$ in an artificial classical system, which here will be a system of world lines.

As an introduction to the three common world line representations

- discrete time path integrals
- continuous time path integrals
- stochastic series expansion
we will first consider the special case of a single quantum mechanical spin- $1 / 2$ in a transverse and longitudinal magnetic field, before discussing the general representations in the following sections.


### 9.2 A Spin-1/2 in a Magnetic Field

The Hamilton operator for a single quantum mechanical spin- $1 / 2$ in a longitudinal magnetic field $h$ and transverse magnetic field $\Gamma$ is given by

$$
\begin{equation*}
\mathcal{H}=\mathcal{H}_{z}+\mathcal{H}_{x}=-h S^{z}-\Gamma S^{x} . \tag{9.5}
\end{equation*}
$$

Using a basis set in which the $z$-component of the spin operator is diagonal

$$
\begin{equation*}
\{|1 / 2\rangle,|-1 / 2\rangle\} \tag{9.6}
\end{equation*}
$$

the spin-1/2 operators $S^{x}$ and $S^{z}$ are given by the Pauli matrices

$$
\left.\begin{array}{rl}
S^{x} & =\frac{\hbar}{2} \sigma^{x}
\end{array}=\left(\begin{array}{cc}
0 & \hbar / 2 \\
\hbar / 2 & 0
\end{array}\right), ~ \begin{array}{cc}
\hbar / 2 & 0  \tag{9.8}\\
0 & -\hbar / 2
\end{array}\right) . ~ . ~ ل \frac{\hbar}{2} \sigma^{z}=\left(\begin{array}{c} 
\\
S^{z}=
\end{array}\right.
$$

Setting $\hbar=1$ from now on, the Hamilton operator in this basis becomes

$$
\mathcal{H}=\left(\begin{array}{cc}
-h / 2 & -\Gamma / 2  \tag{9.9}\\
-\Gamma / 2 & h / 2
\end{array}\right) .
$$

### 9.2.1 Discrete Time Path Integrals

The first representation is a path integral using discrete imaginary time steps $\Delta_{\tau}$. Since we will later take the $\Delta_{\tau} \rightarrow 0$ limit to arrive at a continuous time formulation we will just use a lowest-order approximation that will better illustrate the connection to continuous time path integrals.

We first divide the inverse temperature $\beta$ into $M$ time steps $\Delta_{\tau}=\beta / M$, arriving at a discrete time approximation of the quantum transfer matrix $\exp \left(-\Delta_{\tau} \mathcal{H}\right)$ :

$$
\begin{equation*}
\left.\exp \left(-\Delta_{\tau} \mathcal{H}\right)=U+\Delta_{\tau}^{2}\right) \tag{9.10}
\end{equation*}
$$

where we have introduced the quantum transfer matrix

$$
U=1-\Delta_{\tau} \mathcal{H}=\left(\begin{array}{cc}
1+\Delta_{\tau} h / 2 & \Delta_{\tau} \Gamma / 2  \tag{9.11}\\
\Delta_{\tau} \Gamma / 2 & 1-\Delta_{\tau} h / 2
\end{array}\right) .
$$

Since the Hamilton matrix $\mathcal{H}$ will in general be hard to exponentiate, we have approximated the exponential $\exp \left(-\Delta_{\tau} \mathcal{H}\right)$ by a lowest-order Taylor expansion. In an actual discrete time code a Suzuki-Trotter decomposition might be used instead.

In the discrete time path integral formulation, we evaluate the operator exponential in equation (9.1) by writing the trace as a sum over all basis states $|i\rangle$. Inserting $M$ sums over a complete set of states we obtain

$$
\begin{align*}
Z & \left.=\operatorname{Tr} \exp (-\beta \mathcal{H})=\operatorname{Tr} \exp \left(-\Delta_{\tau} \mathcal{H}\right)^{M}=\operatorname{Tr}\left[U+\Delta_{\tau}^{2}\right)\right]^{M} \\
& \left.=\sum_{\left(i_{1}, \ldots, i_{M}\right)}\left\langle i_{1}\right| U\left|i_{2}\right\rangle\left\langle i_{2}\right| U\left|i_{3}\right\rangle \cdots\left\langle i_{M}\right| U\left|i_{1}\right\rangle+\Delta_{\tau}\right) . \tag{9.12}
\end{align*}
$$

a)

b)

c) $\uparrow-\uparrow-\uparrow \downarrow \downarrow-\downarrow \downarrow \downarrow-\downarrow-\uparrow-\uparrow-\uparrow-\uparrow-\uparrow-\uparrow-\uparrow-\downarrow \downarrow \downarrow \downarrow \downarrow \downarrow-\uparrow-\uparrow$
d)


Figure 9.1: Relationship between discrete and continuous time path integrals illustrated for a single spin- $1 / 2$. From a), over b) to c) the time step $\Delta_{\tau}$ is reduced, approaching the continuous time limit in d). While the discrete time representations a)-c) the configuration can be stored by specifying the value of the spin at each time step, the continuous time representation d) is stored by specifying the locations $\tau_{i}$ of the domain walls and the values of the spin in each domain.

This expression is identical to the partition function of a one-dimensional chain of classical Ising spins $\sigma_{i}= \pm 1$ of length $M$ at an inverse temperature $\beta_{\mathrm{cl}}$

$$
\begin{equation*}
\mathcal{H}_{\mathrm{cl}}=-J_{\mathrm{cl}} \sum_{i=1}^{M} \sigma_{i} \sigma_{i+1}-h_{\mathrm{cl}} \sum_{i=1}^{M} \sigma_{i}+E_{0} \tag{9.13}
\end{equation*}
$$

with periodic boundary conditions $\sigma_{M+1}=\sigma_{1}$, and the following relation between the classical and quantum mechanical coupling constants:

$$
\begin{align*}
& \beta_{\mathrm{cl}} J_{\mathrm{cl}}=-\frac{1}{2} \log \left(\Delta_{\tau} \Gamma / 2\right)  \tag{9.14}\\
& \beta_{\mathrm{cl}} h_{\mathrm{cl}}=\log \left(1+\Delta_{\tau} h / 2\right) \approx \Delta_{\tau} h / 2  \tag{9.15}\\
& \beta_{\mathrm{cl}} E_{0}=M \beta_{\mathrm{cl}} J_{\mathrm{cl}} . \tag{9.16}
\end{align*}
$$

Hence, any Monte Carlo algorithm for the classical Ising model, including cluster updates, can be used for the simulation. Similarly any $d$-dimensional quantum Ising model

$$
\begin{equation*}
\mathcal{H}=-J \sum_{\langle i, j\rangle} S_{i}^{z} S_{j}^{z}-h \sum_{i} S_{i}^{z}-\Gamma \sum_{i} S_{i}^{x} \tag{9.17}
\end{equation*}
$$

can be mapped to a $(d+1)$-dimensional classical Ising model.

### 9.2.2 Continuous Time Path Integrals

Instead of using a discrete time path integral formulation, modern world line QMC algorithms are based on a continuous time representation, which works directly in the limit $\Delta_{\tau} \rightarrow 0(M \rightarrow \infty)$. To arrive at a continuous time representation we consider what happens when we reduce the time step $\Delta_{\tau}$, as is illustrated in figure 9.1.

The discrete time path integral is represented by a chain of classical Ising spins, shown in Fig. 9.1a). Reducing the time step $\Delta_{\tau}$ increases the number of spins as
shown in Fig. 9.1b,c). While the number of spins $M$ diverges in the limit $\Delta_{\tau} \rightarrow 0$, the average number of domain walls between parallel spins remains finite since the coupling between two neighboring spins (9.14) becomes infinitely strong as $\Delta_{\tau} \rightarrow 0$. Since the ratio $\exp \left(-2 \beta_{\mathrm{cl}} J_{\mathrm{cl}}\right)=\Delta_{\tau} \Gamma / 2$ of the weights of two antiparallel spins and two parallel spins probability of having a domain wall is proportional to $\Delta_{\tau}$, the average number of domain walls is less than

$$
\begin{equation*}
M \exp \left(-2 \beta_{\mathrm{cl}} J_{\mathrm{cl}}\right)=M \Delta_{\tau} \Gamma / 2=\beta \Gamma / 2 . \tag{9.18}
\end{equation*}
$$

and hence finite in the $\Delta_{\tau} \rightarrow 0$ limit.
Since the number of domain walls $n$ remains finite while the number of spins $M$ diverges, it will be more efficient to only store the values $\bar{i}_{j}$ of the spins in the $j$-th domain $(j=1, \ldots n)$ and the location of the last spin of the $j$-th domain $i_{j}$, instead of storing the value of each single spin. In such a compacted notation the weight of a configuration in the discrete time representation (9.12) becomes

$$
\begin{align*}
& \left\langle i_{1}\right| U\left|i_{2}\right\rangle\left\langle i_{2}\right| U\left|i_{3}\right\rangle \cdots\left\langle i_{M}\right| U\left|i_{1}\right\rangle \\
& \quad=\left(1+\Delta_{\tau} h \bar{i}_{1}\right)^{i_{1}-1}\left\langle\bar{i}_{1}\right| U\left|\bar{i}_{2}\right\rangle\left(1+\Delta_{\tau} h \bar{i}_{2}\right)^{\left(i_{2}-i_{1}-1\right)} \cdots  \tag{9.19}\\
& \quad \cdots\left(1+\Delta_{\tau} h \bar{i}_{n}\right)^{\left(i_{n}-i_{n-1}-1\right)}\left\langle\bar{i}_{n}\right| U\left|\bar{i}_{1}\right\rangle\left(1+\Delta_{\tau} h \bar{i}_{1}\right)^{\left(M-i_{n}\right)} .
\end{align*}
$$

Identifying $\tau_{j}=i_{j} \Delta_{\tau}$ and $E_{j}=-h \bar{i}_{j}$, realizing that $\left\langle\bar{i}_{j}\right| U\left|\bar{i}_{j+1}\right\rangle=-\Delta_{\tau}\left\langle\bar{i}_{j}\right| \mathcal{H}_{x}\left|\bar{i}_{j+1}\right\rangle$ when $\left|\bar{i}_{j}\right\rangle \neq\left|\bar{i}_{j+1}\right\rangle$, and taking the limit $\Delta_{\tau} \rightarrow 0$ we end up with the continuous time expression

$$
\begin{align*}
& (-1)^{n} e^{-\tau_{1} E_{1}}\left\langle\bar{i}_{1}\right| \mathcal{H}_{x}\left|\bar{i}_{2}\right\rangle e^{-\left(\tau_{2}-\tau_{1}\right) E_{2}} \cdots  \tag{9.20}\\
& \quad \cdots e^{-\left(\tau_{n}-\tau_{n-1}\right) E_{n}}\left\langle\bar{i}_{n}\right| \mathcal{H}_{x}\left|\bar{i}_{1}\right\rangle e^{-\left(\beta-\tau_{1}\right) E_{1}} d \tau_{1} \cdots d \tau_{n} .
\end{align*}
$$

Integrating this weight over all possible location for the domain walls and summing over all possible number of domain walls $n$, we finally obtain the continuous time representation

$$
\begin{align*}
& Z=\sum_{\bar{i}_{0}}\left\langle\bar{i}_{0}\right| e^{-\beta E_{0}}\left|\bar{i}_{0}\right\rangle+ \\
& \sum_{n=1}^{\infty} \sum_{\left(\bar{i}_{1}, \ldots \bar{i}_{n}\right)}(-1)^{n} \int_{0}^{\beta} d \tau_{1} \cdots \int_{\tau_{n-1}}^{\beta} d \tau_{n} e^{-\tau_{1} E_{1}}\left\langle\bar{i}_{1}\right| \mathcal{H}_{x}\left|\bar{i}_{2}\right\rangle e^{-\left(\tau_{2}-\tau_{1}\right) E_{2}} \ldots \\
& \quad \cdots e^{-\left(\tau_{n}-\tau_{n-1}\right) E_{n}}\left\langle\bar{i}_{n}\right| \mathcal{H}_{x}\left|\bar{i}_{1}\right\rangle e^{-\left(\beta-\tau_{n}\right) E_{1}} . \tag{9.21}
\end{align*}
$$

This is nothing but the result of a time-dependent perturbation expansion in the operators $\mathcal{H}_{x}$.
a)

b)


Figure 9.2: Relationship between continuous time path integrals and the stochastic series expansion (SSE) representation illustrated for a single spin- $1 / 2$. a) in continuous time path integrals a representation is specified by the times $\tau_{i}$ at which off-diagonals operators act on the configuration. b) in the SSE representation the expansion is in terms of both diagonal and off-diagonal operators. An integer index specifying the ordering of operators replaces the continuous time label.

### 9.2.3 Stochastic Series Expansion

The stochastic series expansion (SSE) representation performs a Taylor expansion of the full Hamiltonian:

$$
\begin{align*}
Z & =\operatorname{Tr} \exp (-\beta \mathcal{H})=\sum_{n=0}^{\infty} \frac{\beta^{n}}{n!} \operatorname{Tr}(-\mathcal{H})^{n} \\
& =1+\sum_{n=1}^{\infty} \frac{\beta^{n}}{n!} \sum_{\left\{i_{1}, \ldots i_{n}\right\}}\left\langle i_{1}\right|-\mathcal{H}\left|i_{2}\right\rangle\left\langle i_{2}\right|-\mathcal{H}\left|i_{3}\right\rangle \cdots\left\langle i_{n}\right|-\mathcal{H}\left|i_{1}\right\rangle, \tag{9.22}
\end{align*}
$$

giving a much simpler expression than discrete or continuous time path integrals.
The advantage of the SSE representation over continuous time path integrals is that instead of associating times $\tau_{i}$ with the operators there is just an integer index indicating the order of operators. This simplifies QMC programs based on an SSE representation, compared to continuous time programs. This advantage is paid for by the need for higher orders $n$ in the expansion since we perturb in all terms of the Hamiltonian and not just in the off-diagonal term $\mathcal{H}_{x}$. Figure 9.2 illustrates the relationship between continuous time path integrals and the SSE representation.

### 9.3 More complicated models: the XXZ chain

We will next discuss the loop cluster algorithm for a spin- $1 / 2$ quantum XXZ model with the Hamiltonian

$$
\begin{align*}
H & =-\sum_{\langle i, j\rangle}\left(J_{z} S_{i}^{z} S_{j}^{z}+J_{x y}\left(S_{i}^{x} S_{j}^{x}+S_{i}^{y} S_{j}^{y}\right)\right) \\
& =-\sum_{\langle i, j\rangle}\left(J_{z} S_{i}^{z} S_{j}^{z}+\frac{J_{x y}}{2}\left(S_{i}^{+} S_{j}^{-}+S_{i}^{-} S_{j}^{+}\right)\right) . \tag{9.23}
\end{align*}
$$

For $J \equiv J_{z}=J_{x y}$ we have the Heisenberg model ( $J>0$ is ferromagnetic, $J<0$ antiferromagnetic). $J_{x y}=0$ is the (classical) Ising model and $J_{z}=0$ the quantum $X Y$ model.


Figure 9.3: Example of a world line configuration for a spin-1/2 quantum Heisenberg model. Drawn are the world lines for up-spins only. Down spin world lines occupy the rest of the configuration.

## Continuous-time world lines

We again start by discretizing the imaginary time (inverse temperature) direction and subdivide $\beta=M \Delta_{\tau}$ :

$$
\begin{equation*}
\left.e^{-\beta H}=\left(e^{-\Delta_{\tau} H}\right)^{M}=\left(1-\Delta_{\tau} H\right)^{M}+\Delta_{\tau}\right) \tag{9.24}
\end{equation*}
$$

In the limit $M \rightarrow \infty\left(\Delta_{\tau} \rightarrow 0\right)$ this becomes exact. We will take the limit later, but stay at finite $\Delta_{\tau}$ for the derivation.

The next step is to insert the identity matrix, represented by a sum over all basis states $\sum_{i}|i\rangle\langle i|$ between all operators $\left(1-\Delta_{\tau} H\right)$ :

$$
\begin{align*}
Z & \left.=\operatorname{Tr} e^{-\beta H}=\operatorname{Tr}\left(1-\Delta_{\tau} H\right)^{M}+\Delta_{\tau}\right) \\
& \left.=\sum_{i_{1}, \ldots, i_{M}}\left\langle i_{1}\right| 1-\Delta_{\tau} H\left|i_{2}\right\rangle\left\langle i_{2}\right| 1-\Delta_{\tau} H\left|i_{3}\right\rangle \cdots\left\langle i_{M}\right| 1-\Delta_{\tau} H\left|i_{1}\right\rangle+\Delta_{\tau}\right) \\
& =: \sum_{i_{1}, \ldots, i_{M}} P_{i_{1}, \ldots, i_{M}} \tag{9.25}
\end{align*}
$$

and similarly for the measurement, obtaining

$$
\begin{equation*}
\left.\langle A\rangle=\sum_{i_{1}, \ldots, i_{M}} \frac{\left\langle i_{1}\right| A\left(1-\Delta_{\tau} H\right)\left|i_{2}\right\rangle}{\left\langle i_{1}\right| 1-\Delta_{\tau} H\left|i_{2}\right\rangle} P_{i_{1}, \ldots, i_{M}}+\Delta_{\tau}\right) . \tag{9.26}
\end{equation*}
$$

If we choose the basis states $|i\rangle$ to be eigenstates of the local $S^{z}$ operators we end up with an Ising-like spin system in one higher dimension. Each choice $i_{1}, \ldots, i_{M}$ corresponds to one of the possible configurations of this classical spin system. The trace is mapped to periodic boundary conditions in the imaginary time direction of this classical spin system. The probabilities are given by matrix elements $\left\langle i_{n}\right| 1-\Delta_{\tau} H\left|i_{n+1}\right\rangle$. We can now sample this classical system using classical Monte Carlo methods.

However, most of the matrix elements $\left\langle i_{n}\right| 1-\Delta_{\tau} H\left|i_{n+1}\right\rangle$ are zero, and thus nearly all configurations have vanishing weight. The only non-zero configurations are those where
neighboring states $\left|i_{n}\right\rangle$ and $\left|i_{n+1}\right\rangle$ are either equal or differ by one of the off-diagonal matrix elements in $H$, which are nearest neighbor exchanges by two opposite spins. We can thus uniquely connect spins on neighboring "time slices" and end up with world lines of the spins, sketched in Fig. 9.3. Instead of sampling over all configurations of local spins we thus have to sample only over all world line configurations (the others have vanishing weight). Our update moves are not allowed to break world lines but have to lead to new valid world line configurations.

Finally we take the continuous time limit $\Delta_{\tau} \rightarrow 0$. Instead of storing the configurations at all $M \rightarrow \infty$ time steps, we will not just store the times $\tau$ where a spin flips as the consequence of an off-diagonal operator acting at that time. The number of such events stays finite as $M \rightarrow \infty$ : as can be seen from equation (9.24) the probability of $H$ acting at a given time is proportional to $1 / M$, and hence the total number of spin flips will stay finite although $M \rightarrow \infty$

### 9.4 Cluster updates

Before discussing cluster updates for quantum systems, we will review the cluster algorithms for the classical Ising model which should be known from the computational statistical physics course.

### 9.4.1 Kandel-Domany framework

To provide a general framework, which can be extended to quantum systems, we use the Fortuin-Kastelyn representation of the Ising model, as generalized by Kandel and Domany. The phase space of the Ising model is enlarged by assigning a set $\mathcal{G}$ of possible "graphs" to each configuration $C$ in the set of configurations $\mathcal{C}$. We write the partition function as

$$
\begin{equation*}
Z=\sum_{C \in \mathcal{C}} \sum_{G \in \mathcal{G}} W(C, G) \tag{9.27}
\end{equation*}
$$

where the new weights $W(C, G)>0$ are chosen such that $Z$ is the partition function of the original model by requiring

$$
\begin{equation*}
\sum_{G \in \mathcal{G}} W(C, G)=W(C):=\exp (-\beta E[C]) \tag{9.28}
\end{equation*}
$$

where $E[C]$ is the energy of the configuration $C$.
The algorithm now proceeds as follows. First we assign a graph $G \in \mathcal{G}$ to the configuration $C$, chosen with the correct probability

$$
\begin{equation*}
P_{C}(G)=W(C, G) / W(C) \tag{9.29}
\end{equation*}
$$

Then we choose a new configuration $C^{\prime}$ with probability $p\left[(C, G) \rightarrow\left(C^{\prime}, G\right)\right]$, keeping the graph $G$ fixed; next a new graph $G^{\prime}$ is chosen

$$
\begin{equation*}
C \rightarrow(C, G) \rightarrow\left(C^{\prime}, G\right) \rightarrow C^{\prime} \rightarrow\left(C^{\prime}, G^{\prime}\right) \rightarrow \ldots \tag{9.30}
\end{equation*}
$$

What about detailed balance? The procedure for choosing graphs with probabilities $P_{G}$ obeys detailed balance trivially. The non-trivial part is the probability of choosing a new configuration $C^{\prime}$. There detailed balance requires:

$$
\begin{equation*}
W(C, G) p\left[(C, G) \rightarrow\left(C^{\prime}, G\right)\right]=W\left(C^{\prime}, G\right) p\left[\left(C^{\prime}, G\right) \rightarrow(C, G)\right] \tag{9.31}
\end{equation*}
$$

which can be fulfilled using either the heat bath algorithm

$$
\begin{equation*}
p\left[(C, G) \rightarrow\left(C^{\prime}, G\right)\right]=\frac{W\left(C^{\prime}, G\right)}{W(C, G)+W\left(C^{\prime}, G\right)} \tag{9.32}
\end{equation*}
$$

or by again using the Metropolis algorithm:

$$
\begin{equation*}
p\left[(C, G) \rightarrow\left(C^{\prime}, G\right)\right]=\min \left(W\left(C^{\prime}, G\right) / W(C, G), 1\right) \tag{9.33}
\end{equation*}
$$

The algorithm simplifies a lot if we can find a graph mapping such that the graph weights do not depend on the configuration whenever it is nonzero in that configuration. This means, we want the graph weights to be

$$
\begin{equation*}
W(C, G)=\Delta(C, G) V(G), \tag{9.34}
\end{equation*}
$$

where

$$
\Delta(C, G):=\left\{\begin{array}{l}
1 \text { if } W(C, G) \neq 0,  \tag{9.35}\\
0 \text { otherwise }
\end{array} .\right.
$$

Then equation (9.32) simply becomes $p=1 / 2$ and equation (9.33) reduces to $p=1$ for any configuration $C^{\prime}$ with $W\left(C^{\prime}, G\right) \neq 0$.

### 9.4.2 The cluster algorithms for the Ising model

Let us now show how this abstract and general algorithm can be applied to the Ising model. Our graphs will be bond-percolation graphs on the lattice. Spins pointing into the same direction can be connected or disconnected. Spins pointing in opposite directions will always be disconnected. In the Ising model we can write the weights $W(C)$ and $W(C, G)$ as products over all bonds $b$ :

$$
\begin{align*}
W(C) & =\prod_{b} w\left(C_{b}\right)  \tag{9.36}\\
W(C, G) & =\prod_{b} w\left(C_{b}, G_{b}\right)=\prod_{b} \Delta\left(C_{b}, G_{b}\right) V\left(G_{b}\right) \tag{9.37}
\end{align*}
$$

where the local bond configurations $C_{b}$ can be one of $\{\uparrow \uparrow, \downarrow \uparrow, \uparrow \downarrow, \downarrow \downarrow\}$
and the local graphs can be "connected" or "disconnected". The graph selection can thus be done locally on each bond.

Table 9.1 shows the local bond weights $w(c, g), w(c), \Delta(c, g)$ and $V(g)$. It can easily be checked that the sum rule (9.28) is satisfied.

The probability of a connected bond is $[\exp (\beta J)-\exp (-\beta J)] / \exp (\beta J)=1-$ $\exp (-2 \beta J)$ if two spins are aligned and zero otherwise. These connected bonds group the spins into clusters of aligned spins.

Table 9.1: Local bond weights for the Kandel-Domany representation of the Ising model.

|  | $c=\uparrow \uparrow$ | $c=\downarrow \uparrow$ | $c=\uparrow \downarrow$ | $c=\downarrow \downarrow$ | $\mathrm{V}(\mathrm{g})$ |
| :--- | :---: | :---: | :---: | :---: | :---: |
| $\Delta(c$, discon. $)$ | 1 | 1 | 1 | 1 | $\exp (-\beta J)$ |
| $\Delta(c$, con. $)$ | 1 | 0 | 0 | 1 | $\exp (\beta J)-\exp (-\beta J)$ |
| $\mathrm{w}(c)$ | $\exp (\beta J)$ | $\exp (-\beta J)$ | $\exp (-\beta J)$ | $\exp (\beta J)$ |  |

A new configuration $C^{\prime}$ with the same graph $G$ can differ from $C$ only by flipping clusters of connected spins. Thus the name "cluster algorithms". The clusters can be flipped independently, as the flipping probabilities $p\left[(C, G) \rightarrow\left(C^{\prime}, G\right)\right]$ are configuration independent constants.

There are two variants of cluster algorithms that can be constructed using the rules derived above.

## The Swendsen-Wang algorithm

The Swendsen-Wang or multi-cluster algorithm proceeds as follows:
i) Each bond in the lattice is assigned a label "connected" or "disconnected" according to above rules. Two aligned spins are connected with probability $1-$ $\exp (-2 \beta J)$. Two antiparallel spins are never connected.
ii) Next a cluster labeling algorithm, like the Hoshen-Kopelman algorithm is used to identify clusters of connected spins.
iii) Measurements are performed, using improved estimators discussed in the next section.
iv) Each cluster of spins is flipped with probability $1 / 2$.

## The Wolff single-cluster algorithm

The Swendsen Wang algorithm gets less efficient in dimensions higher than two as the majority of the clusters will be very small ones, and only a few large clusters exist. The Wolff algorithm is similar to the Swendsen-Wang algorithm but builds only one cluster starting from a randomly chosen point. As the probability of this point being on a cluster of size $s$ is proportional to $s$ the Wolff algorithm builds preferedly larger clusters. It works in the following way:
i) Choose a random spin as the initial cluster.
ii) If a neighboring spin is parallel to the initial spin it will be added to the cluster with probability $1-\exp (-2 \beta J)$.
iii) Repeat step ii) for all points newly added to the cluster and repeat this procedure until no new points can be added.
iv) Perform measurements using improved estimators.
v) Flip all spins in the cluster.

We will see in the next section that the linear cluster size diverges with the correlation length $\xi$ and that the average number of spins in a cluster is just $\chi T$. Thus the algorithm adapts optimally to the physics of the system and the dynamical exponent $z \approx 0$, thus solving the problem of critical slowing down. Close to criticality these algorithms are many orders of magnitudes (a factor $L^{2}$ ) better than the local update methods. Away from criticality sometimes a hybrid method, mixing cluster updates and local updates can be the ideal method.

### 9.4.3 Improved Estimators

In this section we present a neat trick that can be used in conjunction with cluster algorithms to reduce the variance, and thus the statistical error of Monte Carlo measurements. Not only do these "improved estimators" reduce the variance. They are also much easier to calculate than the usual "simple estimators".

To derive them we consider the Swendsen-Wang algorithm. This algorithm divides the lattice into $N_{c}$ clusters, where all spins within a cluster are aligned. The next possible configuration is any of the $2^{N_{c}}$ configurations that can be reached by flipping any subset of the clusters. The idea behind the "improved estimators" is to measure not only in the new configuration but in all equally probable $2^{N_{c}}$ configurations.

As simplest example we consider the average magnetization $\langle m\rangle$. We can measure it as the expectation value $\left\langle\sigma_{\vec{i}}\right\rangle$ of a single spin. As the cluster to which the spin belongs can be freely flipped, and the flipped cluster has the same probability as the original one, the improved estimator is

$$
\begin{equation*}
\langle m\rangle=\left\langle\frac{1}{2}\left(\sigma_{\vec{i}}-\sigma_{\vec{i}}\right)\right\rangle=0 . \tag{9.38}
\end{equation*}
$$

This result is obvious because of symmetry, but we saw that at low temperatures a single spin flip algorithm will fail to give this correct result since it takes an enormous time to flip all spins. Thus it is encouraging that the cluster algorithms automatically give the exact result in this case.

Correlation functions are not much harder to measure:

$$
\left\langle\sigma_{\vec{i}} \sigma_{\vec{j}}\right\rangle= \begin{cases}1 & \text { if } \vec{i} \text { und } \vec{j} \text { are on the same cluster }  \tag{9.39}\\ 0 & \text { otherwise }\end{cases}
$$

To derive this result consider the two cases and write down the improved estimators by considering all possible cluster flips.

Using this simple result for the correlation functions the mean square of the magnetization is

$$
\begin{equation*}
\left\langle m^{2}\right\rangle=\frac{1}{N^{2}} \sum_{\vec{i}, \vec{j}}\left\langle\sigma_{\vec{i}} \sigma_{\vec{j}}\right\rangle=\frac{1}{N^{2}}\left\langle\sum_{\text {cluster }} S(\text { cluster })^{2}\right\rangle, \tag{9.40}
\end{equation*}
$$

where $S\left(\right.$ cluster ) is the number of spins in a cluster. The susceptibility above $T_{c}$ is simply given by $\beta\left\langle m^{2}\right\rangle$ and can also easily be calculated by above sum over the squares of the cluster sizes.

Table 9.2: The six local configurations for an $X X Z$ model and their weights.

| configuration |  |  |  | weight |
| :---: | :---: | :---: | :---: | :---: |
|  | $4 s_{(1+d t)}$ | $\left.s_{1}(t+d)\right\}^{\prime}$ | \s $s_{\text {( } 2+d t)}$ |  |
| $s_{\text {st }} 4$ | $\uparrow s_{j}(t)$ | $s_{(t)}+\downarrow$ | $\dagger s_{\text {f }}($ c) | $1+\frac{J_{z}}{4} d \tau$ |
|  | $\downarrow s_{(1+d t)}$ | $\left.s_{1}(t+d x)\right\rangle^{\prime}$ | ¢ $s_{s(t+d t)}$ |  |
| $s s_{12} 4$ | $\downarrow s_{\text {f }}(\mathrm{t})$ |  | $\uparrow s_{s, t}(\underline{t}$ | $1-\frac{J_{z}}{4} d \tau$ |
|  | $4 s_{(t+t+c)}$ | $s_{1}(t+d x) 4$ | $\downarrow s_{(k+t d t)}$ |  |
| $s_{t}(t) 4$ | $\downarrow s_{\text {f }}($ t | $s s_{\text {a }}(\tau) \downarrow$ | $\uparrow s_{f}(t)$ | ${ }^{J_{x y}}$ d $d \tau$ |

In the Wolff algorithm only a single cluster is built. Above sum (9.40) can be rewritten to be useful also in case of the Wolff algorithm:

$$
\begin{align*}
\left\langle m^{2}\right\rangle & =\frac{1}{N^{2}}\left\langle\sum_{\text {cluster }} S(\text { cluster })^{2}\right\rangle \\
& =\frac{1}{N^{2}} \sum_{\vec{i}} \frac{1}{S(\text { cluster containing } \vec{i})} S(\text { cluster containing } \vec{i})^{2} \\
& =\frac{1}{N^{2}} \sum_{\vec{i}} S(\text { cluster containing } \vec{i})=\frac{1}{N}\langle S(\text { cluster })\rangle . \tag{9.41}
\end{align*}
$$

The expectation value for $m^{2}$ is thus simply the mean cluster size. In this derivation we replaced the sum over all clusters by a sum over all sites and had to divide the contribution of each cluster by the number of sites in the cluster. Next we can replace the average over all lattice sites by the expectation value for the cluster on a randomly chosen site, which in the Wolff algorithm will be just the one Wolff cluster we build.

### 9.4.4 The loop algorithm for quantum spins

We will now generalize these cluster algorithms to quantum systems and present the loop algorithm. ${ }^{1}$

This algorithm is best described by first taking the continuous time limit $M \rightarrow \infty$ $\left(\Delta_{\tau} \rightarrow d \tau\right)$ and by working with infinitesimals. Similar to the Ising model we look at two spins on neigboring sites $i$ and $j$ at two neighboring times $\tau$ and $\tau+d \tau$, as sketched in Tab. 9.2. There are a total of six possible configurations, having three different probabilities. The total probabilities are the products of all local probabilities, like in the classical case. This is obvious for different time slices. For the same time slice it is also true since, denoting by $H_{i j}$ the term in the Hamiltonian $H$ acting on the bond between sites $i$ and $j$ we have $\prod_{\langle i, j\rangle}\left(1-d \tau H_{i j}\right)=1-d \tau \sum_{\langle i, j\rangle} H_{i j}=1-d \tau H$. In the following we focus only on such local four-spin plaquettes. Next we again use the

[^11]

Figure 9.4: The four local graphs: a) vertical, b) horizontal c) crossing and d) freezing (connects all four corners).

Table 9.3: The graph weights for the quantum- $X Y$ model and the $\Delta$ function specifying whether the graph is allowed. The dash - denotes a graph that is not possible for a configuration because of spin conservation and has to be zero.

| G |  |  | $\begin{aligned} & \uparrow \\ & \Delta( \dagger, G) \\ &= \Delta \\ & \hline \end{aligned}$ | graph weight |
| :---: | :---: | :---: | :---: | :---: |
| $\Phi \$$ | 1 | 1 | $L_{-}$ | $1-\frac{J_{x y}}{4} d \tau$ |
| $\begin{aligned} & \mathrm{G} \\ & \Theta \bigcirc \end{aligned}$ | - | 1 | 1 | ${ }^{\frac{J_{x y}}{4}} d \tau$ |
| $8$ | 1 | - | 1 | ${ }^{J_{x y}} 4 . d \tau$ |
| Qo | 0 | 0 | 0 | 0 |
| total weight | 1 | 1 | $\frac{J_{x y}}{2} d \tau$ |  |

Kandel-Domany framework and assign graphs. As the updates are not allowed to break world lines only four graphs, sketched in Fig. 9.4 are allowed. Finally we have to find $\Delta$ functions and graph weights that give the correct probabilities. The solution for the $X Y$-model, ferromagnetic and antiferromagnetic Heisenberg model and the Ising model is shown in Tables 9.3-9.6.

Let us first look at the special case of the Ising model. As the exchange term is absent in the Ising model all world lines run straight and can be replaced by classical spins. The only non-trivial graph is the "freezing", connecting two neighboring world lines. Integrating the probability that two neighboring sites are nowhere connected along the time direction we obtain: times:

$$
\begin{equation*}
\prod_{\tau=0}^{\beta}(1-d \tau J / 2)=\lim _{M \rightarrow \infty}\left(1-\Delta_{\tau} J / 2\right)^{M}=\exp (-\beta J / 2) \tag{9.42}
\end{equation*}
$$

Taking into account that the spin is $S=1 / 2$ and the corresponding classical coupling $J_{c l}=S^{2} J=J / 4$ we find for the probability that two spins are connected: $1-\exp \left(-2 \beta J_{c l}\right)$. We end up exactly with the cluster algorithm for the classical Ising model!

Table 9.4: The graph weights for the ferromagnetic quantum Heisenberg model and the $\Delta$ function specifying whether the graph is allowed. The dash - denotes a graph that is not possible for a configuration because of spin conservation and has to be zero.

| G |  | $\begin{aligned} & \begin{array}{c} \uparrow \\ \\ \Delta \end{array} \\ &=\Delta, G) \\ &= \uparrow \\ & \hline \end{aligned}$ |  | graph weight |
| :---: | :---: | :---: | :---: | :---: |
| $\Phi \Phi$ | 1 | 1 | $\sim_{-}$ | $1-\frac{J}{4} d \tau$ |
| $\begin{aligned} & \Theta \bigcirc \bigcirc \\ & \Theta \bigcirc \end{aligned}$ | - | 0 | 0 | 0 |
| $88$ | 1 | - | 1 | $\frac{J}{2} d \tau$ |
| $9$ | 0 | 0 | 0 | 0 |
| total weight | $1+\frac{J}{4} d \tau$ | $1-\frac{J}{4} d \tau$ | $\frac{J}{2} d \tau$ |  |

Table 9.5: The graph weights for the antiferromagnetic quantum Heisenberg model and the $\Delta$ function specifying whether the graph is allowed. The dash - denotes a graph that is not possible for a configuration because of spin conservation and has to be zero. To avoid the sign problem (see next subsection) we change the sign of $J_{x y}$, which is allowed only on bipartite lattices.

| G | $\begin{aligned} & \uparrow \\ & \Delta\left(\begin{array}{cc} 4 & 4 \\ & 4, G) \\ = & \Delta( \end{array} t, G\right) \end{aligned}$ | $\begin{aligned} & \dagger \\ \Delta( & \dagger, G) \\ =\Delta & \dagger \\ = & \uparrow, G) \end{aligned}$ | $\begin{aligned} & \Delta(\uparrow \\ &=\Delta( \uparrow \\ &=\uparrow, G) \\ & \hline \end{aligned}$ | graph weight |
| :---: | :---: | :---: | :---: | :---: |
| $\$ \$$ | 1 | 1 | $\mathrm{S}_{-}$ | $1-\frac{\|J\|}{4} d \tau$ |
| $\begin{aligned} & \mathrm{G} \\ & \Theta \longrightarrow \end{aligned}$ | - | 1 | 1 | $\frac{\|J\|}{2} d \tau$ |
| $8$ | 0 | - | 0 | 0 |
| $8$ | 0 | 0 | 0 | 0 |
| total weight | $1-\frac{\|J\|}{4} d \tau$ | $1+\frac{\|J\|}{4} d \tau$ | $\frac{\|J\|}{2} d \tau$ |  |

Table 9.6: The graph weights for the ferromagnetic Ising model and the $\Delta$ function specifying whether the graph is allowed. The dash - denotes a graph that is not possible for a configuration because of spin conservation and has to be zero.

| G | $\begin{aligned} & \uparrow \\ & \Delta\left(\begin{array}{ll} \uparrow & \uparrow, \\ & \dagger \\ & \Delta \\ \hline \end{array}\right.\dagger, G) \\ & \hline \end{aligned}$ | $\begin{aligned} & \begin{array}{c} 4 \\ \\ \Delta \end{array} \\ &=\dagger, G) \\ &= \Delta\left(\begin{array}{l} 4 \\ \end{array}\right. \\ & \hline \end{aligned}$ | $\begin{aligned} & \Delta(\uparrow \\ &=\Delta( \uparrow, G) \\ & \hline \end{aligned}$ | graph weight |
| :---: | :---: | :---: | :---: | :---: |
| $\Phi \$$ | 1 | 1 | $\mathrm{C}_{-}$ | $1-\frac{J_{z}}{4} d \tau$ |
| $\begin{aligned} & \mathrm{O} \\ & \mathrm{O} \end{aligned}$ | - | 0 | 0 | 0 |
| $80$ | 0 | - | 0 | 0 |
| $8$ | 1 | 0 | 0 | $\frac{J_{z}}{2} d \tau$ |
| total weight | $1+\frac{J_{z}}{4} d \tau$ | $1-\frac{J_{z}}{4} d \tau$ | 0 |  |

The other cases are special. Here each graph connects two spins. As each of these spins is again connected to only one other, all spins connected by a cluster form a closed loop, hence the name "loop algorithm". Only one issue remains to be explained: how do we assign a horizontal or crossing graph with infinitesimal probability, such as $(J / 2) d \tau$. This is easily done by comparing the assignment process with radioactive decay. For each segment the graph runs vertical, except for occasional decay processes occuring with probability $(J / 2) d \tau$. Instead of asking at every infinitesimal time step whether a decay occurs we simply calculate an exponentially distributed decay time $t$ using an exponential distribution with decay constant $J / 2$. Looking up the equation in the lecture notes of the winter semester we have $t=-(2 / J) \ln (1-u)$ where $u$ is a uniformly distributed random number.

The algorithm now proceeds as follows (see Fig. 9.5): for each bond we start at time 0 and calculate a decay time. If the spins at that time are oriented properly and an exchange graph is possible we insert one. Next we advance by another randomly chosen decay time along the same bond and repeat the procedure until we have reached the extent $\beta$. This assigns graphs to all infinitesimal time steps where spins do not change. Next we assign a graph to all of the (finite number of) time steps where two spins are exchanged. In the case of the Heisenberg models there is always only one possible graph to assign and this is very easy. In the next step we identify the loop-clusters and then flip them each with probability $1 / 2$. Alternatively a Wolff-like algorithm can be constructed that only builds one loop-cluster.

Improved estimators for measurements can be constructed like in classical models. The derivation is similar to the classical models. I will just mention two simple ones


Figure 9.5: Example of a loop update. In a first step decay paths are inserted where possible at positions drawn randomly according to an exponential distribution and graphs are assigned to all exchange terms (hoppings of world lines). In a second stage (not shown) the loop clusters are identified. Finally each loop cluster is flipped with probability $1 / 2$ and one ends up with a new configuration.
for the ferromagnetic Heisenberg model. The spin-spin corelation is

$$
S_{i}^{z}(\tau) S_{j}^{z}\left(\tau^{\prime}\right)= \begin{cases}1 & \text { if }(i, \tau) \text { und }\left(j, \tau^{\prime}\right) \text { are on the same cluster }  \tag{9.43}\\ 0 & \text { otherwise }\end{cases}
$$

and the uniform susceptibility is

$$
\begin{equation*}
\chi=\frac{1}{N \beta} \sum_{c} S(c)^{2}, \tag{9.44}
\end{equation*}
$$

where the sum goes over all loop clusters and $S(c)$ is the length of all the loop segments in the loop cluster $c$.

### 9.5 The negative sign problem

Now that we have an algorithm with no critical slowing down we could think that we have completely solved the problem of quantum many body problems. However, in this section we will show that the sign problem is NP-hard, following the paper M. Troyer and U.J. Wiese, Phys. Rev. Lett. 94, 170201 (2005).

The difficulties in finding polynomial time solutions to the sign problem are reminiscent of the apparent impossibility to find polynomial time algorithms for nondeterministic polynomial (NP)-complete decision problems, which could be solved in polynomial time on a hypothetical non-deterministic machine, but for which no polynomial time algorithm is known for deterministic classical computers. A hypothetical non-deterministic machine can always follow both branches of an if-statement simultaneously, but can never merge the branches again. It can, equivalently, be viewed as having exponentially many processors, but without any communication between them.

In addition, it must be possible to check a positive answer to a problem in NP on a classical computer in polynomial time.

Many important computational problems in the complexity class NP, including the traveling salesman problem and the problem of finding ground states of spin glasses have the additional property of being NP-hard, forming the subset of NP-complete problems, the hardest problems in NP. A problem is called NP-hard if any problem in NP can be mapped onto it with polynomial complexity. Solving an NP-hard problem is thus equivalent to solving any problem in NP, and finding a polynomial time solution to any of them would have important consequences for all of computing as well as the security of classical encryption schemes. In that case all problems in NP could be solved in polynomial time, and hence $\mathbf{N P}=\mathbf{P}$.

As no polynomial solution to any of the NP-complete problems was found despite decades of intensive research, it is generally believed that $\mathbf{N P} \neq \mathbf{P}$ and no deterministic polynomial time algorithm exists for these problems. The proof of this conjecture remains as one of the unsolved millennium problems of mathematics for which the Clay Mathematics Institute has offered a prize of one million US\$ . In this section we will show that the sign problem is NP-hard, implying that unless the $\mathbf{N P} \neq \mathbf{P}$ conjecture is disproved there exists no generic solution of the sign problem.

Before presenting the details of our proof, we will give a short introduction to classical and quantum Monte Carlo simulations and the origin of the sign problem. In the calculation of the phase space average of a quantity $A$, instead of directly evaluating the sum

$$
\begin{equation*}
\langle A\rangle=\frac{1}{Z} \sum_{c \in \Omega} A(c) p(c), \quad Z=\sum_{c \in \Omega} p(c), \tag{9.45}
\end{equation*}
$$

over a high-dimensional space $\Omega$ of configurations $c$, a classical Monte Carlo method chooses a set of $M$ configurations $\left\{c_{i}\right\}$ from $\Omega$, according to the distribution $p\left(c_{i}\right)$. The average is then approximated by the sample mean

$$
\begin{equation*}
\langle A\rangle \approx \bar{A}=\frac{1}{M} \sum_{i=1}^{M} A\left(c_{i}\right), \tag{9.46}
\end{equation*}
$$

within a statistical error $\Delta A=\sqrt{\operatorname{Var} A\left(2 \tau_{A}+1\right) / M}$, where $\operatorname{Var} A$ is the variance of $A$ and the integrated autocorrelation time $\tau_{A}$ is a measure of the autocorrelations of the sequence $\left\{A\left(c_{i}\right)\right\}$. In typical statistical physics applications, $p(c)=\exp (-\beta E(c))$ is the Boltzmann weight, $\beta=1 / k_{B} T$ is the inverse temperature, and $E(c)$ is the energy of the configuration $c$.

Since the dimension of configuration space $\Omega$ grows linearly with the number $N$ of particles, the computational effort for the direct integration Eq. (9.45) scales exponentially with the particle number $N$. Using the Monte Carlo approach the same average can be estimated to any desired accuracy in polynomial time, as long as the autocorrelation time $\tau_{A}$ does not increase faster than polynomially with $N$.

In a quantum system with Hamilton operator $H$, instead of an integral like Eq. (9.45), an operator expression

$$
\begin{equation*}
\langle A\rangle=\frac{1}{Z} \operatorname{Tr}[A \exp (-\beta H)], \quad Z=\operatorname{Tr} \exp (-\beta H) \tag{9.47}
\end{equation*}
$$



Figure 9.6: A configuration of a fermionic lattice model on a 4 -site square. The configuration has negative weight, since two fermions are exchanged in the sequence $\left|i_{1}\right\rangle \rightarrow\left|i_{2}\right\rangle \rightarrow\left|i_{3}\right\rangle \rightarrow\left|i_{4}\right\rangle \rightarrow\left|i_{1}\right\rangle$. World lines connecting particles on neighboring slices are drawn as thick lines.
needs to be evaluated in order to calculate the thermal average of the observable $A$ (represented by a self-adjoint operator). Monte Carlo techniques can again be applied to reduce the exponential scaling of the problem, but only after mapping the quantum model to a classical one, for example using world line configurations $c$ with weights $p(c)$. If all the weights $p(c)$ are positive, standard Monte Carlo methods can be applied, as it is the case for non-frustrated quantum magnets and bosonic systems. In fermionic systems negative weights $p(c)<0$ arise from the Pauli exclusion principle, when along the sequence $\left|i_{1}\right\rangle \rightarrow\left|i_{2}\right\rangle \rightarrow \cdots \rightarrow\left|i_{n}\right\rangle \rightarrow\left|i_{1}\right\rangle$ two fermions are exchanged, as shown in Fig. 9.6.

The standard way of dealing with the negative weights of the fermionic system is to sample with respect to the bosonic system by using the absolute values of the weights $|p(c)|$ and to assign the $\operatorname{sign} s(c) \equiv \operatorname{sign} p(c)$ to the quantity being sampled:

$$
\begin{align*}
\langle A\rangle & =\frac{\sum_{c} A(c) p(c)}{\sum_{c} p(c)}  \tag{9.48}\\
& =\frac{\sum_{c} A(c) s(c)|p(c)| / \sum_{c}|p(c)|}{\sum_{c} s(c)|p(c)| / \sum_{c}|p(c)|} \equiv \frac{\langle A s\rangle^{\prime}}{\langle s\rangle^{\prime}} .
\end{align*}
$$

While this allows Monte Carlo simulations to be performed, the errors increase exponentially with the particle number $N$ and the inverse temperature $\beta$. To see this, consider the mean value of the sign $\langle s\rangle=Z / Z^{\prime}$, which is just the ratio of the partition functions of the fermionic system $Z=\sum_{c} p(c)$ with weights $p(c)$ and the bosonic system used for sampling with $Z^{\prime}=\sum_{c}|p(c)|$. As the partition functions are exponentials of the corresponding free energies, this ratio is an exponential of the differences $\Delta f$
in the free energy densities: $\langle s\rangle=Z / Z^{\prime}=\exp (-\beta N \Delta f)$. As a consequence, the relative error $\Delta s /\langle s\rangle$ increases exponentially with increasing particle number and inverse temperature:

$$
\begin{equation*}
\frac{\Delta s}{\langle s\rangle}=\frac{\sqrt{\left(\left\langle s^{2}\right\rangle-\langle s\rangle^{2}\right) / M}}{\langle s\rangle}=\frac{\sqrt{1-\langle s\rangle^{2}}}{\sqrt{M}\langle s\rangle} \sim \frac{e^{\beta N \Delta f}}{\sqrt{M}} . \tag{9.49}
\end{equation*}
$$

Similarly the error for the numerator in Eq. (7) increases exponentially and the time needed to achieve a given relative error scales exponentially in $N$ and $\beta$.

In order to avoid any misconception about what would constitute a "solution" of the sign problem, we start by giving a precise definition:

- A quantum Monte Carlo simulation to calculate a thermal average $\langle A\rangle$ of an observable $A$ in a quantum system with Hamilton operator $H$ is defined to suffer from a sign problem if there occur negative weights $p(c)<0$ in the classical representation.
- The related bosonic system of a fermionic quantum system is defined as the system where the weights $p(c)$ are replaced by their absolute values $|p(c)|$, thus ignoring the minus sign coming from fermion exchanges:

$$
\begin{equation*}
\langle A\rangle^{\prime}=\frac{1}{Z^{\prime}} \sum_{c} A(c)|p(c)| . \tag{9.50}
\end{equation*}
$$

- An algorithm for the stochastic evaluation of a thermal average such as Eq. (9.50) is defined to be of polynomial complexity if the computational time $t(\epsilon, N, \beta)$ needed to achieve a relative statistical error $\epsilon=\Delta A /\langle A\rangle$ in the evaluation of the average $\langle A\rangle$ scales polynomially with the system size $N$ and inverse temperature $\beta$, i.e. if there exist integers $n$ and $m$ and a constant $\kappa<\infty$ such that

$$
\begin{equation*}
t(\epsilon, N, \beta)<\kappa \epsilon^{-2} N^{n} \beta^{m} \tag{9.51}
\end{equation*}
$$

- For a quantum system that suffers from a sign problem for an observable $A$, and for which there exists a polynomial complexity algorithm for the related bosonic system Eq. (9.50), we define a solution of the sign problem as an algorithm of polynomial complexity to evaluate the thermal average $\langle A\rangle$.

It is important to note that we only worry about the sign problem if the bosonic problem is easy (of polynomial complexity) but the fermionic problem hard (of exponential complexity) due to the sign problem. If the bosonic problem is already hard, e.g. for spin glasses ${ }^{2}$, the sign problem will not increase the complexity of the problem. Also, changing the representation so that all $p(c) \geq 0$ might not sufficient to solve the sign problem if the scaling remains exponential, since then we just map the sign problem to another exponentially hard problem. Only a polynomial complexity algorithm counts as a solution of the sign problem.

At first sight such a solution seems feasible since the sign problem is not an intrinsic property of the quantum model studied but is representation-dependent: it depends on

[^12]the choice of basis sets $\{|i\rangle\}$, and in some models it can be solved by a simple local basis change.. Indeed, when using the eigen basis in which the Hamilton operator $H$ is diagonal, there will be no sign problem. This diagonalization of the Hamilton operator is, however, no solution of the sign problem since its complexity is exponential in the number of particles $N$.

We now construct a quantum mechanical system for which the calculation of a thermal average provides the solution for one and thus all of the NP-complete problems. This system exhibits a sign problem, but the related bosonic problem is easy to solve. Since, for this model, a solution of the sign problem would provide us with a polynomial time algorithm for an NP-complete problem, the sign problem is NP-hard. Of course, it is expected that the corresponding thermal averages cannot be calculated in polynomial time and the sign problem thus cannot be solved. Otherwise we would have found a polynomial time algorithm for the NP-complete problems and would have shown that $\mathbf{N P}=\mathbf{P}$.

The specific NP-complete problem we consider is to determine whether a state with energy less than or equal to a bound $E_{0}$ exists for a classical three-dimensional Ising spin glass with Hamilton function

$$
\begin{equation*}
H=-\sum_{\langle j, k\rangle} J_{j k} \sigma_{j} \sigma_{k} \tag{9.52}
\end{equation*}
$$

Here the spins $\sigma_{j}$ take the values $\pm 1$, and the couplings $J_{j k}$ between nearest neighbor lattice points $j$ and $k$ are either 0 or $\pm J$.

This problem is in the complexity class NP since the non-deterministic machine can evaluate the energies of all configurations $c$ in polynomial time and test whether there is one with $E(c) \leq E_{0}$. In addition, the validity of a positive answer (i.e. there is a configuration $c$ ) can be tested on a deterministic machine by evaluating the energy of that configuration. The evaluation of the partition function $Z=\sum_{c} \exp (-\beta E(c))$ is, however, not in NP since the non-deterministic machine cannot perform the sum in polynomial time.

This question whether there is a state with energy $E(c) \leq E_{0}$ can also be answered in a Monte Carlo simulation by calculating the average energy of the spin glass at a large enough inverse temperature $\beta$. Since the energy levels are discrete with spacing $J$ it can easily be shown that by choosing an inverse temperature $\beta J \geq N \ln 2+\ln (12 N)$ the thermal average of the energy will be less than $E_{0}+J / 2$ if at least one configuration with energy $E_{0}$ or less exists, and larger than $E_{0}+J$ otherwise.

In this classical Monte Carlo simulation, the complex energy landscape, created by the frustration in the spin glass (Fig. 2a), exponentially suppresses the tunneling of the Monte Carlo simulation between local minima at low temperatures. The autocorrelation times and hence the time complexity of this Monte Carlo approach are exponentially large $\tau \propto \exp (a N)$, as expected for this NP-complete problem.

We now map this classical system to a quantum system with a sign problem. We do so by replacing the classical Ising spins by quantum spins. Instead of the common choice in which the classical spin configurations are basis states and the spins are represented by diagonal $\sigma_{j}^{z}$ Pauli matrices we choose a representation in which the spins point in


Figure 9.7: a) A classically frustrated spin configuration of three antiferromagnetically coupled spins: no configuration can simultaneously minimize the energy of all three bonds. b) A configuration of a frustrated quantum magnet with negative weights: three antiferromagnetic exchange terms with negative weights are present in the sequence $\left|i_{1}\right\rangle \rightarrow\left|i_{2}\right\rangle \rightarrow\left|i_{3}\right\rangle \rightarrow\left|i_{1}\right\rangle$. Here up-spins with $z$-component of spin $\sigma_{j}^{z}=1$ and downspins with $\sigma_{j}^{z}=-1$ are connected with differently colored world lines.
the $\pm x$ direction and are represented by $\sigma_{j}^{x}$ Pauli matrices:

$$
\begin{equation*}
H=-\sum_{\langle j, k\rangle} J_{j k} \sigma_{j}^{x} \sigma_{k}^{x}, \tag{9.53}
\end{equation*}
$$

Here the random signs of the couplings are mapped to random signs of the off-diagonal matrix elements which cause a sign problem (see Fig. 2b). The related bosonic model is the ferromagnet with all couplings $J_{j k} \geq 0$ and efficient cluster algorithms with polynomial time complexity are known for this model. Since the bosonic version is easy to simulate, the sign problem is the origin of the NP-hardness of a quantum Monte Carlo simulation of this model. A generic solution of the sign problem would provide a polynomial time solution to this, and thus to all, NP-complete problems, and would hence imply that $\mathbf{N P}=\mathbf{P}$. Since it is generally believed that $\mathbf{N P} \neq \mathbf{P}$, we expect that such a solution does not exist.

By constructing a concrete model we have shown that the sign problem of quantum Monte Carlo simulations is NP-hard. This does not exclude that a specific sign problem can be solved for a restricted subclass of quantum systems. This was indeed possible using the meron-cluster algorithm ${ }^{3}$ for some particular lattice models. Such a solution must be intimately tied to properties of the physical system and allow an essentially bosonic description of the quantum problem. A generic approach might scale polynomially for some cases but will in general scale exponentially.

In the case of fermions or frustrated quantum magnets, solving the sign problem requires a mapping to a bosonic or non-frustrated system - which is, in general, almost

[^13]certainly impossible for physical reasons. The origin of the sign problem is, in fact, the distinction between bosonic and fermionic systems. The brute-force approach of taking the absolute values of the probabilities means trying to sample a frustrated or fermionic system by simulating a non-frustrated or bosonic one. As for large system sizes $N$ and low temperatures the relevant configurations for the latter are not the relevant ones for the former, the errors are exponentially large.

Given the NP-hardness of the sign problem one promising idea for the simulation of fermionic systems is to use ultra-cold atoms in optical lattices to construct well-controlled and tunable implementations of physical systems, such as the Hubbard model, and to use these "quantum simulators" to study the phase diagrams of correlated quantum systems. But even these quantum simulators are most likely not a generic solution to the sign problem since there exist quantum systems with exponentially diverging time scales and it is at present not clear whether a quantum computer could solve the NP-complete problems.

### 9.6 Worm and directed loop updates

The quantum loop algorithm, like the classical cluster algorithms work only for models with spin-inversion symmetry: a configuration of spins and the flipped configuration need to have the same weight. Applying a magnetic field breaks this spin-inversion symmetry, and the loop algorithm cannot be applied. For that case, Nikolay Prokof'ev and coworkers invented the worm algorithm. ${ }^{4}$ The worm algorithm is based on a very simple idea: while local updates on world lines are not ergodic (since knots cannot be created or undone), the worm algorithm proceeds by cutting a world line, and then moves the open ends in local updates until they meet again and the world line is glued together once more.

[^14]
## Chapter 10

## An Introduction to Quantum Field Theory

### 10.1 Introduction

This chapter is a generalization of the section on Path Integral Monte Carlo, Sec. 7.1. Instead of considering one (or $N$ ) quantum-mechanical particles as was done there, the idea is now to consider a quantum field, which contains infinitely many degrees of freedom. However, in practice, we are going to simulate a large but finite number of degrees of freedom, and extrapolate at the end. So there really is not much difference with Sec. 7.1.

The formal basis for Quantum Field Theory is an important subject, which will not be covered here. The goal of this chapter is to convey some understanding of simulations of quantum field theories, by appealing to intuition rather than rigor.

### 10.2 Path integrals: from classical mechanics to field theory

Consider first the case of a single, classical particle with Hamiltonian $H=\frac{p^{2}}{2 m}+V$. Hamilton's equations describe the time-evolution of this particle:

$$
\begin{align*}
& \frac{d q}{d t}=+\frac{\partial H}{\partial p} \quad \longrightarrow \quad \dot{q}=\frac{p}{m}  \tag{10.1}\\
& \frac{d p}{d t}=-\frac{\partial H}{\partial q} \quad \longrightarrow \quad \dot{p}=-\nabla V \tag{10.2}
\end{align*}
$$

The usual point of view is to start from initial conditions $(q, \dot{q})$ at time $t=0$, and evolve $q$ and $\dot{q}$ according to the coupled ODEs above. Note, however, that the boundary conditions can instead be split between the beginning and the end of the evolution. In particular, one can specify the beginning and ending coordinates $(q(0), q(t))$. There is a unique path $q\left(t^{\prime}\right), t^{\prime} \in[0, t]$, which satisfies the above equations, and specifies the initial and final velocities. To find this path, it is convenient to change viewpoint and consider the action $S=\int_{0}^{t} d t^{\prime} \mathcal{L}(q, \dot{q})$, where $\mathcal{L}$ is the Lagrangian $\frac{1}{2} m \dot{q}^{2}-V(q)$. One

Figure 10.1: A field configuration $q(x, y)$, discretized on a square grid of spacing $a$.
then invokes the principle of stationary (or least) action, from which can be derived the Euler-Lagrange equations

$$
\begin{equation*}
\frac{\partial \mathcal{L}}{\partial q_{i}}=\partial_{\mu} \frac{\partial \mathcal{L}}{\partial\left(\partial_{\mu} q_{i}\right)} \tag{10.3}
\end{equation*}
$$

Note that the notion of action is more general than the notion of Hamiltonian: some systems have an action, but no Hamiltonian. This was in fact the original motivation for Feynman to develop the path integral formalism in his Ph.D. thesis: he was interested in systems having non-local interactions in time (with an interaction term $q(t) q\left(t^{\prime}\right)$ ).

Consider now many particles interacting with each other, with Lagrangian $\mathcal{L}=$ $\sum_{i} \frac{1}{2} m \dot{q}_{i}^{2}-V\left(\left\{q_{i}\right\}\right)$ and take $q_{i}$ to represent the $z$-coordinate of particle $i$, whose $x$ and $y$ coordinates are fixed on a square grid of spacing $a$. Furthermore, take the interaction between particles to be of the form $\sum_{\langle i j\rangle}\left(q_{i}-q_{j}\right)^{2}$, where $\langle i j\rangle$ stands for nearest-neighbours on the grid, as if springs were connecting $i$ and $j$. Low-energy configurations will then have almost the same $q$-value at neighbouring grid points, so that the configuration $\left\{q_{i}\right\}$ will be smooth and look like a "mattress" as in Fig. 10.1.

When the grid spacing $a$ is reduced to zero, the configuration $\left\{q_{i}\right\}$ becomes a classical field $q(\vec{x})\left(\vec{x} \in \mathcal{R}^{2}\right.$ in this example), with infinitely many degrees of freedom. The action of this field is specified by its Lagrangian density $\mathcal{L}=\frac{1}{2} \partial_{\mu} q \partial^{\mu} q-\frac{1}{2} m_{0}^{2} q^{2}-$ $V(q)$ where the first term is the continuum version of $\left(q_{i}-q_{j}\right)^{2}$ (with $\partial_{\mu} q \partial^{\mu} q=\dot{q}^{2}-$ $|\vec{\nabla} q|^{2}$ ), the second one is a harmonic term corresponding to a mass, and the last term describes the local (anharmonic) interaction, e.g. $\propto q^{4}{ }^{1}$. The action is then $S=$ $\int_{0}^{t} d t^{\prime} d x d y \mathcal{L}\left(q\left(x, y, t^{\prime}\right)\right)$. Note that the Lagrangian density $\mathcal{L}$ satisfies several symmetries: it is invariant under translations and rotations in the $(x, y)$ plane, and under the sign flip $q(\vec{x}) \rightarrow-q(\vec{x}) \forall \vec{x}$, at least for an interaction $\propto q^{4}$. Each continuous symmetry leads to a conserved quantity: energy-momentum for translations, angular momentum for rotations. We will see the importance of the discrete symmetry $q \leftrightarrow-q$ later.

[^15]Now we can consider quantum effects on the above system. As a result of quantum fluctuations, the path from $q(t=0)$ to $q(t)$ is no longer unique. All paths contribute, with an amplitude $\propto \exp \left(-\frac{i}{\hbar} \int_{0}^{t} d t^{\prime} \mathcal{L}\right)$, from which it becomes clear that the magnitude of relevant fluctuations in the action is $\hbar$. One can then follow the strategy of Sec. 7.1 and make time purely imaginary, by introducing $\tau=-i t \in \mathcal{R}$. The immediate result is that -idt ${ }^{\prime}$ above becomes $d \tau^{\prime}$, so that the amplitude becomes real. The other change is $\dot{q}^{2} \rightarrow-\left(\partial_{\tau} q\right)^{2}$, so that an overall minus sign can be taken out, leading to the amplitude

$$
\begin{equation*}
\exp \left(-\frac{1}{\hbar} S_{E}\right) \tag{10.4}
\end{equation*}
$$

where $S_{E}=\int d \tau^{\prime} d \vec{x} \mathcal{L}_{E}$ is the Euclidean action, and

$$
\begin{equation*}
\mathcal{L}_{E}=\frac{1}{2}\left(\partial_{\mu} \phi\right)^{2}+\frac{1}{2} m_{0}^{2} \phi^{2}+V(\phi) \tag{10.5}
\end{equation*}
$$

is the Euclidean Lagrangian density, and the field $q$ is now denoted by $\phi$ as is customary. The first term $\left(\partial_{\mu} \phi\right)^{2}=\left(\partial_{\tau} \phi\right)^{2}+|\vec{\nabla} \phi|^{2}$ is now symmetric between space and time, so that the metric is Euclidean in $(d+1)$ dimensions ( $d$ spatial dimensions, plus "Euclidean" time).

It is worth summarizing the sign flips which occurred in the kinetic energy $T$ and the potential energy $U$ during the successive steps we have just taken. We started with the Hamiltonian $H=T+U$, then considered the Lagrangian $L=T-U$. Going to imaginary time changes the sign of $T$. Finally, we take out an overall minus sign in the definition of $L_{E}$, so that paths with the smallest action are the most likely. This leads to the Euclidean Lagrangian density $L_{E}=T+U$, which is identical to the Hamiltonian we started from, except that the momentum $p$ is replaced by the derivative $\partial_{0} \phi$.

It is also useful to perform some elementary dimensional analysis. Since it appears in the exponent of the amplitude Eq.(10.4), the Euclidean action $S_{E}$ is dimensionless (we set $\hbar=1$ ). Hence the Euclidean Lagrangian density has mass dimension $(d+1)$, and therefore the field $\phi$ has mass dimension $\frac{d-1}{2}$. This is interesting, because if we take the "normal" number of spatial dimensions $d=3$ and the interaction term $V(\phi)=\frac{g_{0}}{4!} \phi^{4}$, then $g_{0}$ is a dimensionless number. It makes sense then to perform a Taylor expansion of this theory in powers of $g_{0}$ about the free case $g_{0}=0$ : this is the scope of perturbation theory. Here, we will try to obtain non-perturbative results, by directly simulating the theory at some finite, large value of $g_{0}$.

We have so far considered a field $\phi(\vec{x}, \tau)$ which takes values in $\mathcal{R}$. It is easy to generalize the Lagrangian density Eq.(10.5) to cases when $\phi$ takes values in $\mathcal{C}$, or has several components forming a vector $\vec{\phi} \equiv\left(\begin{array}{c}\phi_{1} \\ . \\ \phi_{N}\end{array}\right)$, perhaps with a constraint $\sum_{N} \phi_{k}^{2}=$ 1, depending on the desired symmetries. Typically, the Euclidean Lagrangian density is the starting, defining point of a quantum field theory.

Finally, we can introduce a finite temperature $T$, exactly as we did in the quantummechanical case: we make the Euclidean time direction compact: $\tau \in\left[0, \beta=\frac{1}{T}\right]$, and impose periodic boundary conditions on the field $\phi: \phi(\vec{x}, \beta)=\phi(\vec{x}, 0) \forall \vec{x}$. This works for the same reason as in quantum mechanics: the partition function

$$
\begin{equation*}
Z=\int_{\text {periodic }} \mathcal{D} \phi \exp \left(-\int_{0}^{\beta} d \tau^{\prime} d \vec{x} \mathcal{L}_{E}(\phi)\right) \tag{10.6}
\end{equation*}
$$

is a weighted sum of eigenstates of the Hamiltonian: $Z=\sum_{i} \exp \left(-\beta E_{i}\right)$. We will be concerned here with the $T=0$ situation. In that case, the two-point correlator provides a means to measure the mass gap $\left(E_{1}-E_{0}\right)$ :

$$
\begin{equation*}
\langle\phi(\vec{x}, \tau) \phi(\vec{x}, 0)\rangle-\langle\phi\rangle_{\tau \rightarrow \infty}^{2}=c^{2} \exp \left(-\left(E_{1}-E_{0}\right) \tau\right) \tag{10.7}
\end{equation*}
$$

or equivalently the correlation length $\xi=\left(E_{1}-E_{0}\right)^{-1}$. The lowest energy state, with energy $E_{0}$, is the vacuum, which contains particle-antiparticle pairs because of quantum fluctuations, but whose net particle number is zero. The first excited state, with energy $E_{1}$, contains one particle at rest. Call its mass $m_{R}=E_{1}-E_{0}$. Then this mass can be obtained from the decay of the two-point correlator, as $m_{R}=1 / \xi$. This is the "true", measurable mass of the theory, and it is not equal to the mass $m_{0}$ used in the Lagrangian density. $m_{R}$ is called the renormalized mass, while $m_{0}$ is the bare mass. Similarly, the "true" strength $g_{R}$ of the interaction can be measured from 4-correlators of $\phi$, and it is not equal to the coupling $g_{0}$ used in the Lagrangian density: $g_{0}$ is the bare coupling, $g_{R}$ the renormalized coupling.

### 10.3 Numerical study of $\phi^{4}$ theory

Here, we show that very important results in Quantum Field Theory can be extracted from simulations of the $4 d$ Ising model. Our starting point is the continuum Euclidean action:

$$
\begin{equation*}
S_{E}=\int d \tau d^{3} x\left[\frac{1}{2}\left(\partial_{\mu} \phi_{0}\right)^{2}+\frac{1}{2} m_{0}^{2} \phi_{0}^{2}+\frac{g_{0}}{4!} \phi_{0}^{4}\right] \tag{10.8}
\end{equation*}
$$

where the subscript 0 is to emphasize that we are dealing with bare quantities (field, mass and coupling), and the coupling normalization $1 / 4$ ! is conventional. We discretize the theory on a hypercubic (4d) lattice with spacing $a^{2}$. After the usual replacements $\int d \tau d^{3} x \rightarrow a^{4} \sum_{\text {sites } x}$ and $\partial_{\mu} \phi_{0} \rightarrow \frac{\phi_{0}(x+\hat{\mu})-\phi_{0}(x)}{a}$, we end up with the lattice action

$$
\begin{equation*}
S_{L}=\sum_{x}\left[-2 \kappa \sum_{\mu} \phi(x) \phi(x+\hat{\mu})+\phi(x)^{2}+\lambda\left(\phi(x)^{2}-1\right)^{2}-\lambda\right] \tag{10.9}
\end{equation*}
$$

where we use the new variables $\phi, \kappa$ and $\lambda$ defined by

$$
\begin{align*}
a \phi_{0} & =\sqrt{2 \kappa} \phi  \tag{10.10}\\
a^{2} m_{0}^{2} & =\frac{1-2 \lambda}{\kappa}-8  \tag{10.11}\\
g_{0} & =\frac{6 \lambda}{\kappa^{2}} \tag{10.12}
\end{align*}
$$

Note in particular the multiplication of $\phi_{0}$ by $a$ to form a dimensionless variable, since $\phi_{0}$ has mass dimension 1. The original formulation had two bare parameters, $m_{0}$ and $g_{0}$. They have been mapped into two bare parameters, $\kappa$ and $\lambda$. This discretized theory can be simulated by standard Monte Carlo algorithms like Metropolis, on a hypercubic

Figure 10.2: Phase diagram of the lattice theory defined by Eq.(10.9). The two phases are separated by a line of second-order transitions.
lattice of $L$ sites in each direction. To minimize finite-size effects, periodic boundary conditions are usually imposed in each direction.

The behaviour of our system is easy to understand qualitatively in the two limits $\lambda=0$ and $\lambda=+\infty$.

- When $\lambda=0$, the interaction is turned off. This is the free theory, which has two phases depending on the value of $\kappa$ : a disordered or symmetric phase $\langle\phi\rangle=0$ when $\kappa$ is small, and an ordered phase $\langle\phi\rangle \neq 0$ when $\kappa$ is large. Thus, the symmetry $\phi \leftrightarrow-\phi$ is spontaneously broken when $\kappa>\kappa_{c}=\frac{1}{8}$, which corresponds to the vanishing of the mass $m_{0}$.
- When $\lambda=+\infty$, fluctuations of $\phi$ away from the values $\pm 1$ cost an infinite amount of energy. Thus, $\phi$ is restricted to $\pm 1$, and our theory reduces to the $4 d$ Ising model with coupling $2 \kappa$. As in lower dimensions, the Ising model undergoes a second-order phase transition corresponding to the spontaneous breaking of the symmetry $\phi \leftrightarrow-\phi$, for a critical value $\kappa_{c} \approx 0.075$.
For intermediate values of $\lambda$, again a second-order transition takes place, leading to the phase diagram depicted Fig. 10.2.

The existence of a second-order phase transition is crucial: it allows us to define a continuum limit of our lattice theory. Remember that the "true", renormalized mass $m_{R}$ can be extracted from the exponential decay of the 2-point correlator

$$
\begin{equation*}
\langle\phi(x) \phi(y)\rangle-\langle\phi\rangle^{2} \underset{|x-y| \rightarrow \infty}{\propto} \exp \left(-m_{R}|x-y|\right)=\exp \left(-\frac{|x-y|}{\xi}\right) \tag{10.13}
\end{equation*}
$$

(see Eq.(10.7)). On the lattice, we can only measure the dimensionless combination

[^16]Figure 10.3: Two different viewpoints on a second-order phase transition: in solidstate physics (left), the crystal is "real" and the physical correlation length diverges; in quantum field theory (right), the correlation length is "real", and the lattice spacing shrinks to zero.
$a m_{R}=\frac{1}{\xi / a}$, and the separation $|x-y|$ can only be measured in lattice units, i.e. $\frac{|x-y|}{a}$. Taking the continuum limit $a \rightarrow 0$ (while keeping $m_{R}$ fixed) forces the correlation length measured in lattice units, i.e. $\xi / a$, to diverge. This only occurs when the lattice theory has a second-order phase transition (or higher order).

Therefore, the interpretation of a second-order phase transition is different between solid-state physics and lattice field theory. In the first case, the lattice spacing has a physical meaning, like the distance between two ions in a crystal: the lattice is "for real", and the correlation length really diverges at a second-order critical point. In the lattice field theory, the correlation length is "for real", and the lattice spacing $a$ shrinks to zero at the critical point. This is illustrated in Fig. 10.3.

In this latter case, one must be careful that the physical box size ( $L a$ ) also shrinks as $a \rightarrow 0$. In order to obtain a controlled continuum limit at constant physical volume, one must increase the number of lattice points $L$ in each direction keeping ( $L a$ ) fixed.

Going back to our $\phi^{4}$ theory, one sees that a continuum limit can be defined for any value of the bare coupling $\lambda \in[0,+\infty]$, by tuning $\kappa$ to its critical value $\kappa_{c}(\lambda)$. An interesting question is: what is the value of the "true", renormalized coupling as a function of $\lambda$ ? The answer is clear when $\lambda=0$ : the theory is free, and the coupling is
zero, whether bare or renormalized. To obtain a non-zero answer, a reasonable strategy is to maximize the bare coupling, and thus to consider the Ising limit $\lambda=+\infty$. The renormalized coupling is extracted from the strength of the 4 -spin correlation. The rather surprising answer is that the renormalized coupling is zero, just like for $\lambda=0$. In fact, the renormalized coupling is always zero for any choice of $\lambda$. In other words, the renormalized $\phi^{4}$ theory is free, no matter the value of the bare coupling! The formal statement is that the $\phi^{4}$ theory is "trivial". Note that this is only true in $(3+1)$ dimensions. In lower dimensions, the renormalized coupling is non-zero.

Now, why is this finding important? The Standard Model of particle interactions contains a Higgs particle, which gives a mass to all other particles by coupling to them. The field theory describing the Higgs particle is very much like the $\phi^{4}$ theory we have just studied, except that the field $\phi$ is now a complex doublet $\binom{\phi_{1}+i \phi_{2}}{\phi_{3}+i \phi_{4}}$. The bare parameters are chosen so that the system is in the broken-symmetry phase, where $\phi$ has a non-zero expectation value. The masses of all particles are proportional to $\langle\phi\rangle$, therefore it is crucial that $\langle\phi\rangle \neq 0$. In turn, this symmetry breaking is only possible if the coupling $g$ is non-zero. But, as we have seen, the "true", renormalized value of $g$ is zero. Therefore, we have a logical inconsistency. The consequence is that the Standard Model cannot be the final, exact description of particle interactions. Some new physics beyond the Standard Model must exist, which becomes visible at an energy scale which depends on the Higgs boson mass. From the numerical study of the lattice theory near $\kappa_{c}(\lambda)$, one can set this scale at around 1000 GeV if the Higgs mass is around $600-800$ GeV , or higher if the Higgs is lighter. In any case, the Higgs boson, and/or possibly new physics, must be found at energies $\leq 1000 \mathrm{GeV}^{3}$. This (slightly abridged) argument is so powerful that it has been used in the design of the Large Hadron Collider (LHC), turned on at CERN in 2009, and which will study collisions up to about 1000 GeV only.

### 10.4 Gauge theories

Of the four forces known in Nature, at least three (the strong, the weak and the electromagnetic forces) are described by gauge theories. In addition to the usual "matter" fields (electrons, quarks), these theories contain "gauge" fields (photons, W and Z bosons, gluons) which "mediate" the interaction: the interaction between, say, two electrons is caused by the exchange of photons between them. This is analogous to the exchange of momentum which occurs when one person throws a ball at another, and the other catches it. In this way, two particles interact when they are far apart, even though the Lagrangian contains only local interactions. Moreover, gauge theories are invariant under a larger class of symmetries, namely local ( $x$-dependent) symmetries.

### 10.4.1 QED

As an example, let us consider here a variant of Quantum ElectroDynamics (QED), called scalar QED, where electrons are turned into bosons. A simple modification of

[^17]Figure 10.4: Graphical representation (left) of the gauge-invariant nearest-neighbour interaction: $\phi^{*}(x) \phi(x+\hat{\mu})$ becomes $\phi^{*}(x) U_{\mu}(x) \phi(x+\hat{\mu})$; (middle) an example of a gauge-invariant 4-point correlation; (right) the smallest closed loop is the plaquette, with associated matrix $U_{\mu}(x) U_{\nu}(x+\hat{\mu}) U_{\mu}^{\dagger}(x+\hat{\nu}) U_{\nu}^{\dagger}(x)$.
the previous $\phi^{4}$ theory is required: in order to represent charged bosons, the field $\phi$, instead of being real, is made complex, $\phi(x) \in \mathcal{C}$. The continuum Euclidean action becomes

$$
\begin{equation*}
S_{E}=\int d \tau d^{3} x\left[\left|\partial_{\mu} \phi_{0}\right|^{2}+m_{0}^{2}\left|\phi_{0}\right|^{2}+\frac{g_{0}}{4!}\left|\phi_{0}\right|^{4}\right] \tag{10.14}
\end{equation*}
$$

and, after discretization on the lattice:

$$
\begin{equation*}
S_{L}=\sum_{x}\left[-\kappa \sum_{\mu}\left(\phi^{*}(x) \phi(x+\hat{\mu})+\text { h.c. }\right)+|\phi(x)|^{2}+\lambda\left(|\phi(x)|^{2}-1\right)^{2}-\lambda\right] \tag{10.15}
\end{equation*}
$$

$S_{L}$ is invariant under the global ( $x$-independent) rotation $\phi(x) \rightarrow \exp (i \alpha) \phi(x) \forall x$. The idea is now to promote this symmetry to a local one, where $\alpha$ may depend on $x$. It is clear that the derivative term $\phi^{*}(x) \phi(x+\hat{\mu})$ is not invariant under this transformation. Invariance is achieved by introducing new degrees of freedom, namely complex phases (elements of $U(1)$ ) which live on the links between nearest-neighbours. Call $U_{\mu}(x)=$ $\exp \left(i \theta_{\mu}(x)\right)$ the link variable starting at site $x$ in direction $\mu$. Modify the derivative term as follows:

$$
\begin{equation*}
\phi^{*}(x) \phi(x+\hat{\mu}) \rightarrow \phi^{*}(x) U_{\mu}(x) \phi(x+\hat{\mu}) \tag{10.16}
\end{equation*}
$$

This term is now invariant under a local transformation $\phi(x) \rightarrow \exp (i \alpha(x)) \phi(x)$, with $\alpha(x) \neq \alpha(x+\hat{\mu})$, provided that $U_{\mu}(x)$ also transforms:

$$
\begin{align*}
\phi(x) & \rightarrow \exp (i \alpha(x)) \phi(x)  \tag{10.17}\\
U_{\mu}(x) & \rightarrow \exp (i \alpha(x)) U_{\mu}(x) \exp (-i \alpha(x+\hat{\mu})) \tag{10.18}
\end{align*}
$$

The significance of the new variables $U_{\mu}(x)$ and of the new expression for the discretized derivative can be elucidated by expressing $\theta_{\mu}(x)=e a A_{\mu}(x)$, and considering the continuum limit $a \rightarrow 0$. To lowest order in $a$, the derivative $\partial_{\mu}$ becomes the covariant derivative $D_{\mu} \equiv \partial_{\mu}+i e A_{\mu}$, and the transformation eq.(10.18) is a gauge transformation for $A_{\mu}: A_{\mu}(x) \rightarrow A_{\mu}(x)-e \partial_{\mu} \alpha(x)$. Thus, our link variables $U_{\mu}(x)$ represent the discretized gauge potential $A_{\mu}(x)$ associated with the electromagnetic field, and eq.(10.16)
describes the interaction of our bosonic electrons with the photon. To complete the discretization of QED, what is missing is the energy of the electromagnetic field, namely $\frac{1}{2} \int d \vec{x} d \tau\left(|\vec{E}|^{2}(x)+|\vec{B}|^{2}(x)\right)$. We identify its lattice version below.

It becomes simple to construct $n$-point correlators of $\phi$ which are invariant under the local transformation eq.(10.18): all the fields $\phi$ need to be connected by "strings" of gauge fields, made of products of gauge links $U_{\mu}$ as in Fig. 10.4. Under a local gauge transformation, the phase changes $\alpha(x)$ will always cancel out between $\phi$ and the attached $U$, or between two successive $U$ 's.

There is another type of gauge-invariant object. Consider the product of links $\prod_{x \rightarrow x} U$ around a closed loop, starting and ending at $x$. It transforms as

$$
\begin{equation*}
\prod_{x \rightarrow x} U \rightarrow \exp (i \alpha(x)) \prod_{x \rightarrow x} U \exp (-i \alpha(x)) \tag{10.19}
\end{equation*}
$$

which is invariant since all the $U$ 's are complex phases which commute with each other. Thus, another valid term to add to the [real] lattice action is the real part of any closed loop, summed over translations and rotations to preserve the other desired symmetries. The simplest version of such a term is to take elementary square loops of size $a$, made of 4 links going around a plaquette: $P_{\mu \nu}(x) \equiv U_{\mu}(x) U_{\nu}(x+\hat{\mu}) U^{\dagger}(x+\hat{\mu}) U^{\dagger}(x)$. Thus, the complete action of our scalar QED theory is

$$
\begin{equation*}
\sum_{x}|\phi(x)|^{2}-\kappa \sum_{x} \sum_{\mu}\left(\phi^{*}(x) U_{\mu}(x) \phi(x+\hat{\mu})+\text { h.c. }\right)+\beta \sum_{x} \sum_{\mu \neq \nu} \operatorname{Re}\left(P_{\mu \nu}(x)\right) \tag{10.20}
\end{equation*}
$$

The plaquette term looks geometrically like a curl. Indeed, substituting $U_{\mu}(x)=$ $\exp \left(i e a A_{\mu}(x)\right)$ and expanding to leading-order in $a$ yields

$$
\begin{equation*}
\operatorname{Re}\left(P_{\mu \nu}(x)\right) \approx 1-\frac{1}{2} e^{2} a^{4}\left(\partial_{\mu} A_{\nu}-\partial_{\nu} A_{\mu}\right)^{2} \tag{10.21}
\end{equation*}
$$

so that the last term in eq.(10.20) becomes, up to an irrelevant constant, $-\beta e^{2} \frac{1}{2} \int d \vec{x} d \tau\left(|\vec{E}|^{2}+\right.$ $|\vec{B}|^{2}$ ), where one has expressed the electric and magnetic fields $\vec{E}$ and $\vec{B}$ in terms of the gauge potential $A_{\mu}$. It suffices then to set $\beta=1 / e^{2}$ to recover the energy of an electro-magnetic field.

Note that it is our demand to preserve invariance under the local transformation eq.(10.18) which has led us to the general form of the action eq.(10.20). We could have considered larger loops instead of plaquettes. But in the continuum limit $a \rightarrow 0$, these loops would yield the same continuum action. So the form of the QED action is essentially dictated by the local gauge symmetry.

One can now study the scalar QED theory defined by eq.(10.20) using Monte Carlo simulations, for any value of the bare couplings $(\kappa, \beta)$. Contrary to continuum perturbation theory, one is not limited to small values of $e$ (i.e. large $\beta$ ).

### 10.4.2 QCD

Other gauge theories have basically the same discretized action eq.(10.20). What changes is the group to which the link variables $U_{\mu}(x)$ belong. For QCD, these variables
represent the gluon field, which mediates the interaction between quarks. Quarks come in 3 different colors and are thus represented by a 3 -component vector at each site ${ }^{4}$. Hence, the link variables are $3 \times 3$ matrices. The gauge-invariant piece associated with a closed loop is the trace of the corresponding matrix, thanks to cyclic invariance of the trace of eq.(10.19). No other changes are required to turn lattice QED into lattice QCD!

As emphasized in Sec. 10.3, the Euclidean Lagrangian density defines the lattice theory. The continuum limit can be obtained by approaching a critical point. For QCD, the critical point is $\beta \rightarrow+\infty$, i.e. $g_{0}=0$ since $\beta \propto 1 / g_{0}^{2}$ as in QED. As we have seen, the vanishing of the bare coupling does not imply much about the true, renormalized coupling.

### 10.5 Overview

The formulation of lattice QCD is due to K. Wilson (1974). First Monte Carlo simulations were performed by M. Creutz in 1980, on a $4^{4}$ lattice. A goal of early simulations was to check whether quarks were confined. This can be demonstrated by considering the potential $V(r)$ between a quark and an anti-quark separated by distance $r$. Contrary to the case of QED where the potential $\propto 1 / r$ saturates as $r \rightarrow \infty$, in QCD the potential keeps rising linearly, $V(r) \sim \sigma r$, so that it takes an infinite amount of energy to completely separate the quark and anti-quark. Equivalently, the force between the two objects goes to a constant $\sigma$. The energy of the quark-antiquark pair grows as if it was all concentrated in a tube of finite diameter. Describing the quark-antiquark pair as an infinitely thin, vibrating string is a very good approximation, as shown in the state-of-the-art Monte Carlo data Fig. 10.5, now performed on $32^{4}$ lattices. To control discretization errors, the lattice spacing must be about $1 / 10^{\text {th }}$ of the correlation length or less. To control finite-volume effects, the lattice size must be about 3 times the correlation length or more. This implies lattices of minimum size $30^{4}$, which have only become within reach of a reasonable computer budget in recent years.

The above simulations considered only the effect of gluons: since gluons carry a color charge (in contrast to the photon which is electrically neutral), they can lead to complex effects like the confinement of charges introduced in the gluon system. But to study QCD proper, quarks must be simulated also. This is more difficult because quarks are fermions, i.e. non-commuting variables. The strategy is to integrate them out analytically. This integration induces a more complicated interaction among the remaining gluonic link variables. In fact, this interaction is non-local, which increases the algorithmic complexity of the Monte Carlo simulation. An efficient, exact simulation algorithm, called Hybrid Monte Carlo, was only discovered in 1987 (see bibliography). Even so, the simulation of so-called "full QCD", on lattices of size $30^{4}$ or larger, requires a computer effort $\mathcal{O}(1)$ Teraflop $\times$ year, which has forced the community to evolve into large collaborations using dedicated computers.

Using these resources, one is now able to reproduce the masses of quark and antiquark bound states, i.e. mesons and baryons, to a few percent accuracy. The impact of

[^18]neglecting the effect of quarks or including them is nicely illustrated in Fig. 10.6. Some predictions have also been made for the properties of mesons made of charm or bottom quarks, currently being studied in particle accelerators.

Another essential purpose of QCD simulations is to quantify QCD effects in experimental tests of the electroweak Standard Model. By checking whether experimental results are consistent with the Standard Model, one can expose inconsistencies which would be the signature of new, beyond-the-standard-model physics. To reveal such inconsistencies, one must first determine precisely the predictions of the Standard Model. This entails the determination of QCD effects, which can only be obtained from lattice QCD simulations.

Finally, another direction where QCD simulations have been playing a major role is that of high temperature. The confinement of quarks, which is an experimental fact at normal temperatures, is believed to disappear at very high temperatures $\mathcal{O}(100) \mathrm{MeV}$ $\sim \mathcal{O}\left(10^{12}\right) K$. This new state of matter, where quarks and gluons form a plasma, is being probed by accelerator experiments which smash heavy ions against each other. Lattice simulations provide an essential tool to predict the properties of this plasma.

### 10.6 Useful references

- Computational Physics, by J.M. Thijssen, Cambridge Univ. Press (2007), second edition. See Chapter 15.
- Quantum Field Theory in a nutshell, by A. Zee, Princeton Univ. Press (2003). This book reads like a thriller.
- Hybrid Monte Carlo, by S. Duane, A. D. Kennedy, B. J. Pendleton and D. Roweth, Phys. Lett. B 195 (1987) 216.

Figure 10.5: Potential $V(r)$ between a static quark and antiquark, as a function of their separation $r$. Data obtained at 2 values of the lattice spacing (finite values of $\beta$ ) are extrapolated to the continuum limit $(\beta \rightarrow \infty)$. At short distance, the potential is Coulomb-like because the interaction becomes weak (the solid line shows the prediction of perturbation theory). At large distance, the potential rises linearly, which shows that it takes an infinite energy to separate the two objects: quarks are confined. A simple model of a vibrating string (dotted line) gives a good description, down to rather short distances. From hep-lat/0108008.

Figure 10.6: Comparison of lattice and experimental measurements of various quantities. The left figure shows the ratios lattice/experiment, for a lattice model which neglects quark effects (the number $n_{f}$ of quark flavors is set to zero). The right figure shows the same ratios, for a lattice model including 3 quark flavors, all with equal masses. From hep-lat/0304004.

## Appendix A

## Numerical methods

## A. 1 Numerical root solvers

The purpose of a root solver is to find a solution (a root) to the equation

$$
\begin{equation*}
f(x)=0, \tag{A.1}
\end{equation*}
$$

or in general to a multi-dimensional equation

$$
\begin{equation*}
\vec{f}(\vec{x})=0 . \tag{A.2}
\end{equation*}
$$

Numerical root solvers should be well known from the numerics courses and we will just review three simple root solvers here. Keep in mind that in any serious calculation it is usually best to use a well optimized and tested library function over a hand-coded root solver.

## A.1.1 The Newton and secant methods

The Newton method is one of best known root solvers, however it is not guaranteed to converge. The key idea is to start from a guess $x_{0}$, linearize the equation around that guess

$$
\begin{equation*}
f\left(x_{0}\right)+\left(x-x_{0}\right) f^{\prime}\left(x_{0}\right)=0 \tag{A.3}
\end{equation*}
$$

and solve this linearized equation to obtain a better estimate $x_{1}$. Iterating this procedure we obtain the Newton method:

$$
\begin{equation*}
x_{n+1}=x_{n}-\frac{f\left(x_{n}\right)}{f^{\prime}\left(x_{n}\right)} . \tag{A.4}
\end{equation*}
$$

If the derivative $f^{\prime}$ is not known analytically, as is the case in our shooting problems, we can estimate it from the difference of the last two points:

$$
\begin{equation*}
f^{\prime}\left(x_{n}\right) \approx \frac{f\left(x_{n}\right)-f\left(x_{n-1}\right)}{x_{n}-x_{n-1}} \tag{A.5}
\end{equation*}
$$

Substituting this into the Newton method (A.4) we obtain the secant method:

$$
\begin{equation*}
x_{n+1}=x_{n}-\left(x_{n}-x_{n-1}\right) \frac{f\left(x_{n}\right)}{f\left(x_{n}\right)-f\left(x_{n-1}\right)} . \tag{A.6}
\end{equation*}
$$

The Newton method can easily be generalized to higher dimensional equations, by defining the matrix of derivatives

$$
\begin{equation*}
A_{i j}(\vec{x})=\frac{\partial f_{i}(\vec{x})}{\partial x_{j}} \tag{A.7}
\end{equation*}
$$

to obtain the higher dimensional Newton method

$$
\begin{equation*}
\vec{x}_{n+1}=\vec{x}_{n}-A^{-1} \vec{f}(\vec{x}) \tag{A.8}
\end{equation*}
$$

If the derivatives $A_{i j}(\vec{x})$ are not known analytically they can be estimated through finite differences:

$$
\begin{equation*}
A_{i j}(\vec{x})=\frac{f_{i}\left(\vec{x}+h_{j} \vec{e}_{j}\right)-f_{i}(\vec{x})}{h_{j}} \quad \text { with } \quad h_{j} \approx x_{j} \sqrt{\varepsilon} \tag{A.9}
\end{equation*}
$$

where $\varepsilon$ is the machine precision (about $10^{-16}$ for double precision floating point numbers on most machines).

## A.1.2 The bisection method and regula falsi

Both the bisection method and the regula falsi require two starting values $x_{0}$ and $x_{1}$ surrounding the root, with $f\left(x_{0}\right)<0$ and $f\left(x_{1}\right)>0$ so that under the assumption of a continuous function $f$ there exists at least one root between $x_{0}$ and $x_{1}$.

The bisection method performs the following iteration

1. define a mid-point $x_{m}=\left(x_{0}+x_{1}\right) / 2$.
2. if $\operatorname{sign} f\left(x_{m}\right)=\operatorname{sign} f\left(x_{0}\right)$ replace $x_{0} \leftarrow x_{m}$ otherwise replace $x_{1} \leftarrow x_{m}$ until a root is found.

The regula falsi works in a similar fashion:

1. estimate the function $f$ by a straight line from $x_{0}$ to $x_{1}$ and calculate the root of this linearized function: $x_{2}=\left(f\left(x_{0}\right) x_{1}-f\left(x_{1}\right) x_{0}\right) /\left(f\left(x_{1}\right)-f\left(x_{0}\right)\right.$
2. if $\operatorname{sign} f\left(x_{2}\right)=\operatorname{sign} f\left(x_{0}\right)$ replace $x_{0} \leftarrow x_{2}$ otherwise replace $x_{1} \leftarrow x_{2}$

In contrast to the Newton method, both of these two methods will always find a root.

## A.1.3 Optimizing a function

These root solvers can also be used for finding an extremum (minimum or maximum) of a function $f(\vec{x})$, by looking a root of

$$
\begin{equation*}
\nabla f(\vec{x})=0 . \tag{A.10}
\end{equation*}
$$

While this is efficient for one-dimensional problems, but better algorithms exist.
In the following discussion we assume, without loss of generality, that we want to minimize a function. The simplest algorithm for a multi-dimensional optimization is
steepest descent, which always looks for a minimum along the direction of steepest gradient: starting from an initial guess $\vec{x}_{n}$ a one-dimensional minimization is applied to determine the value of $\lambda$ which minimizes

$$
\begin{equation*}
f\left(\vec{x}_{n}+\lambda \nabla f\left(\vec{x}_{n}\right)\right) \tag{A.11}
\end{equation*}
$$

and then the next guess $\vec{x}_{n+1}$ is determined as

$$
\begin{equation*}
\vec{x}_{n+1}=\vec{x}_{n}+\lambda \nabla f\left(\vec{x}_{n}\right) \tag{A.12}
\end{equation*}
$$

While this method is simple it can be very inefficient if the "landscape" of the function $f$ resembles a long and narrow valley: the one-dimensional minimization will mainly improve the estimate transverse to the valley but takes a long time to traverse down the valley to the minimum. A better method is the conjugate gradient algorithm which approximates the function locally by a paraboloid and uses the minimum of this paraboloid as the next guess. This algorithm can find the minimuim of a long and narrow parabolic valley in one iteration! For this and other, even better, algorithms we recommend the use of library functions.

One final word of warning is that all of these minimizers will only find a local minimum. Whether this local minimum is also the global minimum can never be decided by purely numerically. A necessary but never sufficient check is thus to start the minimization not only from one initial guess but to try many initial points and check for consistency in the minimum found.

## A. 2 The Lanczos algorithm

Sparse matrices with only $N$ ) non-zero elements are very common in scientific simulations. We have already encountered them in the winter semester when we discretized partial differential equations. Now we have reduced the transfer matrix of the Ising model to a sparse matrix product. We will later see that also the quantum mechanical Hamilton operators in lattice models are sparse.

The importance of sparsity becomes obvious when considering the cost of matrix operations as listed in table A.1. For large $N$ the sparsity leads to memory and time savings of several orders of magnitude.

Here we will discuss the iterative calculation of a few of the extreme eigenvalues of a matrix by the Lanczos algorithm. Similar methods can be used to solve sparse linear systems of equations.

To motivate the Lanczos algorithms we will first take a look at the power method for a matrix $A$. Starting from a random initial vector $u_{1}$ we calculate the sequence

$$
\begin{equation*}
u_{n+1}=\frac{A u_{n}}{\left\|A u_{n}\right\|} \tag{A.13}
\end{equation*}
$$

which converges to the eigenvector of the largest eigenvalue of the matrix $A$. The Lanczos algorithm optimizes this crude power method.

Table A.1: Time and memory complexity for operations on sparse and dense $N \times N$ matrices

| operation | time | memory |
| :--- | :---: | :---: |
| storage <br> dense matrix <br> sparse matrix | - | $N^{2}$ |
| matrix-vector multiplication | - | $\mathrm{O}(N)$ |
| dense matrix <br> sparse matrix | $\mathrm{O}\left(N^{2}\right)$ | $\mathrm{O}\left(N^{2}\right)$ |
| matrix-matrix multiplication <br> dense matrix | $\mathrm{O}(N)$ | $\mathrm{O}(N)$ |
| sparse matrix | $\mathrm{O}(N) \ldots \mathrm{O}\left(N^{\ln 7 / \ln 2}\right)$ | $\mathrm{O}\left(N^{2}\right)$ | $\mathrm{O}(N) \ldots \mathrm{O}\left(N^{2}\right)$.

## Lanczos iterations

The Lanczos algorithm builds a basis $\left\{v_{1}, v_{2}, \ldots, v_{M}\right\}$ for the Krylov-subspace $K_{M}=$ $\operatorname{span}\left\{u_{1}, u_{2}, \ldots, u_{M}\right\}$, which is constructed by $M$ iterations of equation (A.13). This is done by the following iterations:

$$
\begin{equation*}
\beta_{n+1} v_{n+1}=A v_{n}-\alpha_{n} v_{n}-\beta_{n} v_{n-1}, \tag{A.14}
\end{equation*}
$$

where

$$
\begin{equation*}
\alpha_{n}=v_{n}^{\dagger} A v_{n}, \quad \beta_{n}=\left|v_{n}^{\dagger} A v_{n-1}\right| . \tag{A.15}
\end{equation*}
$$

As the orthogonality condition

$$
\begin{equation*}
v_{i}^{\dagger} v_{j}=\delta_{i j} \tag{A.16}
\end{equation*}
$$

does not determine the phases of the basis vectors, the $\beta_{i}$ can be chosen to be real and positive. As can be seen, we only need to keep three vectors of size $N$ in memory, which makes the Lanczos algorithm very efficient, when compared to dense matrix eigensolvers which require storage of order $N^{2}$.

In the Krylov basis the matrix $A$ is tridiagonal

$$
T^{(n)}:=\left[\begin{array}{ccccc}
\alpha_{1} & \beta_{2} & 0 & \cdots & 0  \tag{A.17}\\
\beta_{2} & \alpha_{2} & \ddots & \ddots & \vdots \\
0 & \ddots & \ddots & \ddots & 0 \\
\vdots & \ddots & \ddots & \ddots & \beta_{n} \\
0 & \cdots & 0 & \beta_{n} & \alpha_{n}
\end{array}\right] .
$$

The eigenvalues $\left\{\tau_{1}, \ldots, \tau_{M}\right\}$ of $T$ are good approximations of the eigenvalues of $A$. The extreme eigenvalues converge very fast. Thus $M \ll N$ iterations are sufficient to obtain the extreme eigenvalues.

## Eigenvectors

It is no problem to compute the eigenvectors of $T$. They are however given in the Krylov basis $\left\{v_{1}, v_{2}, \ldots, v_{M}\right\}$. To obtain the eigenvectors in the original basis we need to perform a basis transformation.

Due to memory constraints we usually do not store all the $v_{i}$, but only the last three vectors. To transform the eigenvector to the original basis we have to do the Lanczos iterations a second time. Starting from the same initial vector $v_{1}$ we construct the vectors $v_{i}$ iteratively and perform the basis transformation as we go along.

## Roundoff errors and ghosts

In exact arithmetic the vectors $\left\{v_{i}\right\}$ are orthogonal and the Lanczos iterations stop after at most $N-1$ steps. The eigenvalues of $T$ are then the exact eigenvalues of $A$.

Roundoff errors in finite precision cause a loss of orthogonality. There are two ways to deal with that:

- Reorthogonalization of the vectors after every step. This requires storing all of the vectors $\left\{v_{i}\right\}$ and is memory intensive.
- Control of the effects of roundoff.

We will discuss the second solution as it is faster and needs less memory. The main effect of roundoff errors is that the matrix $T$ contains extra spurious eigenvalues, called "ghosts". These ghosts are not real eigenvalues of $A$. However they converge towards real eigenvalues of $A$ over time and increase their multiplicities.

A simple criterion distinguishes ghosts from real eigenvalues. Ghosts are caused by roundoff errors. Thus they do not depend on on the starting vector $v_{1}$. As a consequence these ghosts are also eigenvalues of the matrix $\tilde{T}$, which can be obtained from $T$ by deleting the first row and column:

$$
\tilde{T}^{(n)}:=\left[\begin{array}{ccccc}
\alpha_{2} & \beta_{3} & 0 & \cdots & 0  \tag{A.18}\\
\beta_{3} & \alpha_{3} & \ddots & \ddots & \vdots \\
0 & \ddots & \ddots & \ddots & 0 \\
\vdots & \ddots & \ddots & \ddots & \beta_{n} \\
0 & \cdots & 0 & \beta_{n} & \alpha_{n}
\end{array}\right]
$$

From these arguments we derive the following heuristic criterion to distinguish ghosts from real eigenvalues:

- All multiple eigenvalues are real, but their multiplicities might be too large.
- All single eigenvalues of $T$ which are not eigenvalues of $\tilde{T}$ are also real.

Numerically stable and efficient implementations of the Lanczos algorithm can be obtained from netlib or fromhttp://www.comp-phys.org/software/ietl/ .


[^0]:    ${ }^{1}$ R. Barret, M. Berry, T.F. Chan, J. Demmel, J. Donato, J. Dongarra, V. Eijkhout, R. Pozo, C. Romine, and H. van der Vorst, Templates for the Solution of Linear Systems: Building Blocks for Iterative Methods (SIAM, 1993)
    ${ }^{2}$ J.G. Siek, A. Lumsdaine and Lie-Quan Lee, Generic Programming for High Performance Numerical Linear Algebra in Proceedings of the SIAM Workshop on Object Oriented Methods for Inter-operable Scientific and Engineering Computing (OO'98) (SIAM, 1998); the library is available on the web at: http://www.osl.iu.edu/research/itl/

[^1]:    ${ }^{3}$ http://www.comp-phys.org/software/ietl/
    ${ }^{4}$ Z. Bai, J. Demmel and J. Dongarra (Eds.), Templates for the Solution of Algebraic Eigenvalue Problems: A Practical Guide (SIAM, 2000).

[^2]:    ${ }^{1}$ H. F. Trotter, On the product of semi-groups of operators, Proc. Amer. Math. Soc. 10, 545 (1959); M. Suzuki, Generalized Trotter's formula and systematic approximants of exponential operators and inner derivations with applications to many-body problems, Commun. Math. Phys. 51, 183 (1976).

[^3]:    ${ }^{1}$ R.P. Feynman, Simulating physics with computers. International Journal of Theoretical Physics 21, 467-488 (1982).

[^4]:    ${ }^{2}$ The notation poly $(x)$ indicates an effort that is polynomial in $x$.
    ${ }^{3}$ Some of the figures in this section are taken from proseminar notes of L. Gamper

[^5]:    ${ }^{4}$ The discussion here partially follows the presentation on WIkipedia

[^6]:    ${ }^{5}$ L. Landau (1932), Zur Theorie der Energieübertragung. II, Physikalische Zeitschrift der Sowjetunion 24651 (1932); C. Zener (1932), Non-Adiabatic Crossing of Energy Levels, Proceedings of the Royal Society of London A 137, 696 (1932).

[^7]:    ${ }^{6}$ If there are degenerate eigenvalues (within the measurement accuracy) then the resulting state would still be a superposition of all states with the same energy (within measurement accuracy).

[^8]:    ${ }^{1}$ As a side remark we want to mention that in two dimensions the first homotopy group is $\mathbb{Z}$ and not trivial: it matters whether we move the particles clock-wise or anti-clock wise when exchanging them, and two clock-wise exchanges are not the identity anymore. Then more general, anyonic, statistics are possible.

[^9]:    ${ }^{1}$ If a magnetic field is present the wave function must have an imaginary part also.

[^10]:    ${ }^{2}$ For diagonal operators, one can implement exact estimators using the forward walking technique (see references).

[^11]:    ${ }^{1}$ H. G. Evertz et al., Phys. Rev. Lett. 70, 875 (1993); B. B. Beard and U.-J. Wiese, Phys. Rev. Lett. 77, 5130 (1996); B. Ammon, H. G. Evertz, N. Kawashima, M. Troyer and B. Frischmuth, Phys. Rev. B 58, 4304 (1998).

[^12]:    ${ }^{2}$ F. Barahona, J. Phys. A 15, 3241 (1982)

[^13]:    ${ }^{3}$ S. Chandrasekharan and U.-J. Wiese, Phys. Rev. Lett. 83, 3116 (1999)

[^14]:    ${ }^{4}$ N. V. Prokof'ev, B. V. Svistunov and I. S. Tupitsyn, Sov. Phys - JETP 87, 310 (1998).

[^15]:    ${ }^{1}$ One could think of additional interaction terms, constructed from higher derivatives of the field. They are not considered here because they lead to non-renormalizable theories.

[^16]:    ${ }^{2}$ The lattice spacing is taken to be the same in space and in time for simplicity; one could consider different values $a_{s}$ and $a_{\tau}$.

[^17]:    ${ }^{3}$ Update 2013: the Higgs boson has most likely been found at LHC, with a mass $\approx 125 \mathrm{GeV}$. This small mass may allow the scale of new physics to be as high as the Planck mass.

[^18]:    ${ }^{4}$ This would be the full story if quarks were bosons. Because they are fermions, each color component is in fact a 4 -component vector, called Dirac spinor.

